

PHY 113 A General Physics I

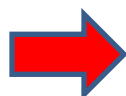
9-9:50 AM MWF Olin 101

Plan for Lecture 14:

Chapter 9 -- Linear momentum

- 1. Impulse and momentum in two dimensions**
- 2. Center of mass**
- 3. Collision analysis in two dimensions**

5	09/07/2012	Motion in 2d	4.1-4.3	4.3.4.50	09/10/2012
6	09/10/2012	Circular motion	4.4-4.6	4.29.4.30	09/12/2012
7	09/12/2012	Newton's laws	5.1-5.6	5.1.5.13	09/14/2012
8	09/14/2012	Newton's laws applied	5.7-5.8	5.20.5.30.5.48	09/17/2012
	09/17/2012	Review	1-5		
	09/19/2012	Exam	1-5		
9	09/21/2012	More applications of Newton's laws	6.1-6.4	6.3.6.14	09/24/2012
10	09/24/2012	Work	7.1-7.4	7.1.7.15	09/26/2012
11	09/26/2012	Kinetic energy	7.5-7.9	7.31.7.41.7.49	09/28/2012
12	09/28/2012	Conservation of energy	8.1-8.5	8.6.8.22.8.35	10/01/2012
13	10/01/2012	Momentum and collisions	9.1-9.4	9.15.9.18	10/03/2012
14	10/03/2012	Momentum and collisions	9.5-9.9	9.29.9.37	10/05/2012
	10/05/2012	Review	6-9		
	10/08/2012	Exam	6-9		
15	10/10/2012	Rotational motion	10.1-10.5		10/12/2012



Relationship between Newton's second law and linear momentum for a single particle:

$$\mathbf{F} = m\mathbf{a} = m \frac{d\mathbf{v}}{dt} = \frac{d(m\mathbf{v})}{dt} = \frac{d\mathbf{p}}{dt}$$

Using a little calculus:

$$\mathbf{F}dt = d\mathbf{p}$$

$$\int_i^f \mathbf{F}dt = \int_i^f d\mathbf{p} = \mathbf{p}_f - \mathbf{p}_i$$

Define "impulse": $\mathbf{I} = \int_i^f \mathbf{F}dt$

$$\mathbf{I} = \int_i^f \mathbf{F}dt = \mathbf{p}_f - \mathbf{p}_i$$

Physics of composite systems

Newton's second law :

$$\sum_i \mathbf{F}_i = \sum_i m_i \mathbf{a}_i = \sum_i m_i \frac{d\mathbf{v}_i}{dt} = \sum_i \frac{dm_i \mathbf{v}_i}{dt} = \frac{d}{dt} \left(\sum_i \mathbf{p}_i \right)$$

Note that if $\sum_i \mathbf{F}_i = 0$, then :

$$\frac{d}{dt} \left(\sum_i \mathbf{p}_i \right) = 0$$

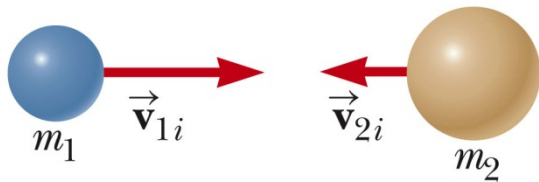
$$\Rightarrow \sum_i \mathbf{p}_i = (\text{constant})$$

$$\Rightarrow \sum_i \mathbf{p}_{i \text{ initial}} = \sum_i \mathbf{p}_{i \text{ final}}$$

Examples of completely one-dimensional (head-on) collision; balls moving on a frictionless surface

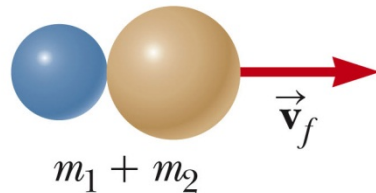
inelastic:

Before the collision, the particles move separately.



