PHY 711 Classical Mechanics and Mathematical Methods 9-9:50 AM MWF Olin 107

Plan for Lecture 12:

Continue reading Chapter 3 & 6

- 1. Hamiltonian formalism
- 2. Phase space & Liouville's theorem
- 3. Modern applications

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-	Date	F&W Reading	nary schedule subject to frequent adjustr	Assignment	Due
1	MANAGER PROPERTY AND ADDRESS OF THE PARTY AND	Chap. 1	Introduction	#1	9/6/2017
		Chap. 1	Scattering theory	#2	9/6/2017
		Chap, 1	Scattering theory		
		Chap. 1	Scattering theory	#3	9/6/2017
		Chap 2			9/8/2017
6	Fri, 9/08/2017	Chap. 3	Calculus of variations	#5	9/11/201
7	Mon, 9/11/2017	Chap.3	Calculus of variations	#6	9/13/201
8	Wed, 9/13/2017	Chap 3	Lagrangian Mechanics	#7	9/15/201
9	Fri, 9/15/2017	Chap. 3 and 6	Lagrangian mechanics and constraints	#8	9/20/201
10	Mon, 9/18/2017	Chap. 3 and 6	Constants of the motion		
11	Wed, 9/20/2017	Chap. 3 and 6	Hamiltonian formalism	#9	9/27/201
12	Fri, 9/22/2017	Chap. 3 and 6	Liouville equation		
13	Mon, 9/25/2017				
14	Wed, 9/27/2017				
	Fri, 9/29/2017				
	Mon, 10/02/2017		Take-home exam - No class		
	Wed, 10/04/2017		Take-home exam No class		
16	Fri, 10/06/2017				

Hamiltonian formalism

 $H = H\big(\big\{q_\sigma(t)\big\}, \big\{p_\sigma(t)\big\}, t\big)$

Canonical equations of motion

$$\frac{dq_{\sigma}}{dt} = \frac{\partial H}{\partial p_{\sigma}}$$

$$\frac{dp_{\sigma}}{dt} = -\frac{\partial H}{\partial q_{\sigma}}$$

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Phase space

Phase space is defined at the set of all coordinates and momenta of a system:

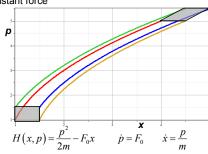
 $(\{q_{\sigma}(t)\},\{p_{\sigma}(t)\})$

For a d dimensional system with N particles, the phase space corresponds to 2dN degrees of freedom.

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Phase space diagram for one-dimensional motion due to constant force

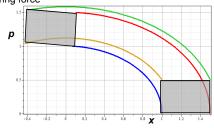


 $p_i(t) = p_{0i} + F_0 t$ $x_i(t) = x_{0i} + \frac{p_{0i}}{m}t + \frac{1}{2}F_0 t^2$

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Phase space diagram for one-dimensional motion due to spring force



 $H(x,p) = \frac{p^2}{2m} + \frac{1}{2}m\omega^2 x^2 \qquad \dot{p} = -m\omega^2 x \qquad \dot{x} = \frac{p}{m}$

 $p_i(t) = p_{0i} \cos(\omega t + \theta_{0i})$ $x_i(t) = \frac{p_{0i}}{m\omega} \sin(\omega t + \theta_{0i})$

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Liouville's Theorem (1838)

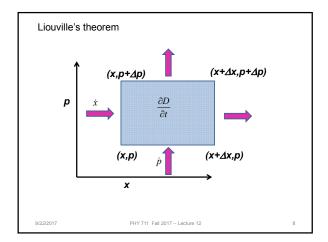
The density of representative points in phase space corresponding to the motion of a system of particles remains constant during the motion.

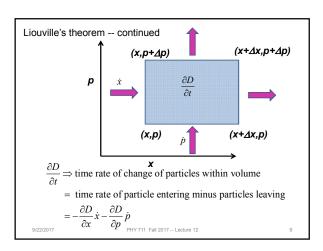
Denote the density of particles in phase space : $D = D(\{q_{\sigma}(t)\}, \{p_{\sigma}(t)\}, t)$

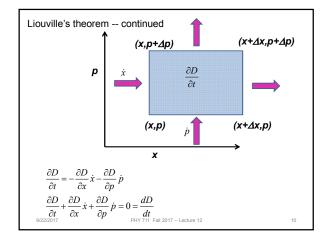
$$\frac{dD}{dt} = \sum_{\sigma} \left(\frac{\partial D}{\partial q_{\sigma}} \dot{q}_{\sigma} + \frac{\partial D}{\partial p_{\sigma}} \dot{p}_{\sigma} \right) + \frac{\partial D}{\partial t}$$

According to Liouville's theorem: $\frac{dD}{dt} = 0$

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Review:

Liouville's theorem:

Imagine a collection of particles obeying the Canonical equations of motion in phase space.

