## Efficient Tensor-based Approximations to Kernel Interactions

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Tensor Methods for Kernel Matrices

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## Motivation: Kernel Methods

- $\bullet\,$  Model pairwise interactions between sets of points defined by kernel  $\kappa\,$
- Applications where kernel methods are used:
  - Integral equations (Green's Function), *n*-body problems, Gaussian processes
- Major challenges include
  - Number of interaction points often large
  - Kernel matrices are dense, difficult to store and compute with

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- Major challenges include
  - Number of interaction points often large
  - Kernel matrices are dense, difficult to store and compute with
- General approach: store kernel matrix efficiently as a rank-structured matrix in a hierarchical form
  - Forms include *H*-matrices, *H*<sup>2</sup>-matrices, Hierarchical Semiseparable (HSS) matrices, Hierarchical Off-Diagonal Low Rank (HODLR) matrices
  - Constructed by recursively identifying and compressing off-diagonal blocks in low-rank form

#### Problem Setup

- $N_s$  source points  $\boldsymbol{X} = \{\boldsymbol{x}_1, \dots, \boldsymbol{x}_{N_s}\}$  in  $\mathcal{B}_s = [a_1, b_1] \times \dots \times [a_D, b_D]$
- $N_t$  target points  $\boldsymbol{Y} = \{\boldsymbol{y}_1, \dots, \boldsymbol{y}_{N_t}\}$  in  $\mathcal{B}_t = [c_1, d_1] \times \dots \times [c_D, d_D]$ • kernel  $\kappa : \mathbb{R}^D \times \mathbb{R}^D \to \mathbb{R}$



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Define interaction matrix

$$\mathcal{K}(\boldsymbol{X}, \boldsymbol{Y}) = \begin{bmatrix} \kappa(\boldsymbol{x}_1, \boldsymbol{y}_1) & \kappa(\boldsymbol{x}_1, \boldsymbol{y}_2) & \dots & \kappa(\boldsymbol{x}_1, \boldsymbol{y}_{N_t}) \\ \kappa(\boldsymbol{x}_2, \boldsymbol{y}_1) & \kappa(\boldsymbol{x}_2, \boldsymbol{y}_2) & \dots & \kappa(\boldsymbol{x}_2, \boldsymbol{y}_{N_t}) \\ \vdots & \vdots & \ddots & \vdots \\ \kappa(\boldsymbol{x}_{N_s}, \boldsymbol{y}_1) & \kappa(\boldsymbol{x}_{N_s}, \boldsymbol{y}_2) & \dots & \kappa(\boldsymbol{x}_{N_s}, \boldsymbol{y}_{N_t}) \end{bmatrix}$$

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Main idea: approximate  $\kappa$  using Chebyshev interpolation and tensor compression methods

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## Multivariate Chebyshev Interpolation

For two spatial dimensions (D = 2):

$$\kappa(\mathbf{x}, \mathbf{y}) = f(x_1, x_2, y_1, y_2) = f(\xi_1, \xi_2, \xi_3, \xi_4)$$
  
$$\approx \sum_{j_1=1}^n \cdots \sum_{j_4=1}^n f(\eta_{j_1}^{(1)}, \eta_{j_2}^{(2)}, \eta_{j_3}^{(3)}, \eta_{j_4}^{(4)}) \left(\prod_{k=1}^4 S_n^{[\alpha_k, \beta_k]}(\eta_{j_k}^{(k)}, \xi_k)\right)$$

with

- *n* number of Chebyshev points per dimension
- $S_n^{[a,b]}$  Chebyshev polynomial interpolant

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## Chebyshev Interpolation as a Tensor

$$\kappa(\mathbf{x}, \mathbf{y}) = f(x_1, x_2, y_1, y_2) = f(\xi_1, \xi_2, \xi_3, \xi_4)$$
  
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Can be written in tensor form:

$$f(\xi_1,\xi_2,\xi_3,\xi_4) \approx \mathcal{M} \bigotimes_{k=1}^4 \boldsymbol{s}_k(\xi_k)$$

where

• 
$$\mathcal{M}_{j_1, j_2, j_3, j_4} = f(\eta_{j_1}^{(1)}, \eta_{j_2}^{(2)}, \eta_{j_3}^{(3)}, \eta_{j_4}^{(4)})$$
, with  $\mathcal{M} \in \mathbb{R}^{n \times n \times n \times n}$   
•  $\mathbf{s}_k(\xi_k) = \left[ S_n^{[\alpha_k, \beta_k]}(\eta_1^{(k)}, \xi_k) \quad \dots \quad S_n^{[\alpha_k, \beta_k]}(\eta_n^{(k)}, \xi_k) \right] \in \mathbb{R}^{1 \times n}$ 

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## Our Tensor-based Compression Approach

Idea: Use tensor compression methods on  $\mathcal{M}$  to obtain Tucker approximation  $\widehat{\mathcal{M}} = [\mathcal{G}; A_1, A_2, A_3, A_4]$ 

Three new randomized methods for compressing  $\mathcal{M}$ 

- Method 1: uses row interpolatory decomposition to approximate mode unfoldings
- Method 2: Method 1 but with a subsampled tensor
- Method 3: uses a Kronecker product of random Gaussian matrices instead of a single Gaussian matrix

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$$\kappa(\mathbf{x}, \mathbf{y}) = f(\xi_1, \xi_2, \xi_3, \xi_4) \approx \widehat{\mathcal{M}} \bigotimes_{k=1}^{4} \mathbf{s}_k(\xi_k)$$
$$= \mathcal{G} \bigotimes_{i=1}^{4} A_i \bigotimes_{k=1}^{4} \mathbf{s}_k(\xi_k) = \mathcal{G} \bigotimes_{k=1}^{4} \mathbf{s}_k(\xi_k) A_k$$