a

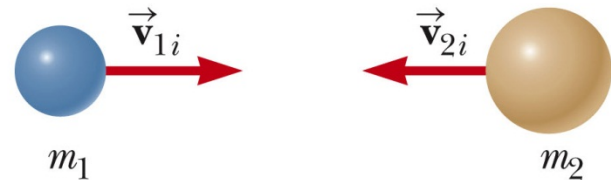
After the collision, the particles move together.



b

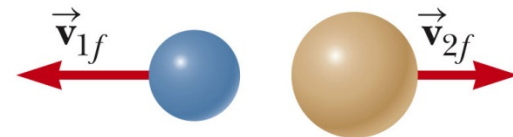
elastic:

Before the collision, the particles move separately.



a

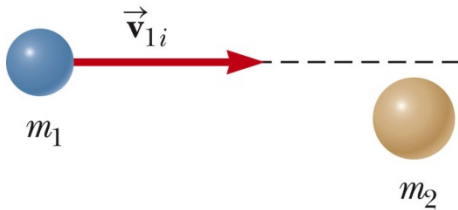
After the collision, the particles continue to move separately with new velocities.



b

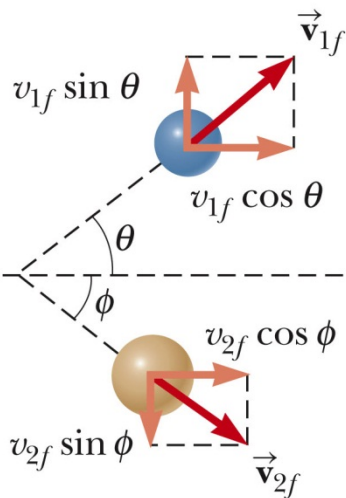
Examples of two-dimensional collision; balls moving on a frictionless surface

Before the collision



a

After the collision



b

$$\sum_i \mathbf{p}_{i \text{ initial}} = \sum_i \mathbf{p}_{i \text{ final}}$$

$$m_1 v_{1i} = m_1 v_{1f} \cos \theta + m_2 v_{2f} \cos \phi$$

$$0 = m_1 v_{1f} \sin \theta - m_2 v_{2f} \sin \phi$$

Knowns: m_1, m_2, v_{1i}

Unknowns: $v_{1f}, v_{2f}, \theta, \phi$

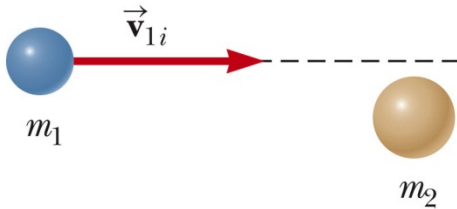
Need 2 more equations --

Examples of two-dimensional collision; balls moving on a frictionless surface

Suppose : $m_1 = m_2 = 0.06\text{kg}$, $v_{1i} = 2\text{m/s}$,

$$v_{2f} = 1\text{m/s}, \quad \phi = 20^\circ$$

Before the collision



$$m_1 v_{1i} = m_1 v_{1f} \cos \theta + m_2 v_{2f} \cos \phi$$

$$0 = m_1 v_{1f} \sin \theta - m_2 v_{2f} \sin \phi$$

$$v_{1f} \sin \theta = v_{2f} \sin \phi$$

$$= (1\text{m/s}) \sin 20^\circ = 0.342\text{m/s}$$

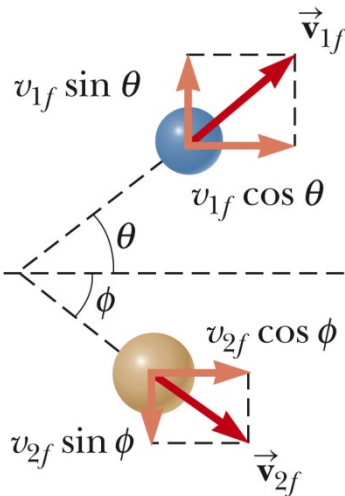
$$v_{1f} \cos \theta = v_{1i} - v_{2f} \cos \phi$$

