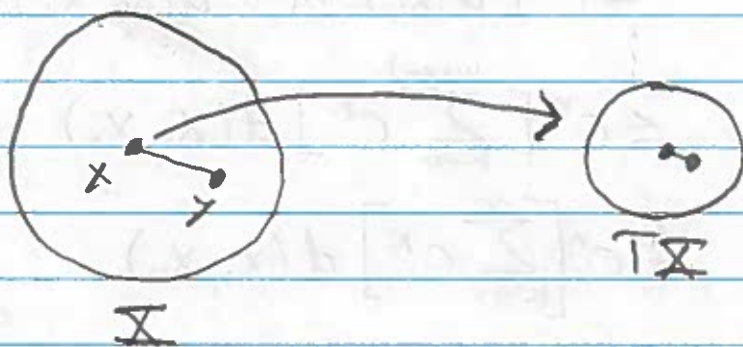


## Lecture 12: Contraction Mapping Theorem

Definition- Let  $(X, d)$  be a metric space. A mapping  $T: X \rightarrow X$  is a contraction mapping if there exists a constant  $c$ , with  $0 \leq c < 1$  such that

$$d(T(x), T(y)) \leq c d(x, y)$$

for all  $x, y \in X$ .



Definition- If  $T: X \rightarrow X$ , then a point  $x \in X$  such that

$$T(x) = x$$

is called a fixed point of  $T$ .

Theorem (Contraction Mapping)- If  $T: X \rightarrow X$  is a contraction mapping on a complete metric space  $(X, d)$ , then there is a unique fixed point of  $T$ .

proof:

Let  $x_0 \in X$ . Define a sequence by

$$x_{n+1} = T x_n.$$

Denote the  $n$ -th composition of  $T$  by  $T^n$ .

Therefore,  $x_n = T^n x_0$ .

Now,

$$\begin{aligned}d(x_n, x_m) &= d(T^n x_0, T^m x_0) \\&= d(T^n x_0, T^n(T^{m-n} x_0)) \\&\leq c^n d(x_0, T^{m-n} x_0) \\&\leq c^n [d(x_0, T x_0) + d(T x_0, T^{m-n} x_0)] \\&= c^n [d(x_0, x_1) + d(T x_0, T^{m-n} x_0)] \\&\leq c^n [d(x_0, x_1) + d(T x_0, T^2 x_0) + d(T^2 x_0, T^{m-n} x_0)] \\&\leq c^n [d(x_0, x_1) + c d(x_0, x_1) + d(T x_0, T^{m-n} x_0)] \\&\vdots \\&\leq c^n \left[ \sum_{k=0}^{m-n-1} c^k \right] d(x_1, x_0) \\&\leq c^n \left[ \sum_{k=0}^{\infty} c^k \right] d(x_1, x_0) \\&\leq \frac{c^n}{1-c} d(x_1, x_0)\end{aligned}$$

Therefore,  $x_n$  is Cauchy. By completeness there exists  $x^*$  such that  $x_n \rightarrow x^* \in X$ . Clearly  $T$  is continuous and thus

$$T x^* = T \lim_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} T x_n = \lim_{n \rightarrow \infty} x_{n+1} = x^*.$$

Finally, if  $x^*, y^*$  are two fixed points, then  
 $0 \leq d(x^*, y^*) = d(T x^*, T y^*) \leq c d(x^*, y^*)$ .  
 $\Rightarrow d(x^*, y^*) = 0$ .

### Example (Integral Equations):

Let  $K(x, y)$  be a smooth function on  $[a, b] \times [a, b]$

Under what conditions on  $\lambda$  does

$$u(x) = f(x) + \lambda \int_a^b K(x, y) u(y) dy$$

have a continuous solution  $u(x)$ ?

