

MTH 225

Homework #4

Due Date: February 12, 2025

1. Let $\mathbf{u}, \mathbf{v}, \mathbf{w}, \mathbf{z}$ be vectors in a vector space V . Prove or provide a counterexample: if \mathbf{z} is a linear combination of $\mathbf{u}, \mathbf{v}, \mathbf{w}$ then \mathbf{w} is a linear combination of $\mathbf{u}, \mathbf{v}, \mathbf{z}$.
2. Suppose $f(t)$ and $g(t)$ are functions from \mathbb{R} to \mathbb{R}^2 .

- (a) Prove that if $f(t_0)$ and $g(t_0)$ are linearly independent as vectors in \mathbb{R}^2 for some $t_0 \in \mathbb{R}$ then $f(t)$ and $g(t)$ are linearly independent functions.
- (b) Show that $f(t) = \begin{bmatrix} 1 \\ t \end{bmatrix}$ and $g(t) = \begin{bmatrix} 2t - 1 \\ 2t^2 - t \end{bmatrix}$ are linearly independent functions.
- (c) Show that $f(t_0) = \begin{bmatrix} 1 \\ t_0 \end{bmatrix}$ and $g(t_0) = \begin{bmatrix} 2t_0 - 1 \\ 2t_0^2 - t_0 \end{bmatrix}$ are linearly dependent for all $t_0 \in \mathbb{R}$.

Parts (b) and (c) show that the converse of (a) is not true in general.

3. The Wronskian of a pair of differentiable functions $f(x), g(x)$ defined by

$$W[f(x), g(x)] = \det \left(\begin{bmatrix} f(x) & g(x) \\ f'(x) & g'(x) \end{bmatrix} \right).$$

- (a) Prove that if f and g are linearly dependent then $W[f(x), g(x)] = 0$.
 - (b) Use part (a) to prove that if $W[f(x), g(x)] \neq 0$ then f and g are linearly independent.
 - (c) Let $f(x) = x^3$ and $g(x) = |x|^3$. Show that f and g are linearly independent but $W[f(x), g(x)] = 0$. Why does this not contradict parts (a) and (b)?
4. Consider the set $\mathcal{A} = \{1 + x^2, x + x^2, 1 + 2x + x^2\}$.
- (a) Prove that \mathcal{A} is a basis for $P_2(\mathbb{R})$.
 - (b) Find the coordinates of $p(x) = 1 + 4x + 7x^2$ in this basis.
5. Let $S_{n \times n}(\mathbb{R})$ denote the subspace of $M_{2 \times 2}(\mathbb{R})$ consisting of all symmetric $n \times n$ matrices with complex entries.

- (a) Show that a basis for $S_{2 \times 2}(\mathbb{R})$ is given by

$$\mathcal{A} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}.$$

- (b) Find a basis for $S_{3 \times 3}(\mathbb{R})$ and determine $\dim(S_{3 \times 3}(\mathbb{R}))$. You do not have to prove that your choice is a basis.

6. A real valued matrix is said to be a *semi-magic square* if its row sums and column sums, i.e., the sum of entries in an individual row or column, all add up to the sum number. An example is

$$M = \begin{bmatrix} 8 & 1 & 6 \\ 3 & 5 & 7 \\ 4 & 9 & 2 \end{bmatrix}.$$

- (a) Prove that S , the set of all 3×3 semi-magic squares, is a subspace of $M_{3 \times 3}(\mathbb{R})$.
 - (b) Find a basis for S . You do not have to prove that your choice is a basis and, as a hint, $\dim(S) = 6$.
7. Find a linear transformation $T : \mathbb{R}^2 \mapsto \mathbb{R}^2$ such that

$$T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \text{ and } T\left(\begin{bmatrix} 2 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

8. Consider the map $T : P_3(\mathbb{R}) \mapsto \mathbb{R}^4$ defined by

$$T(a_3x^3 + a_2x^2 + a_1 + a_0) = \begin{bmatrix} a_1 \\ -a_1 \\ a_2 \\ -a_2 \end{bmatrix}.$$

- (a) Show that T is a linear transformation.
 - (b) Find bases for $\ker(T)$ and $\text{im}(T)$.
9. Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and $B = \begin{bmatrix} p & q \\ r & s \end{bmatrix}$ be 2×2 real valued matrices. For each of the following functions, prove that $T : M_{2 \times 2}(\mathbb{R}) \mapsto M_{2 \times 2}(\mathbb{R})$ is a linear transformation and then find its 4×4 matrix representation with respect to the standard basis:

$$\mathcal{A} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$

- (a) $T[X] = AX$.
- (b) $R[X] = XB$.
- (c) $K[X] = AXB$.

