PHY 113 A General Physics I 9-9:50 AM MWF Olin 101

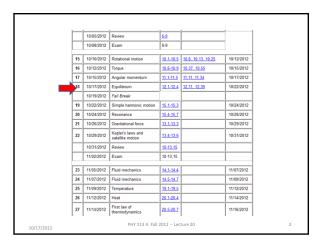
Plan for Lecture 20:

Chapter 12 - Static equilibrium

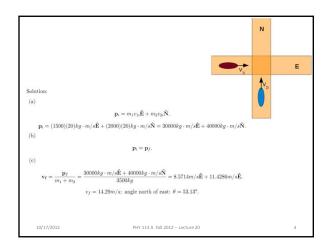
- 1. Balancing forces and torques; stability
- 2. Center of gravity
- 3. Note: May not have time to cover elastic properties of materials

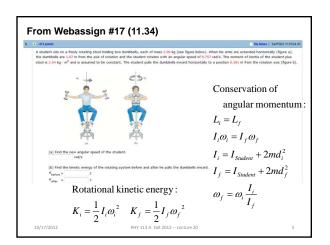
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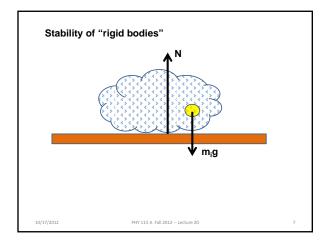


| Comment on exam question #4 | N | |
|---|---|---|
| V _{ji} | | E |
| The diagram above shows two vehicles approaching an intersection. The vehicle labeled "1" has mass $m_1 = 1500kg$ and a velocity of $v_{11} = 20m/s$ in the east (E) direction. The vehicle labeled "2" has a mass $m_2 = 2000kg$ and a velocity of $v_{21} = 20m/s$ in the north (N) direction. The two vehicles collide in the middle of the intersection and stick together with the velocity of the combined system of v_1 immediately after the collision. Assume that because of road conditions (small friction due to ice), it is a good approximation to assume that momentum is conserved immediately before and after the collision. (a) What is the momentum of the two vehicle system before the collision? (b) What is the momentum of the two vehicle system immediately after the c) What is the velocity of the combined system of $\mathbf{v_f}$ (magnitude and direct immediately after the collision? | | ? |
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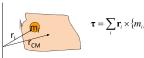


| Cond | litions for stable equilibrium | |
|------------|--|---|
| F F | Balance of force: $\sum_{i} \mathbf{F}_{i} = 0$ Balance of torque: $\sum_{i} \mathbf{\tau}_{i} = 0$ | |
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| | | |



Center-of-mass $\mathbf{r}_{CM} \equiv \frac{\sum\limits_{i} m_{i} \mathbf{r}_{i}}{\sum\limits_{i} m_{i}}$

Torque on an extended object due to gravity (near surface of the earth) is the same as the torque on a point mass M located at the center of mass.

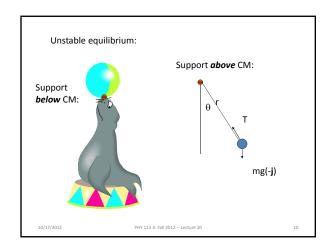


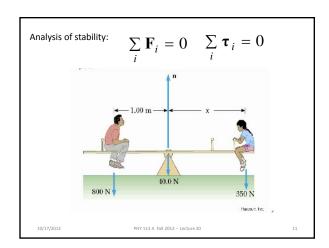
 $\mathbf{r} = \sum_{i} \mathbf{r}_{i} \times \{m_{i}g(-\mathbf{j})\} = \mathbf{r}_{CM} \times \{Mg(-\mathbf{j})\}$

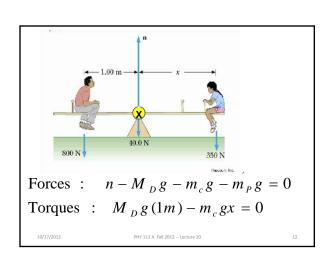
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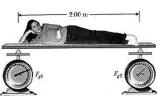
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Notion of equilibrium: $\sum_i \mathbf{F}_i = 0 \qquad \sum_i \mathbf{\tau}_i = 0$ Notion of stability: $\sum_i \mathbf{F}_i = 0 \qquad \sum_i \mathbf{\tau}_i = 0$ T- $\operatorname{mg} \cos \theta = 0$ $-\operatorname{mg} \sin \theta = -\operatorname{ma}_\theta$ $\mathbf{\tau} = \mathbf{I} \alpha \Rightarrow \operatorname{r} \operatorname{mg} \sin \theta = \operatorname{mr}^2 \alpha = \operatorname{mra}_\theta$ Example of stable equilibrium.





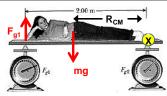




A student takes a nap on a massless plank which is supported by two scales as shown. If the left and right scale readings are $F_{g1} = 350$ N and $F_{g2} = 300$ N, respectively, what is her total weight and where is her center of mass located? (Please indicate whether you are measuring her center of mass from her feet or head.)

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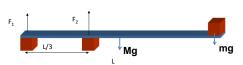
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Torques : $-F_{g1}(2m) + mg(R_{CM}) = 0$

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iclicker question:

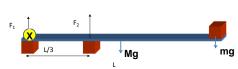


Consider the above drawing of the two supports for a uniform plank which has a total weight Mg and has a weight mg at its end. What can you say about F_1 and F_2 ?

- (a) F_1 and F_2 are both up as shown.
- (b) F_1 is up but F_2 is down.
- (c) F_1 is down but F_2 is up.

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Forces: $F_1 + F_2 - Mg - mg = 0$

Torques : $F_2 \frac{L}{3} - Mg \frac{L}{2} - mgL = 0$

$$F_2 = \frac{3}{2}Mg + 3mg$$
 $F_1 = -\frac{1}{2}Mg - 2mg$

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iclicker question:

The fact that we found F_1 <0 means:

- A. We set up the problem incorrectly
- B. The analysis is correct, but the direction of F₁ is opposite to the arrow
- C. Physics makes no sense

iclicker question:

What would happen if we analyzed this problem by placing the pivot point at F₁?:

- A. The answer would be the same.
- B. The answer would be different.
- C. Physics makes no sense

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