Let ${\cal D}$ denote the "distribution" of particles in phase space :

$$D = D(\{q_1 \cdots q_{3N}\}, \{p_1 \cdots p_{3N}\}, t)$$

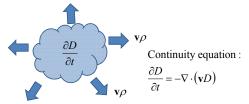
Liouville's theorm shows that:

$$\frac{dD}{dt} = 0 \qquad \Rightarrow D \text{ is constant in time}$$

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Proof of Liouville'e theorem:



Note: in this case, the velocity is the 6*N* dimensional vector: $\mathbf{v} = (\dot{\mathbf{r}}_1, \dot{\mathbf{r}}_2, \dots \dot{\mathbf{r}}_N, \dot{\mathbf{p}}_1, \dot{\mathbf{p}}_2, \dots \dot{\mathbf{p}}_N)$

We also have a 6N dimensional gradient:

$$\nabla = \left(\nabla_{\mathbf{r}_1}, \nabla_{\mathbf{r}_2}, \dots \nabla_{\mathbf{r}_N}, \nabla_{\mathbf{p}_1}, \nabla_{\mathbf{p}_2}, \dots \nabla_{\mathbf{p}_N}\right)$$

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$$\begin{split} \frac{\partial D}{\partial t} &= -\nabla \cdot (\mathbf{v}D) \\ &= -\sum_{j=1}^{3N} \left[\frac{\partial}{\partial q_j} (\dot{q}_j D) + \frac{\partial}{\partial p_j} (\dot{p}_j D) \right] \\ &= -\sum_{j=1}^{3N} \left[\frac{\partial D}{\partial q_j} \dot{q}_j + \frac{\partial D}{\partial p_j} \dot{p}_j \right] - D \sum_{j=1}^{3N} \left[\frac{\partial \dot{q}_j}{\partial q_j} + \frac{\partial \dot{p}_j}{\partial p_j} \right] \\ &\frac{\partial \dot{q}_j}{\partial q_j} + \frac{\partial \dot{p}_j}{\partial p_j} &= \frac{\partial^2 H}{\partial q_j \partial p_j} + \left(-\frac{\partial^2 H}{\partial p_j \partial q_j} \right) = 0 \end{split}$$

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$$\begin{split} \frac{\partial D}{\partial t} &= -\sum_{j=1}^{3N} \left[\frac{\partial D}{\partial q_j} \dot{q}_j + \frac{\partial D}{\partial p_j} \dot{p}_j \right] - D \sum_{j=1}^{3N} \left[\frac{\partial \dot{q}_j}{\partial q_j} + \frac{\partial \dot{p}_j}{\partial p_j} \right] \\ \frac{\partial D}{\partial t} &= -\sum_{j=1}^{3N} \left[\frac{\partial D}{\partial q_j} \dot{q}_j + \frac{\partial D}{\partial p_j} \dot{p}_j \right] \\ \Rightarrow \frac{\partial D}{\partial t} + \sum_{j=1}^{3N} \left[\frac{\partial D}{\partial q_j} \dot{q}_j + \frac{\partial D}{\partial p_j} \dot{p}_j \right] = \frac{dD}{dt} = 0 \end{split}$$

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Importance of Liouville's theorem to statistical mechanical analysis:

In statistical mechanics, we need to evaluate the probability of various configurations of particles. The fact that the density of particles in phase space is constant in time, implies that each point in phase space is equally probable and that the time average of the evolution of a system can be determined by an average of the system over phase space volume.

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Modern usage of Lagrangian and Hamiltonian formalisms

J. Chem. Physics 72 2384-2393 (1980)

Molecular dynamics simulations at constant pressure and/or temperature^{a)}

Hans C. Andersen

Department of Chemistry, Stanford University, Stanford, California 94305 (Received 10 July 1979; accepted 31 October 1979)

In the molecular dynamics simulation method for fluids, the equations of motion for a collection of particle in a fluid volume are solved numerically. The energy, volume, and number of puricles are constant for a particular simulation, and it is assumed that time averages of properties of the simulated fluid are equal to intercenonized entered averages of the same properties. In some situations, it is desirable to perform simulations of a fluid for particular values of temperature and/or pressure or under conditions in which the energy and volumes of the fluid can fluid fluid

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"Molecular dynamics" is a subfield of computational physics focused on analyzing the motions of atoms in fluids and solids with the goal of relating the atomistic and macroscopic properties of materials. Ideally molecular dynamics calculations can numerically realize the statistical mechanics viewpoint.