Homework #4

#1

Let $\vec{U}, \vec{V}, \vec{W}, \vec{Z}$ be vectors in a vector space V . Prove or provide a counterexample: If \vec{Z} is a linear combination of $\vec{U}, \vec{V}, \vec{W}, \vec{Z}$ then \vec{W} is a linear combination of $\vec{U}, \vec{V}, \vec{Z}$.

Solution:

(Counterexample): Let

$$\vec{U} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \vec{V} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \vec{W} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \vec{Z} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

Consequently, $\vec{Z} = 1 \cdot \vec{U} + 1 \cdot \vec{V} + 0 \cdot \vec{W}$ but $\vec{W} \notin \text{span}\{\vec{U}, \vec{V}, \vec{Z}\}$.

#2

Suppose \vec{f}, \vec{g} are functions from $\mathbb{R} \rightarrow \mathbb{R}^2$

(a) Prove that if $\vec{f}(t_0)$ and $\vec{g}(t_0)$ are linearly independent as vectors in \mathbb{R}^2 for some $t_0 \in \mathbb{R}$ then $\vec{f}(t), \vec{g}(t)$ are linearly independent functions.

(b) Show that $\vec{f}(t) = \begin{bmatrix} 1 \\ t \end{bmatrix}$ and $\vec{g}(t) = \begin{bmatrix} 2t-1 \\ 2t+1 \end{bmatrix}$ are linearly independent functions.

(c) Show that $\vec{f}(t_0) = \begin{bmatrix} 1 \\ t_0 \end{bmatrix}$ and $\vec{g}(t_0) = \begin{bmatrix} 2t_0-1 \\ 2t_0+1 \end{bmatrix}$ are linearly dependent for all $t_0 \in \mathbb{R}$

Solutions:

(a) Suppose for some $t_0 \in \mathbb{R}$, the only solution to the equation $c_1 \vec{f}(t_0) + c_2 \vec{g}(t_0) = \vec{0}$ is $c_1 = c_2 = 0$. Therefore, for all t , the only solution to the equation

$$c_1 \vec{f}(t) + c_2 \vec{g}(t) = \vec{0}$$

is $c_1 = c_2 = 0$ which implies that \vec{f}, \vec{g} are linearly ind. as functions.

(b) Now, consider the equation

$$c_1 \begin{bmatrix} 1 \\ t \end{bmatrix} + c_2 \begin{bmatrix} 2t-1 \\ 2t^2-t \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Setting $t=0$ we obtain

$$c_1 - c_2 = 0 \Rightarrow c_1 = c_2 \quad (\ast)$$

Setting $t=1$ we obtain

$$c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow c_1 = -c_2 \quad (\ast\ast)$$

Therefore, the only combination that satisfies (\ast) and $(\ast\ast)$ is given by $c_1 = c_2 = 0$ and thus \vec{f}, \vec{g} are linearly independent.

(c) Evaluating at t_0 , we have the equation

$$c_1 \begin{bmatrix} 1 \\ t_0 \end{bmatrix} + c_2 \begin{bmatrix} 2t_0-1 \\ 2t_0^2-t_0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 2t_0-1 \\ t_0 & t_0(2t_0-1) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now

$$\det \begin{pmatrix} 1 & 2t_0-1 \\ t_0 & t_0(2t_0-1) \end{pmatrix} = t_0(2t_0-1) - t_0(2t_0-1) = 0.$$

Thus, as vectors in \mathbb{R}^2 , $\vec{f}(t_0), \vec{g}(t_0)$ are linearly dependent.

#3

The Wronskian of a pair of differentiable functions $f(x), g(x)$ is defined by

$$W[f(x), g(x)] = \det \begin{pmatrix} f(x) & g(x) \\ f'(x) & g'(x) \end{pmatrix}$$

(a) Prove that if f, g are linearly dependent then

$$W[f(x), g(x)] = 0.$$

(b) Use part (a) to prove that if $W[f(x), g(x)] \neq 0$ then f and g are linearly independent.

