

**PHY 711 Classical Mechanics and
Mathematical Methods**
10-10:50 AM MWF Olin 103

Plan for Lecture 13:

Finish reading Chapter 6

- 1. Virial theorem**
- 2. Canonical transformations**
- 3. Hamilton-Jacobi formalism**

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Course schedule

(Preliminary schedule -- subject to frequent adjustment.)

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Date	F&W Reading	Topic	Assignment Due
1 Mon, 8/27/2018	Chap. 1	Introduction	#1 9/7/2018
Wed, 8/29/2018	No class		
2 Fri, 8/31/2018	Chap. 1	Scattering theory	#2 9/7/2018
3 Mon, 9/03/2018	Chap. 1	Scattering theory	
4 Wed, 9/05/2018	Chap. 1	Scattering theory	#3 9/10/2018
5 Fri, 9/07/2018	Chap. 2	Non-inertial coordinate systems	#4 9/12/2018
6 Mon, 9/10/2018	Chap. 3	Calculus of Variation	#5 9/12/2018
7 Wed, 9/12/2018	Chap. 3	Calculus of Variation	#6 9/17/2018
Fri, 9/14/2018	No class	University closed due to weather.	
8 Mon, 9/17/2018	Chap. 3	Lagrangian Mechanics	#7 9/19/2018
9 Wed, 9/19/2018	Chap. 3 and 6	Lagrangian Mechanics and constraints	#8 9/24/2018
10 Fri, 9/21/2018	Chap. 3 and 6	Constants of the motion	
11 Mon, 9/24/2018	Chap. 3 and 6	Hamiltonian formalism	#9 9/28/2018
12 Wed, 9/26/2018	Chap. 3 and 6	Liouville theorem	#10 10/3/2018
13 Fri, 9/28/2018	Chap. 3 and 6	Canonical transformations	
14 Mon, 10/1/2018	Chap. 4	Small oscillations about equilibrium	
15 Wed, 10/3/2018	Chap. 4	Normal modes of vibration	
16 Fri, 10/6/2018	Chap. 1-4, 6	Review	

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Virial theorem (Clausius ~ 1860)

$$2\langle T \rangle = - \left\langle \sum_{\sigma} \mathbf{F}_{\sigma} \cdot \mathbf{r}_{\sigma} \right\rangle$$

Proof:

Define: $A \equiv \sum_{\sigma} \mathbf{p}_{\sigma} \cdot \mathbf{r}_{\sigma}$

$$\frac{dA}{dt} = \sum_{\sigma} (\dot{\mathbf{p}}_{\sigma} \cdot \mathbf{r}_{\sigma} + \mathbf{p}_{\sigma} \cdot \dot{\mathbf{r}}_{\sigma}) = \sum_{\sigma} \mathbf{F}_{\sigma} \cdot \mathbf{r}_{\sigma} + 2T$$

Because $\dot{\mathbf{p}}_{\sigma} = \mathbf{F}_{\sigma}$

$$\left\langle \frac{dA}{dt} \right\rangle = \left\langle \sum_{\sigma} \mathbf{F}_{\sigma} \cdot \mathbf{r}_{\sigma} \right\rangle + 2\langle T \rangle$$

$$\left\langle \frac{dA}{dt} \right\rangle = \frac{1}{\tau} \int_0^{\tau} \frac{dA(t)}{dt} dt = \frac{A(\tau) - A(0)}{\tau} \Rightarrow 0$$

Note that this implies that the motion is bounded

$$\Rightarrow \left\langle \sum_{\sigma} \mathbf{F}_{\sigma} \cdot \mathbf{r}_{\sigma} \right\rangle + 2\langle T \rangle = 0$$

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Examples of the Virial Theorem

$$2\langle T \rangle = - \left\langle \sum_{\sigma} \mathbf{F}_{\sigma} \cdot \mathbf{r}_{\sigma} \right\rangle$$

Harmonic oscillator:

$$\mathbf{F} = -kx\hat{\mathbf{x}} \quad T = \frac{1}{2}m\dot{x}^2 \quad \langle m\dot{x}^2 \rangle = \langle kx^2 \rangle$$

Check: for $x(t) = A \sin\left(\sqrt{\frac{k}{m}}t + \alpha\right)$

$$\langle m\dot{x}^2 \rangle = \frac{1}{2}kA^2 = \langle kx^2 \rangle$$

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Examples of the Virial Theorem

$$2\langle T \rangle = - \left\langle \sum_{\sigma} \mathbf{F}_{\sigma} \cdot \mathbf{r}_{\sigma} \right\rangle$$