Define  $T: C([a, b]) \rightarrow C([a, b])$  by:

$$T(u(x)) = f(x) + \lambda \int_a^b K(x, y) u(y) dy$$

Now,

$$|T(u(x)) - T(v(x))| = \left| \lambda \int_a^b K(x, y) (u(y) - v(y)) dy \right|$$

$$\leq |\lambda| \int_a^b |K(x, y)| |u(y) - v(y)| dy$$

$$\leq |\lambda| \cdot \|u - v\|_{\infty} \int_a^b |K(x, y)| dy$$

$$\Rightarrow \|Tu - Tv\| \leq |\lambda| \max_x \left\{ \int_a^b |K(x, y)| dy \right\} \cdot \|u - v\|_{\infty}$$

Therefore, if

$$|\lambda| < \frac{1}{\max_x \left\{ \int_a^b |K(x, y)| dy \right\}}$$

it follows from the contraction mapping theorem that  $T$  has a fixed point  $u^*$ . Consequently,

$$u^*(x) = f(x) + \lambda \int_a^b K(x, y) u^*(y) dy.$$

Example (Linear ODEs):

$$\frac{d\vec{u}}{dt} = A(t)\vec{u}(t) + \vec{b}(t)$$

$$\vec{u}(0) = \vec{u}_0$$

where  $A: \mathbb{R} \rightarrow \mathbb{R}^{n \times n}$  is a continuous matrix-valued function,  $\vec{b}: \mathbb{R} \rightarrow \mathbb{R}^n$  is a continuous vector-valued function.

Is there a solution to this equation?

$$\Rightarrow \vec{u}(t) = \vec{u}_0 + \int_0^t [A(s)\vec{u}(s) + \vec{b}(s)] ds$$

Define  $T$  by  $T\vec{u} = \vec{u}_0 + \int_0^t [A(s)\vec{u}(s) + \vec{b}(s)] ds$ .

$$\begin{aligned} \Rightarrow \|T\vec{u} - T\vec{v}\|_{\infty} &\leq \int_0^t \|A(s)(\vec{u}(s) - \vec{v}(s))\|_{\infty} ds \\ &\leq \int_0^t \|A\|_{\infty} \|\vec{u}(s) - \vec{v}(s)\|_{\infty} ds \\ &= \|A\|_{\infty} \cdot \|\vec{u}(s) - \vec{v}(s)\|_{\infty} \cdot t \end{aligned}$$

Therefore, for  $t < 1/\|A\|_{\infty}$  the contraction mapping theorem guarantees a unique solution.

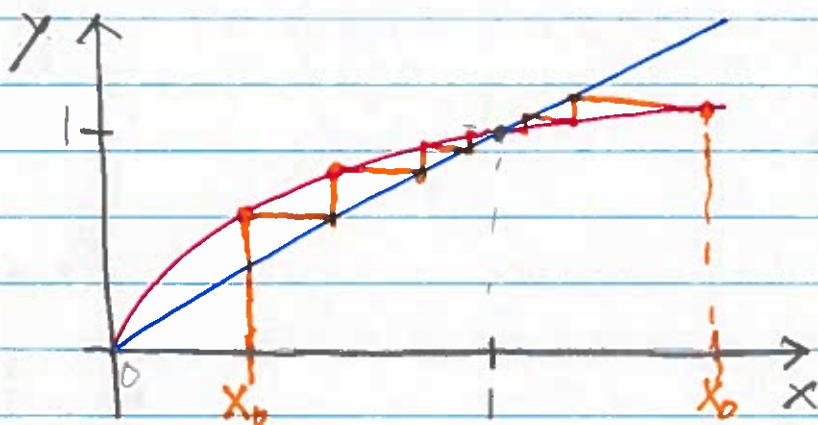
A global solution can be constructed using overlapping intervals.

## Example (Discrete Dynamical Systems):

$$X_{n+1} = \sqrt{X_n} = f(X_n)$$

$$X_0 = a \geq 0$$

Fixed points are given by  
 $x^* = 0$  and  $x^* = 1$ .



$x^* = 1$  is stable, meaning nearby starting initial conditions satisfy  $\lim_{n \rightarrow \infty} X_n = 1$ . How do we prove this??

$$|x_1 - 1| = |f(x_0) - f(1)| = |f'(c)| \cdot |x_0 - 1|$$

where  $c \in B_{x_1}(1)$ . Therefore, if  $|f'(1)| < 1$  we can select  $x_1$  sufficiently small so that:

$$|x_1 - 1| < M \cdot |x_0 - 1|,$$

with  $M < 1$ . We can iterate this process to obtain:

$$|x_n - 1| < M^n |x_0 - 1|$$

$$\Rightarrow \lim_{n \rightarrow \infty} x_n = 1.$$

The key condition to show stability is that  $|f'(x^*)| < 1$ .