

Lecture #9: Diagonalization and Eigenvalues

Example:

Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be given by

$$\begin{aligned} T(\vec{v}) &= A\vec{v} \\ &= \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \vec{v} \end{aligned}$$

Consider the basis

$$\beta = \left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right\} = \{ \vec{u}_1, \vec{u}_2 \}, \quad \mathcal{S} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} = \{ \vec{e}_1, \vec{e}_2 \}.$$

$$\Rightarrow T(\vec{u}_1) = A\vec{u}_1 = \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \end{bmatrix} = -2 \begin{bmatrix} 1 \\ -1 \end{bmatrix},$$

$$T(\vec{u}_2) = A\vec{u}_2 = \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 15 \\ 20 \end{bmatrix} = 5 \begin{bmatrix} 3 \\ 4 \end{bmatrix}.$$

There

$$[T(\beta, \beta)] = \begin{bmatrix} -2 & 0 \\ 0 & 5 \end{bmatrix} = \Delta$$

$$\Rightarrow \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} \vec{v} = [T(\mathcal{S}, \mathcal{S})] \vec{v} = [I(\beta, \mathcal{S})] [T(\beta, \beta)] [I(\mathcal{S}, \beta)] \vec{v}$$

$$\Rightarrow \boxed{A = P^{-1} \Delta P}$$

$$P = \begin{bmatrix} 1 & 3 \\ -1 & 4 \end{bmatrix}, \quad P^{-1} = \frac{1}{7} \begin{bmatrix} 4 & 3 \\ -1 & 1 \end{bmatrix}$$

$$\Rightarrow \boxed{\begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 4 & -3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -2 & 0 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ -1 & 4 \end{bmatrix}} \rightarrow \text{Diagonalization}$$

Example:

If $A = \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix}$, what is A^3 ?

$$A = P^{-1} \Delta P$$

$$\Rightarrow A^3 = P^{-1} \Delta P P^{-1} \Delta P P^{-1} \Delta P = P^{-1} \Delta^3 P$$

Therefore,

$$A^3 = \frac{1}{7} \begin{bmatrix} 4 & -3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -8 & 0 \\ 0 & 125 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ -1 & 4 \end{bmatrix}$$

Remark:

The key to diagonalization was the existence of a vector (eigenvector) and scalar $\lambda \in F$ (eigenvalue) such that

$$T(\vec{v}) = \lambda \vec{v}, [T(S, S)] \vec{v} = \lambda \vec{v} \text{ (If a matrix exists).}$$

If $\beta = \{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis of eigenvectors then

$$[T(\beta, \beta)] = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

Example:

If $T: C^\infty(\mathbb{R}) \rightarrow C^\infty(\mathbb{R})$ is defined by $T(f) = \frac{df}{dx}$, what are the eigenvectors of T ?

$$T(f) = \lambda f$$

$$\Rightarrow \frac{df}{dx} = \lambda f$$

For every real number $\lambda \in \mathbb{R}$ there is a corresponding eigenfunction $f_\lambda(x) = e^{\lambda x}$.