Imagine that the generalized coordinates $\,q_\sigma(t)$ represent $\,N$ atoms, each with 3 spacial coordinates :

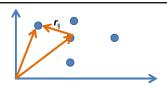
$$L = L(\lbrace q_{\sigma}(t)\rbrace, \lbrace \dot{q}_{\sigma}(t)\rbrace, t) = T - U$$

For simplicity, it is assumed that the potential interaction is a sum of pairwise interactions :

$$U(\mathbf{r}^{N}) = \sum_{i \in j} u(\mathbf{r}_{i,j})$$
 (2.1)

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$$L = L(\{\mathbf{r}_i(t)\}, \{\dot{\mathbf{r}}_i(t)\}) = \sum_i \frac{1}{2} m_i |\dot{\mathbf{r}}_i|^2 - \sum_{i < j} u \left(\mathbf{r}_i - \mathbf{r}_j \right)$$

→ From this Lagrangian, can find the 3N coupled 2nd order differential equations of motion and/or find the corresponding Hamiltonian, representing the system at constant energy, volume, and particle number N (N,V,E ensemble).

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Lagrangian and Hamiltonian forms

$$L = L\left(\left\{\mathbf{r}_{i}(t)\right\}, \left\{\dot{\mathbf{r}}_{i}(t)\right\}\right) = \sum_{i} \frac{1}{2} m_{i} \left|\dot{\mathbf{r}}_{i}\right|^{2} - \sum_{i < j} u \left(\left|\mathbf{r}_{i} - \mathbf{r}_{j}\right|\right)$$

$$\mathbf{p}_{\cdot} = m_{\cdot}\dot{\mathbf{r}}$$

$$H = \sum_{i} \frac{\left|\mathbf{p}_{i}\right|^{2}}{2m_{i}} + \sum_{i < j} u \left(\left|\mathbf{r}_{i} - \mathbf{r}_{j}\right|\right)$$

Canonical equations:

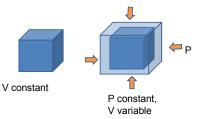
$$\frac{d\mathbf{r}_i}{dt} = \frac{\mathbf{p}_i}{m_i}$$

$$\frac{d\mathbf{p}_i}{dt} = -\sum_{i < j} u' \Big(\Big| \mathbf{r}_i - \mathbf{r}_j \Big| \Big) \frac{\mathbf{r}_i - \mathbf{r}_j}{\Big| \mathbf{r}_i - \mathbf{r}_j \Big|}$$

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H. C. Andersen wanted to adapt the formalism for modeling an (N,V,E) ensemble to one which could model a system at constant pressure (P).



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Andersen's clever transformation:

PV contribution to potential energy

Let
$$\mathbf{\rho}_i = \mathbf{r}_i / Q^{1/3}$$

$$L = L(\{\mathbf{r}_i(t)\}, \{\dot{\mathbf{r}}_i(t)\}) = \sum_{i=1}^{L} m_i |\dot{\mathbf{r}}_i|^2 - \sum_{i=1}^{L} u(|\mathbf{r}_i - \mathbf{r}_j|)$$

$$L = L(\{\mathbf{r}_{i}(t)\}, \{\dot{\mathbf{r}}_{i}(t)\}) = \sum_{i} \frac{1}{2} m_{i} |\dot{\mathbf{r}}_{i}|^{2} - \sum_{i < j} u (|\mathbf{r}_{i} - \mathbf{r}_{j}|)$$

$$L = L(\{\boldsymbol{\rho}_{i}(t)\}, \{\dot{\boldsymbol{\rho}}_{i}(t)\}, Q, \dot{Q}) = Q^{2/3} \sum_{i} \frac{1}{2} m_{i} |\dot{\boldsymbol{\rho}}_{i}|^{2} - \sum_{i < j} u (Q^{1/3} |\boldsymbol{\rho}_{i} - \boldsymbol{\rho}_{j}|) + \frac{1}{2} M \dot{Q}^{2} - \alpha Q$$

kinetic energy of "balloon"