Circular orbit due to gravitational field
of massive object:

$$\mathbf{F} = -\frac{GMm}{r^2}\hat{\mathbf{r}} \quad T = \frac{1}{2}mr^2\omega^2 \quad \langle mr^2\omega^2 \rangle = \left\langle \frac{GMm}{r} \right\rangle$$

Check: for $r\omega^2 = \frac{GM}{r^2} \Rightarrow \langle mr^2\omega^2 \rangle = \left\langle \frac{GMm}{r} \right\rangle$

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Hamiltonian formalism and the canonical equations of motion:

$$H = H(\{q_{\sigma}(t)\}, \{p_{\sigma}(t)\}, t)$$

Canonical equations of motion

$$\frac{dq_{\sigma}}{dt} = \frac{\partial H}{\partial p_{\sigma}}$$

$$\frac{dp_{\sigma}}{dt} = -\frac{\partial H}{\partial q_{\sigma}}$$

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Notion of "Canonical" transformations

$$q_\sigma = q_\sigma(\{Q_1 \cdots Q_n\}, \{P_1 \cdots P_n\}, t) \quad \text{for each } \sigma$$

$$p_\sigma = p_\sigma(\{Q_1 \cdots Q_n\}, \{P_1 \cdots P_n\}, t) \quad \text{for each } \sigma$$

For some $\tilde{H}$ and F , using Legendre transformations

$$\sum_\sigma p_\sigma \dot{q}_\sigma - H(\{q_\sigma\}, \{p_\sigma\}, t) = \sum_\sigma P_\sigma \dot{Q}_\sigma - \tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) + \frac{d}{dt} F(\{q_\sigma\}, \{Q_\sigma\}, t)$$

Apply Hamilton's principle:

$$\begin{aligned} \delta \int_{t_i}^{t_f} \left[\sum_\sigma P_\sigma \dot{Q}_\sigma - \tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) + \frac{d}{dt} F(\{q_\sigma\}, \{Q_\sigma\}, t) \right] dt &= 0 \\ \delta \int_{t_i}^{t_f} \left[\frac{d}{dt} F(\{q_\sigma\}, \{Q_\sigma\}, t) \right] dt &= \int_{t_i}^{t_f} \left[\frac{d}{dt} \delta F(\{q_\sigma\}, \{Q_\sigma\}, t) \right] dt \\ &= \delta F(t_f) - \delta F(t_i) = 0 \quad \text{and} \quad \dot{Q}_\sigma = \frac{\partial \tilde{H}}{\partial P_\sigma} \quad \dot{P}_\sigma = -\frac{\partial \tilde{H}}{\partial Q_\sigma} \end{aligned}$$

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Some relations between old and new variables:

$$\begin{aligned} \sum_\sigma p_\sigma \dot{q}_\sigma - H(\{q_\sigma\}, \{p_\sigma\}, t) &= \\ \sum_\sigma P_\sigma \dot{Q}_\sigma - \tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) + \frac{d}{dt} F(\{q_\sigma\}, \{Q_\sigma\}, t) &= \\ \frac{d}{dt} F(\{q_\sigma\}, \{Q_\sigma\}, t) &= \sum_\sigma \left(\left(\frac{\partial F}{\partial q_\sigma} \right) \dot{q}_\sigma + \left(\frac{\partial F}{\partial Q_\sigma} \right) \dot{Q}_\sigma \right) + \frac{\partial F}{\partial t} \\ \Rightarrow \sum_\sigma \left(p_\sigma - \left(\frac{\partial F}{\partial q_\sigma} \right) \right) \dot{q}_\sigma - H(\{q_\sigma\}, \{p_\sigma\}, t) &= \\ \sum_\sigma \left(P_\sigma + \left(\frac{\partial F}{\partial Q_\sigma} \right) \right) \dot{Q}_\sigma - \tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) + \frac{\partial F}{\partial t} &= \end{aligned}$$

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$$\begin{aligned} \sum_\sigma \left(p_\sigma - \left(\frac{\partial F}{\partial q_\sigma} \right) \right) \dot{q}_\sigma - H(\{q_\sigma\}, \{p_\sigma\}, t) &= \\ \sum_\sigma \left(P_\sigma + \left(\frac{\partial F}{\partial Q_\sigma} \right) \right) \dot{Q}_\sigma - \tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) + \frac{\partial F}{\partial t} &= \\ \Rightarrow p_\sigma = \left(\frac{\partial F}{\partial q_\sigma} \right) \quad P_\sigma = - \left(\frac{\partial F}{\partial Q_\sigma} \right) &= \\ \Rightarrow \tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) = H(\{q_\sigma\}, \{p_\sigma\}, t) + \frac{\partial F}{\partial t} &= \end{aligned}$$