### Low-rank Approximation to Kernel Matrix

For a single pair of points,

$$\begin{aligned} \kappa(\mathbf{x},\mathbf{y}) &= \mathcal{G} \bigotimes_{k=1}^{4} \mathbf{s}_{k}(\xi_{k}) \mathcal{A}_{k} = \mathcal{G} \bigotimes_{k=1}^{4} \widehat{\mathbf{s}}_{k}(\xi_{k}) \\ &= \left(\widehat{\mathbf{s}}_{2}(\xi_{2}) \otimes \widehat{\mathbf{s}}_{1}(\xi_{1})\right) \mathcal{G}_{(1:2)}\left(\widehat{\mathbf{s}}_{4}^{\top}(\xi_{4}) \otimes \widehat{\mathbf{s}}_{3}^{\top}(\xi_{3})\right) \end{aligned}$$

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Collect  $\hat{s}$  matrices for all points:

• 
$$U_j = \begin{bmatrix} \widehat{s}_j(x_1) & \dots & \widehat{s}_j(x_{N_s}) \end{bmatrix}^\top \in \mathbb{R}^{N_s \times r}, \quad j = 1, 2$$
  
•  $V_j = \begin{bmatrix} \widehat{s}_j(y_1) & \dots & \widehat{s}_j(y_{N_t}) \end{bmatrix}^\top \in \mathbb{R}^{N_t \times r}, \quad j = 3, 4$ 

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Then interaction matrix approximation is

$$\mathcal{K}(\boldsymbol{X}, \boldsymbol{Y}) pprox (U_2 \ltimes U_1) \mathcal{G}_{(1:2)} (V_4 \ltimes V_3)^{ op}$$

## Randomized Row Interpolatory Decomposition (RRID)<sup>1</sup>

Gives low-rank approximation using randomized range finder and subset selection

<sup>1</sup>Halko, Martinsson, Tropp, SIAM Review, 2011

Main Steps

For a matrix  $X \in \mathbb{R}^{m \times n}$ , target rank r, oversampling parameter p > 0 such that r + p < m,

- Estimate range of X
- Subset selection to identify indices *J*
- Ompute approximation matrix
   F so X ≈ FX(J,:)

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#### <u>Details</u>

- Draw  $\Omega \in \mathbb{R}^{n \times (r+p)}$  a Gaussian random matrix
- Form product  $Y = X\Omega$
- Compute thin QR Y = QR
  - $\mathcal{R}(Q) \approx \mathcal{R}(X)$
- Use pivoted QR on  $Q^{\top}$ 
  - Gives indices  ${\mathcal J}$  of
    - well-conditioned rows of Q

• Compute  $F = Q(Q(\mathcal{J}, :))^{-1}$ 

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Compresses tensor  $\mathcal{M} \in \mathbb{R}^{n \times n \times n \times n}$ 

• Easily extendable to *d*-dimensional tensors

Process:

• For mode 1:

 $Infold <math>\mathcal{M} \to M_{(1)}$ 

- 2 Apply RRID with target rank r to  $M_{(1)} \approx A_1 M_{(1)}(\mathcal{J}_1, :)$
- Repeat for modes 2-4 to obtain matrices  $A_2, A_3, A_4$  and index sets  $\mathcal{J}_2, \mathcal{J}_3, \mathcal{J}_4$
- Compute core  $\mathcal{G} = \mathcal{M}(\mathcal{J}_1, \mathcal{J}_2, \mathcal{J}_3, \mathcal{J}_4)$
- Gives approximation  $\widehat{\mathcal{M}} = \mathcal{G} \times_1 A_1 \times_2 A_2 \times_3 A_3 \times_4 A_4$

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Similar to Method 1, but working with subsampled tensor instead of  ${\cal M}$  to decrease computational cost

Process:

- For mode 1:
  - Sample tensor: form index set I of size b, and extract subsampled tensor X = M(:, I, I, I)
  - **2** Unfold  $\mathcal{X} \to X_{(1)}$
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Parameters:

- n: number of Chebyshev nodes
- r: target rank
- p: oversampling parameter
- b: size of index set for Method 2

Compression Method	Computational Cost (flops)	Kernel Evals.
Method 1	$\mathcal{O}\left(rn^{4} ight)$	n <sup>4</sup>
Method 2	$\mathcal{O}(b^3n)$	$b^3n + (r + p)^4$
Method 3	$\mathcal{O}\left(rn^{4} ight)$	$n^4$

### Numerical Results Setup

- Generate  $N_s = N_t = 5000$  random points within boxes of length L = 5, D = 10 units apart, with angle  $\theta = \pi/4$
- *n* = 30 Chebyshev nodes
- oversampling parameter p = 5,  $\ell = r + p$

• kernel 
$$\kappa(x,y) = 1/\|x-y\|_2$$

• Error is computed in the  $\infty$ -norm



### Accuracy with different kernels



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## Accuracy while varying distance D between boxes



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## Accuracy with increasing n



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Contributions:

- Use of tensor-based methods for computing efficient low-rank kernel approximations
  - for any number of spatial dimensions
- New randomized tensor compression methods for low-rank Tucker approximations
  - Reduce computational costs of standard algorithms
  - Similar accuracy to standard algorithms
  - Error analysis included in preprint

In preparation: Minster, Saibaba, Kilmer, *Efficient Tensor-based* Approximation to Kernel Interactions