$$\begin{split} L &= L\Big(\{ \mathbf{p}_i(t) \}, \{ \dot{\mathbf{p}}_i(t) \}, Q, \dot{Q} \big) = Q^{2/3} \sum_i \frac{1}{2} m_i |\dot{\mathbf{p}}_i|^2 - \sum_{i < j} u \Big(Q^{1/3} |\dot{\mathbf{p}}_i - \mathbf{p}_j| \Big) + \frac{1}{2} M \dot{Q}^2 - \alpha Q \Big) \\ \pi_i &= \frac{\partial L}{\partial \dot{\mathbf{p}}_i} = m Q^{2/3} \dot{\mathbf{p}}_i \\ \Pi &= \frac{\partial L}{\partial \dot{Q}} = M \dot{Q} \\ H &= \sum_i \frac{|\pi_i|^2}{2 m_i Q^{2/3}} + \sum_{i < j} u \Big(Q^{1/3} |\dot{\mathbf{p}}_i - \mathbf{p}_j| \Big) + \frac{\Pi^2}{2 M} + \alpha Q \\ \frac{d\mathbf{p}_i}{dt} &= \frac{\pi_i}{2 m_i Q^{2/3}} \qquad \frac{dQ}{dt} = \frac{\Pi}{M} \\ \frac{d\pi_i}{dt} &= -Q^{1/3} \sum_{i < j} u^i \Big(Q^{1/3} |\dot{\mathbf{p}}_i - \mathbf{p}_j| \Big) \frac{\mathbf{p}_i - \mathbf{p}_j}{|\mathbf{p}_i - \mathbf{p}_j|} \\ \frac{d\Pi}{dt} &= \frac{2}{3Q} \sum_i \frac{|\pi_i|^2}{2 m_i Q^{2/3}} - \frac{1}{3Q^{2/3}} \sum_{i < j} u^i \Big(Q^{1/3} |\dot{\mathbf{p}}_i - \mathbf{p}_j| \Big) \mathbf{p}_i - \mathbf{p}_j \Big| \partial \mathbf$$

Relationship between system representations

$$\begin{array}{lll} \text{Scaled} & & \text{Original} \\ \mathcal{Q}(t) & = & \mathcal{V}(t) \\ \mathcal{Q}^{1/3} \mathbf{\rho}_i(t) & = & \mathbf{r}_i(t) \\ \mathbf{\pi}_i / \mathcal{Q}^{1/3} & = & \mathbf{p}_i \end{array}$$

Equations of motion in "original" coordinates:

$$\begin{split} &\frac{d\mathbf{r}_{i}}{dt} = \frac{\mathbf{p}_{i}}{m_{i}} + \frac{1}{3}\mathbf{r}_{i} \frac{d \ln V}{dt} \\ &\frac{d\mathbf{p}_{i}}{dt} = -\sum_{j < l} \frac{\mathbf{r}_{i} - \mathbf{r}_{j}}{|\mathbf{r}_{i} - \mathbf{r}_{j}|} u' \Big(|\mathbf{r}_{i} - \mathbf{r}_{j}| \Big) - \frac{1}{3}\mathbf{p}_{i} \frac{d \ln V}{dt} \\ &M \frac{d^{2}V}{dt^{2}} = -\alpha + \frac{1}{V} \left(\frac{2}{3} \sum_{i} \frac{\mathbf{p}_{i} \cdot \mathbf{p}_{i}}{m_{i}} - \frac{1}{3} \sum_{j < l} |\mathbf{r}_{i} - \mathbf{r}_{j}| u' \Big(|\mathbf{r}_{i} - \mathbf{r}_{j}| \Big) \right) \end{split}$$

Physical interpretation:

 $\alpha \Leftrightarrow \text{Imposed (target) pressure}$

$$\frac{1}{V} \left(\frac{2}{3} \sum_{i} \frac{\mathbf{p}_{i} \cdot \mathbf{p}_{i}}{m_{i}} - \frac{1}{3} \sum_{j < i} \left| \mathbf{r}_{i} - \mathbf{r}_{j} \right| u' \left(\mathbf{r}_{i} - \mathbf{r}_{j} \right) \right) \Leftrightarrow \text{Internal pressure of system}$$

Time dependence

$$M\,\frac{d^2V}{dt^2} = -\alpha + \frac{1}{V} \left(\frac{2}{3} \sum_i \frac{\mathbf{p}_i \cdot \mathbf{p}_i}{m_i} - \frac{1}{3} \sum_{j < i} \left| \mathbf{r}_i - \mathbf{r}_j \right| \mu' \left(\left| \mathbf{r}_i - \mathbf{r}_j \right| \right) \right)$$