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Note that it is conceivable that if we were extraordinarily clever, we could find all of the constants of the motion!

$$\dot{Q}_\sigma = \frac{\partial \tilde{H}}{\partial P_\sigma} \quad \dot{P}_\sigma = -\frac{\partial \tilde{H}}{\partial Q_\sigma}$$

$$\text{Suppose: } \dot{Q}_\sigma = \frac{\partial \tilde{H}}{\partial P_\sigma} = 0 \quad \text{and} \quad \dot{P}_\sigma = -\frac{\partial \tilde{H}}{\partial Q_\sigma} = 0$$

$\Rightarrow Q_\sigma, P_\sigma$ are constants of the motion

Possible solution – Hamilton-Jacobi theory:

$$\text{Suppose: } F(\{q_\sigma\}, \{Q_\sigma\}, t) \Rightarrow -\sum_\sigma P_\sigma Q_\sigma + S(\{q_\sigma\}, \{P_\sigma\}, t)$$

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$$\sum_\sigma p_\sigma \dot{q}_\sigma - H(\{q_\sigma\}, \{p_\sigma\}, t) =$$

$$\sum_\sigma P_\sigma \dot{Q}_\sigma - \tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) + \frac{d}{dt} \left(-\sum_\sigma P_\sigma Q_\sigma + S(\{q_\sigma\}, \{P_\sigma\}, t) \right)$$

$$= -\tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) - \sum_\sigma \dot{P}_\sigma Q_\sigma + \sum_\sigma \left(\frac{\partial S}{\partial q_\sigma} \dot{q}_\sigma + \frac{\partial S}{\partial P_\sigma} \dot{P}_\sigma \right) + \frac{\partial S}{\partial t}$$

Solution :

$$p_\sigma = \frac{\partial S}{\partial q_\sigma} \quad Q_\sigma = \frac{\partial S}{\partial P_\sigma}$$

$$\tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t) = H(\{q_\sigma\}, \{p_\sigma\}, t) + \frac{\partial S}{\partial t}$$

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When the dust clears :

Assume $\{Q_\sigma\}, \{P_\sigma\}, \tilde{H}$ are constants; choose $\tilde{H} = 0$

Need to find $S(\{q_\sigma\}, \{P_\sigma\}, t)$

$$p_\sigma = \frac{\partial S}{\partial q_\sigma} \quad Q_\sigma = \frac{\partial S}{\partial P_\sigma}$$

$$\Rightarrow H\left(\{q_\sigma\}, \left\{\frac{\partial S}{\partial q_\sigma}\right\}, t\right) + \frac{\partial S}{\partial t} = 0$$

Note: S is the "action":

$$\sum_\sigma p_\sigma \dot{q}_\sigma - H(\{q_\sigma\}, \{p_\sigma\}, t) =$$

$$\sum_\sigma \overset{0}{P_\sigma \dot{Q}_\sigma} - \overset{0}{\tilde{H}(\{Q_\sigma\}, \{P_\sigma\}, t)} + \frac{d}{dt} \left(-\sum_\sigma \overset{0}{P_\sigma Q_\sigma} + S(\{q_\sigma\}, \{P_\sigma\}, t) \right)$$

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$$\sum_{\sigma} p_{\sigma} \dot{q}_{\sigma} - H(\{q_{\sigma}\}, \{p_{\sigma}\}, t) =$$

$$\sum_{\sigma} p_{\sigma} \dot{Q}_{\sigma} - \tilde{H}(\{Q_{\sigma}\}, \{P_{\sigma}\}, t) + \frac{d}{dt} \left(- \sum_{\sigma} P_{\sigma} Q_{\sigma} + S(\{q_{\sigma}\}, \{p_{\sigma}\}, t) \right)$$

$$\int_{t_i}^{t_f} \left(\sum_{\sigma} p_{\sigma} \dot{q}_{\sigma} - H(\{q_{\sigma}\}, \{p_{\sigma}\}, t) \right) dt = \int_{t_i}^{t_f} \left(\frac{d}{dt} (S(\{q_{\sigma}\}, \{p_{\sigma}\}, t)) \right) dt$$

$$= S(\{q_{\sigma}\}, \{p_{\sigma}\}, t) \Big|_{t_i}^{t_f}$$

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Differential equation for S :

$$H\left(\{q_{\sigma}\}, \left\{\frac{\partial S}{\partial q_{\sigma}}\right\}, t\right) + \frac{\partial S}{\partial t} = 0$$