(c) Let $f(x) = x^3$ and $g(x) = |x|^3$. Show that f and g are linearly independent but $W[f(x), g(x)] = 0$.

Solutions:

(a) If f, g are linearly dependent then there exists $c \in \mathbb{R}$ such that

$$f(x) = cg(x).$$

Differentiating, we have

$$f'(x) = cg'(x).$$

Consequently,

$$\begin{aligned} \det \begin{pmatrix} f(x) & g(x) \\ f'(x) & g'(x) \end{pmatrix} &= \det \begin{pmatrix} cg(x) & g(x) \\ cg'(x) & g'(x) \end{pmatrix} \\ &= cg(x)g'(x) - cg(x)g'(x) \\ &= 0. \end{aligned}$$

(b) If we assume $W[f(x), g(x)] \neq 0$ and f, g are linearly dependent then we obtain the contradiction $W[f(x), g(x)] = 0$.

Consequently, f, g are linearly independent.

(c) If we consider the equation

$$c_1 f(x) + c_2 g(x) = 0$$

and set $x=1$ and $x=-1$ we obtain

$$c_1 + c_2 = 0$$

$$-c_1 + c_2 = 0$$

which implies $c_1 = c_2 = 0$. Therefore, f, g are linearly independent.

Now,

$$g(x) = \begin{cases} x^3, & x \geq 0 \\ -x^3, & x < 0 \end{cases} \Rightarrow g'(x) = \begin{cases} 3x^2, & x \geq 0 \\ -3x^2, & x < 0 \end{cases}$$

Therefore,

$$\det(W[f, g]) = \det\left(\begin{matrix} x^3 & x^3 \\ 3x^2 & 3x^2 \end{matrix}\right), \quad x \geq 0$$
$$\det\left(\begin{matrix} x^3 - x^3 \\ 3x^2 - 3x^2 \end{matrix}\right), \quad x < 0$$
$$= 0.$$

#4.

Consider the set $A = \{1+x^3, x+x^3, 1+2x+x^3\}$.

(a) Prove that A is a basis for $P_2(\mathbb{R})$.

(b) Find the coordinates of $p(x) = 1+4x+7x^3$ in this basis.

Solution:

(a) Let $p(x) = a+bx+cx^3$ for some $a, b, c \in \mathbb{R}$ and suppose

$$a+bx+cx^3 = c_1(1+x^3) + c_2(x+x^3) + c_3(1+2x+x^3)$$

for some $c_1, c_2, c_3 \in \mathbb{R}$

$$\Rightarrow a+bx+cx^3 = (c_1+c_3) + (c_2+2c_3)x + (c_1+c_2+c_3)x^3$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 & | & a \\ 0 & 1 & 2 & | & b \\ 1 & 1 & 1 & | & c \end{bmatrix}_{R1} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & | & a \\ 0 & 1 & 2 & | & b \\ 0 & 1 & 0 & | & c-a-b \end{bmatrix}_{R2} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & | & a \\ 0 & 1 & 2 & | & b \\ 0 & 0 & -2 & | & c-a-b \end{bmatrix}_{L2} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & | & a \\ 0 & 1 & 2 & | & b \\ 0 & 0 & 1 & | & \frac{c-a-b}{2} \end{bmatrix}_{-R3} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & | & a \\ 0 & 1 & 2 & | & b \\ 0 & 0 & 1 & | & \frac{c-a-b}{2} \end{bmatrix}_{-2R3}$$

$$\begin{bmatrix} 1 & 0 & 0 & \frac{(a-b+c)/2}{1} \\ 0 & 1 & 0 & \frac{(c-a)}{1} \\ 0 & 0 & 1 & \frac{(a+b-c)/2}{1} \end{bmatrix}$$

Consequently, the unique solution is

$$c_1 = (a-b+c)/2$$

$$c_2 = c-a$$

$$c_3 = (a+b-c)/2$$

and thus A is a basis.

(b) For $p(x) = 1 + 4x + 7x^2$, we have $a=1, b=4, c=7$ and thus

$$c_1 = 2$$

$$c_2 = 6$$

$$c_3 = -1$$

Consequently,

$$[p(x)]_A = \begin{bmatrix} 2 \\ 6 \\ -1 \end{bmatrix}.$$

#5.