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Digression on numerical evaluation of differential equations

Example differential equation (one dimension);

$$\frac{d^2x}{dt^2} = f(t)$$

Let
$$t = nh$$
 $(n = 1, 2, 3...)$

Euler's method:

$$x_n \equiv x(nh); \quad f_n \equiv f(nh)$$

$$x_{n+1} = x_n + hv_n + \frac{1}{2}h^2 f_n$$

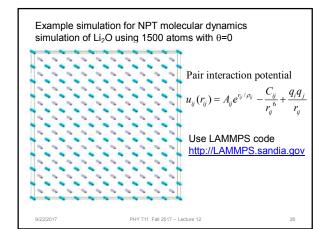
$$v_{n+1} = v_n + hf_n$$

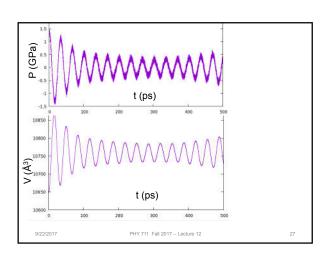
Velocity Verlet algorithm :

$$x_{n+1} = x_n + hv_n + \frac{1}{2}h^2 f_n$$

$$v_{n+1} = v_n + \frac{1}{2}h(f_n + f_{n+1})$$

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Molecular Physics, 1984, Vol. 52, No. 2, 255-268

A molecular dynamics method for simulations in the canonical ensemble†

by SHŪICHI NOSɇ

Division of Chemistry, National Research Council Canada, Ottawa, Ontario, Canada K1A 0R6

(Received 3 October 1983; accepted 28 November 1983)

A molecular dynamics simulation method which can generate configurations belonging to the canonical (T, V, N) ensemble or the constant temperature constant pressure (T, P, N) ensemble, is proposed. The physical system of interest consists of N particles (T, P, N) ensemble, is proposed. The physical system of interest consists of N particles (T, P, N) ensemble, where (T, P, N) ensemble is proposed. The physical system to which an external, macroscopic variable and its conjugate momentum are added. This device allows the total energy of the physical system to fluctuate. The equilibrium distribution of the energy coincides with the

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Nose's Lagrangian:

$$L(\{\mathbf{r}_i\}, s, \{\dot{\mathbf{r}}_i\}, \dot{s}) = \frac{1}{2} \sum_{i} m_i s^2 \dot{\mathbf{r}}^2 + \frac{1}{2} \underbrace{O \dot{s}^2 - \phi(\{\mathbf{r}_i\}) - (f+1)kT_{eq} \ln s}_{\text{velocity scaling}}$$
 velocity scaling

Equations of motion:

$$\frac{d}{dt}(m_i s^2 \, \dot{\mathbf{r}}_i) = -\frac{\partial \phi}{\partial \mathbf{r}_i},$$

$$\ddot{\mathbf{r}}_{i} = -\frac{1}{m_{i}s^{2}} \frac{\partial \phi}{\partial \mathbf{r}_{i}} - \frac{2\dot{s}}{s} \, \dot{\mathbf{r}}_{i}.$$

$$Q\ddot{s} = \sum_{i} m_{i} s \dot{\mathbf{r}}_{i}^{2} - \frac{(f+1)kT_{\text{eq}}}{s}.$$

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Time averaged relationships

$$\left\langle \frac{\sum_{i} m_{i} s^{2} \hat{\mathbf{r}}_{i}^{2}}{s} \right\rangle = (f+1)k T_{\text{eq}} \left\langle \frac{1}{s} \right\rangle$$

Hamiltonian

$$\mathcal{H}_1 = \sum_i \frac{\mathbf{p}_i^2}{2m_i s^2} + \phi(\mathbf{r}) + \frac{p_s^2}{2Q} + (f+1)kT_{eq} \ln s,$$

In statistical mechanics, the thermodynamic functions can be analyzed in terms of a partition function. A canonical partition function for a system with N particles at a temperature T_{eq} can be determined from the phase space integral:

$$Z = \frac{1}{N!} \int d^{3N} r \ d^{3N} p \ e^{-\mathcal{H}(\{\mathbf{r}_i\}, \{\mathbf{p}_i\})/kT_{aq}}$$

Nose' was able to show that his effective Hamiltonian well approximates such a canonical distribution.

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