$$= (2\text{m/s}) - (1\text{m/s})(\cos 20^\circ) = 1.060\text{m/s}$$

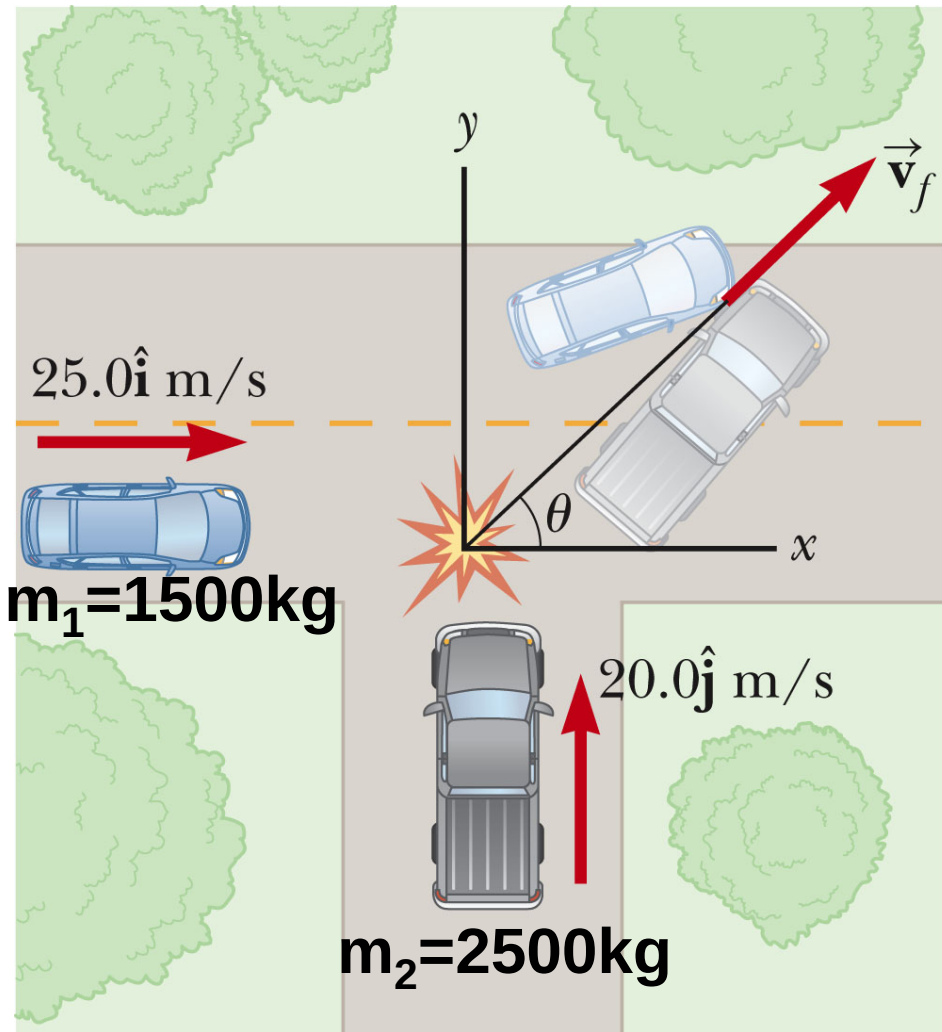
$$\tan \theta = \frac{0.342}{1.060} \Rightarrow \theta = 17.88^\circ$$

$$v_{1f} = \frac{0.342\text{m/s}}{\sin 17.88^\circ} = \frac{1.060\text{m/s}}{\cos 17.88^\circ} = 1.11\text{m/s}$$