Let $S_{n \times n}(\mathbb{R})$ denote the subspace of $M_{n \times n}(\mathbb{R})$ consisting of all symmetric $n \times n$ matrices with complex entries.

(a) Show that a basis for $S_{2 \times 2}(\mathbb{R})$ is given by

$$A = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}.$$

(b) Find a basis for $S_{3 \times 3}(\mathbb{R})$ and determine $\dim(S_{3 \times 3}(\mathbb{R}))$.

Solution:

(a) If $A \in S_{2 \times 2}(\mathbb{R})$ then there exists $a, b, c \in \mathbb{R}$ such that

$$A = \begin{bmatrix} a & b \\ b & c \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

and thus A is a basis.

(b) If $B \in S_{3 \times 3}(\mathbb{R})$ then there exists $a, b, c, d, e, f \in \mathbb{R}$ such that

$$B = \begin{bmatrix} a+d+f & & \\ a+b+e & & \\ f+c & & \end{bmatrix} = a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + e \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} + f \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

and thus a basis is given by

$$\beta = \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \right\}$$

$$\Rightarrow \dim(S_{3 \times 3}(\mathbb{R})) = 6.$$

#6

(a) Prove that S , the set of 3×3 semi-magic squares, is a subspace of $M_{3 \times 3}(\mathbb{R})$.

(b) Find a basis for S .

Solution:

(a) Let $A, B \in S$ and $\lambda \in \mathbb{R}$. Therefore, there exists $a, b \in \mathbb{R}$ such that the rows and columns of A, B sum to a, b . Consequently, if we let $C = A + \lambda B$ then the row and column sums are given by $a + \lambda b$ and thus $C \in S$. Therefore, S is a subspace.

(b) The set

$$A = \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \right\}$$

is a basis and thus

$$\dim(S) = 6.$$

#7

Find a linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that

$$T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ -1 \end{bmatrix}, T\left(\begin{bmatrix} 2 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ -1 \end{bmatrix}.$$

Solution:

Let T have the representation

$$T = \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

Consequently,

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \text{ and } \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$\Rightarrow a+2b=2 \quad \text{and} \quad 2a+b=0$$

$$c+2d=-1 \quad \text{and} \quad 2c+d=-1$$

$$\Rightarrow \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 0 \end{bmatrix} \xrightarrow{-2R1} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & -1 \end{bmatrix} \xrightarrow{-2R1}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 2 \\ 0 & -3 & -4 \end{bmatrix} \xrightarrow{1/3} \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 1 \end{bmatrix} \xrightarrow{1/3}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 4/3 \end{bmatrix} \xrightarrow{-2R2} \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & -1/3 \end{bmatrix} \xrightarrow{-2R2}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & -2/3 \\ 0 & 1 & 4/3 \end{bmatrix} \xrightarrow{1/3} \begin{bmatrix} 1 & 0 & -1/3 \\ 0 & 1 & -1/3 \end{bmatrix}$$

Consequently,

$$a = -\frac{2}{3}$$

$$b = \frac{4}{3}$$

$$c = -\frac{1}{3}$$

$$d = -\frac{1}{3}$$

and therefore

$$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} -\frac{2}{3}, \frac{4}{3} \\ -\frac{1}{3}, -\frac{1}{3} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -\frac{2}{3}x + \frac{4}{3}y \\ -\frac{1}{3}x - \frac{1}{3}y \end{bmatrix}$$

#8

Consider the map $T: P_3(\mathbb{R}) \rightarrow \mathbb{R}^4$ by

$$T(a_3 x^3 + a_2 x^2 + a_1 x + a_0) = \begin{bmatrix} a_1 \\ a_1 \\ a_2 \\ -a_2 \end{bmatrix}.$$

(a) Show that T is a linear transformation.

(b) Find bases for $\ker(T)$ and $\text{im}(T)$.