Example: $H(\{q\}, \{p\}, t) = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 q^2$

Hamilton - Jacobi Eq: $H\left(\{q\}, \left\{\frac{\partial S}{\partial q}\right\}, t\right) + \frac{\partial S}{\partial t} = 0$

$$\frac{1}{2m} \left(\frac{\partial S}{\partial q} \right)^2 + \frac{1}{2} m \omega^2 q^2 + \frac{\partial S}{\partial t} = 0$$

Assume: $S(q, t) \equiv W(q) - Et$ (E constant)

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Continued:

$$\frac{1}{2m} \left(\frac{\partial S}{\partial q} \right)^2 + \frac{1}{2} m \omega^2 q^2 + \frac{\partial S}{\partial t} = 0$$

Assume: $S(q, t) \equiv W(q) - Et$ (E constant)

$$\frac{1}{2m} \left(\frac{dW}{dq} \right)^2 + \frac{1}{2} m \omega^2 q^2 = E$$

$$\frac{dW}{dq} = \sqrt{2mE - (m\omega)^2 q^2}$$

$$W(q) = \int \sqrt{2mE - (m\omega)^2 q^2} dq$$

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Continued:

$$\begin{aligned}
 W(q) &= \int \sqrt{2mE - (m\omega)^2 q^2} dq \\
 &= \frac{1}{2} q \sqrt{2mE - (m\omega)^2 q^2} + \frac{E}{\omega} \sin^{-1} \left(\frac{m\omega q}{\sqrt{2mE}} \right) + C \\
 S(q, E, t) &= \frac{1}{2} q \sqrt{2mE - (m\omega)^2 q^2} + \frac{E}{\omega} \sin^{-1} \left(\frac{m\omega q}{\sqrt{2mE}} \right) - Et \\
 \frac{\partial S}{\partial E} = Q &= \frac{1}{\omega} \sin^{-1} \left(\frac{m\omega q}{\sqrt{2mE}} \right) - t \\
 \Rightarrow q(t) &= \frac{\sqrt{2mE}}{m\omega} \sin(\omega(t + Q))
 \end{aligned}$$

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Another example of Hamilton Jacobi equations

Example: $H(\{q\}, \{p\}, t) = \frac{p^2}{2m} + mgy$

Assume $y(0) = h$; $p(0) = 0$

Hamilton-Jacobi Eq: $H\left(\{q\}, \left\{\frac{\partial S}{\partial q}\right\}, t\right) + \frac{\partial S}{\partial t} = 0$

$$\frac{1}{2m} \left(\frac{\partial S}{\partial y} \right)^2 + mgy + \frac{\partial S}{\partial t} = 0$$

Assume: $S(y, t) \equiv W(y) - Et$ (E constant)

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Example: $H(\{q\}, \{p\}, t) = \frac{p^2}{2m} + mgy$

Assume $y(0) = h$; $p(0) = 0$

$$\frac{1}{2m} \left(\frac{dW}{dy} \right)^2 + mgy = E \equiv mgh$$

$$W(y) = m \int_y^h \sqrt{2g(h - y')} dy' = \frac{2}{3} m \sqrt{2g} (h - y)^{3/2}$$

$$S(y, t) = W(y) - Et = \frac{2}{3} m \sqrt{2g} (h - y)^{3/2} - mght$$

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Check action:

For this case: $y(t) = h - \frac{1}{2}gt^2$

$$S = \int_0^t \left(\frac{1}{2} m \dot{y}^2 - mgy \right) dt' = \frac{1}{3} mg^2 t^3 - mght$$

$$S(y, t) = W(y) - Et = \frac{2}{3} m \sqrt{2g} (h - y)^{3/2} - mght$$

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Recap --

Lagrangian picture

For independent generalized coordinates $q_\sigma(t)$:

$$L = L(\{q_\sigma(t)\}, \{\dot{q}_\sigma(t)\}, t)$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_\sigma} - \frac{\partial L}{\partial q_\sigma} = 0$$

$\Rightarrow$ Second order differential equations for $q_\sigma(t)$

Hamiltonian picture

$$H = H(\{q_\sigma(t)\}, \{p_\sigma(t)\}, t)$$

$$\frac{dq_\sigma}{dt} = \frac{\partial H}{\partial p_\sigma} \quad \frac{dp_\sigma}{dt} = -\frac{\partial H}{\partial q_\sigma}$$

$\Rightarrow$ Coupled first order differential equations for

$$q_\sigma(t) \quad \text{and} \quad p_\sigma(t)$$

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