After the collision



Example: two-dimensional totally inelastic collision



$$m_1 \mathbf{v}_{1i} + m_2 \mathbf{v}_{2i} = (m_1 + m_2) \mathbf{v}_f$$

$$\mathbf{v}_f = \frac{m_1}{m_1 + m_2} \mathbf{v}_{1i} + \frac{m_2}{m_1 + m_2} \mathbf{v}_{2i}$$

$$\begin{aligned} \mathbf{v}_f &= \frac{1500}{4000} 25\text{ m/s} \hat{i} + \frac{2500}{4000} 20\text{ m/s} \hat{j} \\ &= 9.375\text{ m/s} \hat{i} + 12.5\text{ m/s} \hat{j} \end{aligned}$$

Loss of kinetic energy in this case:

$$\begin{aligned} \Delta E &= \frac{1}{2} (m_1 + m_2) |\mathbf{v}_f|^2 - \left(\frac{1}{2} m_1 |\mathbf{v}_{1i}|^2 + \frac{1}{2} m_2 |\mathbf{v}_{2i}|^2 \right) \\ &= \frac{1}{2} (4000) ((9.375)^2 + (12.5)^2) \\ &\quad - \left(\frac{1}{2} 1500 (25)^2 + \frac{1}{2} 2500 (20)^2 \right) \end{aligned}$$

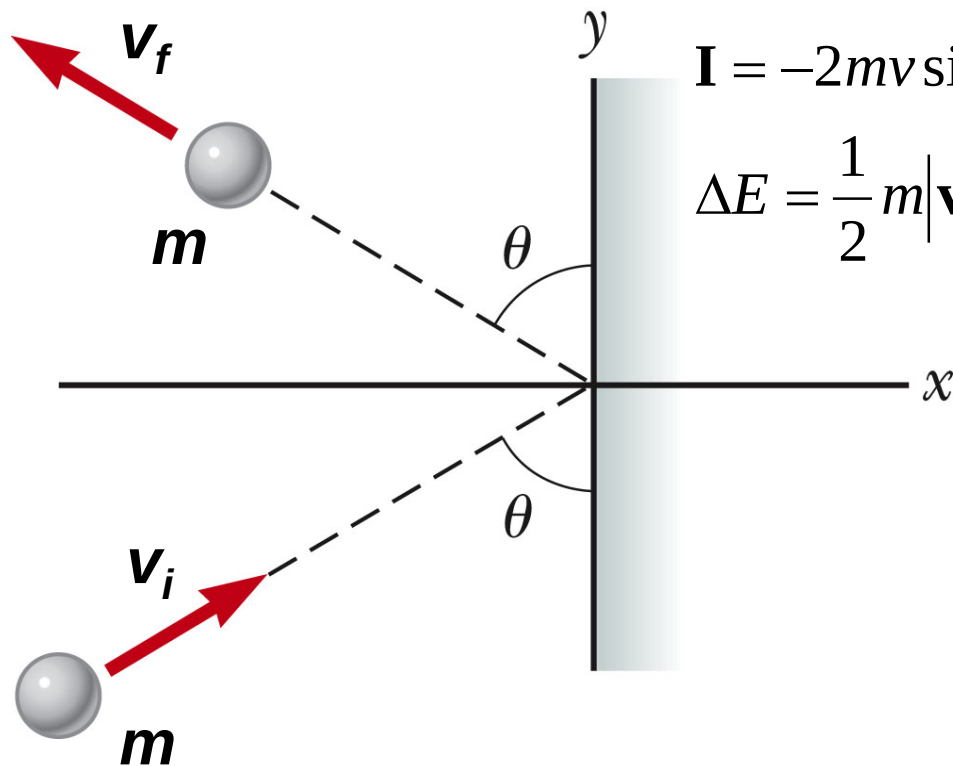
$$\Delta E = -4.8 \times 10^5 \text{ J}$$

iclicker exercise:

Can this analysis be used to analyze a real collision?