Solution:

(a) Let $p_1(x), p_2(x) \in P_3(\mathbb{R})$. Therefore, there exists $a_3, a_2, a_1, a_0, b_3, b_2, b_1, b_0 \in \mathbb{R}$ such that

$$p_1(x) = a_3 x^3 + a_2 x^2 + a_1 x + a_0,$$

$$p_2(x) = b_3 x^3 + b_2 x^2 + b_1 x + b_0.$$

Consequently, for $\lambda \in \mathbb{R}$ it follows that

$$T(p_1(x) + \lambda p_2(x)) = \begin{bmatrix} a_1 + \lambda b_1 \\ a_1 - \lambda b_1 \\ a_2 + \lambda b_2 \\ -a_2 - \lambda b_2 \end{bmatrix} = \begin{bmatrix} a_1 \\ a_1 \\ a_2 \\ -a_2 \end{bmatrix} + \lambda \begin{bmatrix} b_1 \\ -b_1 \\ b_2 \\ -b_2 \end{bmatrix} = T(p_1) + \lambda(T(p_2)).$$

Therefore, T is a linear transformation.

(b) $\ker(T) = \text{span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

$$\text{im}(T) = \text{span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix} \right\}$$

#9

Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and $B = \begin{bmatrix} p & q \\ r & s \end{bmatrix}$ be real 2×2 matrices. For each of the following functions, prove that $T: M_{2 \times 2}(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$ is a linear transformation and then find its 4×4 matrix representation with respect to the standard basis.

(a) $T[X] = AX$

(b) $R[X] = XB$

(c) $K[X] = AXB$

Solution:

(a) Let $X, Y \in M_{2 \times 2}(\mathbb{R})$ and $\lambda \in \mathbb{R}$. Therefore,

$$T[X + \lambda Y] = A(X + \lambda Y) = AX + \lambda AY = T[X] + \lambda T[Y]$$

and thus T is linear.

Now,

$$T\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a & 0 \\ c & 0 \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$$T\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & a \\ 0 & c \end{bmatrix} = a \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$T\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} b & 0 \\ d & 0 \end{bmatrix} = b \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$$T\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & b \\ 0 & d \end{bmatrix} = b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Therefore, the matrix representation is given by,

$$\begin{bmatrix} a & b & 0 & 0 \\ 0 & a & b & 0 \\ c & d & 0 & 0 \\ 0 & c & d & 0 \end{bmatrix}$$

(b) Let $X, Y \in M_{2 \times 2}(\mathbb{R})$ and $\lambda \in \mathbb{R}$. Therefore,

$$R[X + \lambda Y] = (X + \lambda Y)B = XB + \lambda YB = R[X] + \lambda R[Y]$$

and thus T is linear.

Now,

$$R\left[\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}\right] = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} p & q \\ r & s \end{bmatrix} = \begin{bmatrix} p & q \\ 0 & 0 \end{bmatrix} = p \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + q \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$R\left[\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right] = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} p & q \\ r & s \end{bmatrix} = \begin{bmatrix} r & s \\ 0 & 0 \end{bmatrix} = r \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + s \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$R\left[\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}\right] = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} p & q \\ r & s \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ p & q \end{bmatrix} = p \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + q \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$R\left[\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}\right] = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} p & q \\ r & s \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ rs & 0 \end{bmatrix} = r \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + s \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Therefore, the matrix representation is given by

$$\begin{bmatrix} p & r & 0 & 0 \\ q & s & 0 & 0 \\ 0 & 0 & p & r \\ 0 & 0 & q & s \end{bmatrix}$$

(c) Let $A, B \in M_{2 \times 2}(\mathbb{R})$ and $\lambda \in \mathbb{R}$. Therefore,

$$K[X + \lambda Y] = A(X + \lambda Y)B = (AX + \lambda AY)B = AXB + \lambda AYB = K[X] + \lambda K[Y]$$

and thus K is a linear transformation.

To find the matrix representation we can commute

$$\begin{bmatrix} a & b & 0 & 0 \\ 0 & a & b & 0 \\ c & d & 0 & 0 \\ 0 & c & d & 0 \end{bmatrix} \begin{bmatrix} p & r & 0 & 0 \\ q & s & 0 & 0 \\ 0 & 0 & p & r \\ 0 & 0 & q & s \end{bmatrix} = \begin{bmatrix} ap & ar & bp & bs \\ aq & as & bq & bs \\ cp & cr & dp & dr \\ cq & cs & dq & ds \end{bmatrix}$$