- A. Of course! The laws of physics must be obeyed.**
- B. Of course NOT! In physics class we only deal with idealized situations which never happen.**

Another example of 2-dimensional elastic collision:

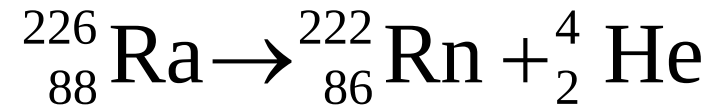


In this case, the collision is elastic -- $|\mathbf{v}_i| = |\mathbf{v}_f| \equiv v$

$$\mathbf{I} = -2mv \sin \theta \hat{\mathbf{i}}$$

$$\Delta E = \frac{1}{2} m |\mathbf{v}_f|^2 - \frac{1}{2} m |\mathbf{v}_i|^2 = 0$$

Energy analysis of a simple nuclear reaction :

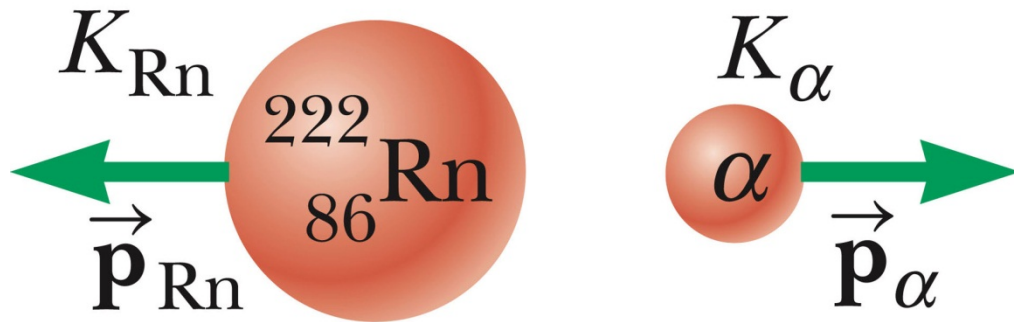


$$K_{\text{Ra}} = 0$$

$$\vec{\mathbf{p}}_{\text{Ra}} = 0$$

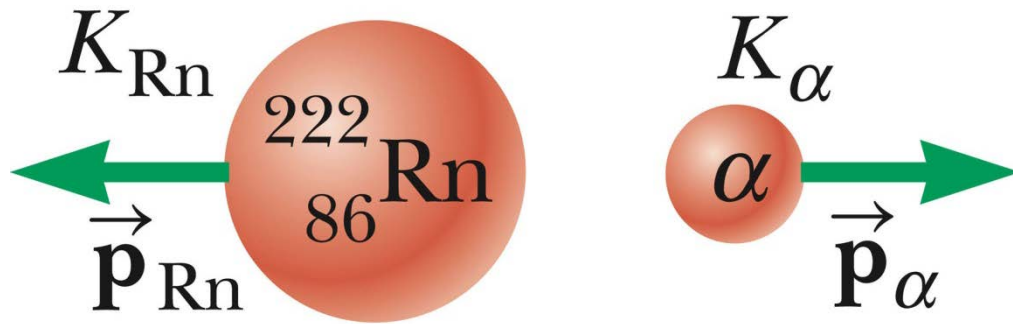
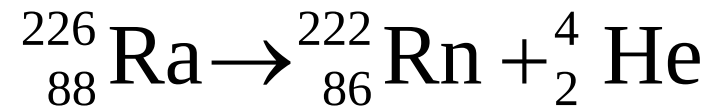
Before decay

$$Q = 4.87 \text{ MeV}$$



After decay

Energy analysis of a simple reaction :



$$Q = 4.87 \text{ MeV}$$

$$\mathbf{p}_{Rn} = -\mathbf{p}_{He} \equiv \mathbf{p}$$

$$Q = \frac{p_{Rn}^2}{2m_{Rn}} + \frac{p_{He}^2}{2m_{He}} \approx \frac{p^2}{2m_u} \left(\frac{1}{222} + \frac{1}{4} \right)$$

$$E_{He} = \frac{p_{He}^2}{2m_{He}} = \frac{1/4}{1/222 + 1/4} Q = 0.98 \cdot Q = 4.8 \text{ MeV}$$

The notion of the center of mass and the physics of composite systems

Newton's second law :

$$\sum_i \mathbf{F}_i = \sum_i m_i \mathbf{a}_i = \sum_i m_i \frac{d\mathbf{v}_i}{dt} = \sum_i \frac{d(m_i \mathbf{v}_i)}{dt} = \frac{d}{dt} \left(\sum_i \mathbf{p}_i \right)$$

or

$$\sum_i \mathbf{F}_i = \sum_i m_i \mathbf{a}_i = \sum_i m_i \frac{d^2 \mathbf{r}_i}{dt^2} = \sum_i \frac{d^2 (m_i \mathbf{r}_i)}{dt^2}$$

$$\text{Define: } \mathbf{r}_{CM} \equiv \frac{\sum_i (m_i \mathbf{r}_i)}{M} \quad M \equiv \sum_i (m_i)$$

$$\sum_i \mathbf{F}_i = \mathbf{F}_{total} = M \frac{d^2 \mathbf{r}_{CM}}{dt^2}$$

General relation for center of mass :

Define : $\mathbf{r}_{CM} \equiv \frac{\sum_i (m_i \mathbf{r}_i)}{M}$ $M \equiv \sum_i (m_i)$

$$\sum_i \mathbf{F}_i = \mathbf{F}_{total} = M \frac{d^2 \mathbf{r}_{CM}}{dt^2}$$

If $\mathbf{F}_{total} \equiv \sum_i \mathbf{F}_i = 0$, then :

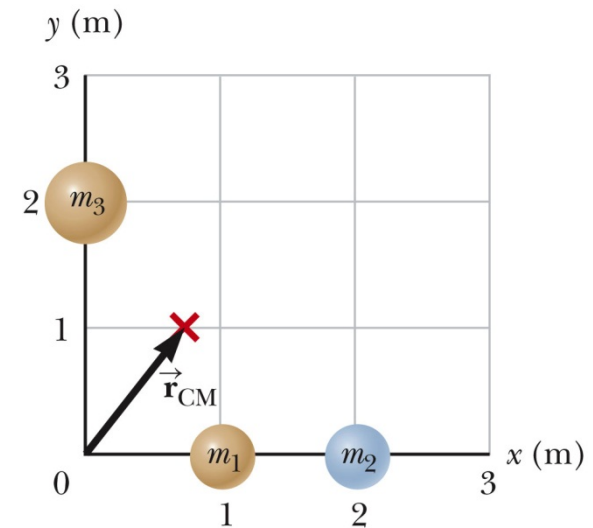
$$\frac{d}{dt} \left(\sum_i \mathbf{p}_i \right) = 0$$

$$\Rightarrow \sum_i \mathbf{p}_i = (\text{constant})$$

$$\Rightarrow \sum_i \mathbf{p}_{i \text{ initial}} = \sum_i \mathbf{p}_{i \text{ final}} = M \frac{d\mathbf{r}_{CM}}{dt}$$

Finding the center of mass

$$\mathbf{r}_{CM} \equiv \frac{\sum_i (m_i \mathbf{r}_i)}{M} \quad M \equiv \sum_i (m_i)$$



In this example: $m_1 = m_2 = 1\text{kg}$; $m_3 = 2\text{kg}$

$$\mathbf{r}_{CM} = \frac{m_1 x_1 \hat{\mathbf{i}} + m_2 x_2 \hat{\mathbf{i}} + m_3 y_3 \hat{\mathbf{j}}}{m_1 + m_2 + m_3}$$

$$\begin{aligned} \mathbf{r}_{CM} &= \frac{(1)(1m)\hat{\mathbf{i}} + (1)(2m)\hat{\mathbf{i}} + (2)(2m)\hat{\mathbf{j}}}{4} \\ &= 0.75m\hat{\mathbf{i}} + 1.00m\hat{\mathbf{j}} \end{aligned}$$

Finding the center of mass

For a solid object composed of constant density material, the center of mass is located at the center of the object.

