

**PHY 711 Classical Mechanics and  
Mathematical Methods  
10-10:50 AM MWF online**

**Discussion for Lecture 34: Chap. 13 in F & W**

**Physics of elastic continua –**

- 1. Stress and strain**
- 2. Waves in elastic media**

Modified schedule for holiday 11/25/2020-11/27/2020

## Schedule for weekly one-on-one meetings (EST)

Nick – 11 AM Monday – 11/23

Tim – 9 AM Tuesday – 11/24

Gao – 9 PM Tuesday -- 11/24 (11/25 in China)

Jeanette – 11 AM Friday – 11/20

Derek – 12 PM Friday – 11/20



<b>27</b>	Mon, 10/26/2020	Chap. 9	Mechanics of 3 dimensional fluids	<a href="#">#18</a>	10/30/2020
<b>28</b>	Wed, 10/28/2020	Chap. 9	Mechanics of 3 dimensional fluids		
<b>29</b>	Fri, 10/30/2020	Chap. 9	Linearized hydrodynamics equations	<a href="#">#19</a>	11/02/2020
<b>30</b>	Mon, 11/02/2020	Chap. 9	Linear sound waves	<a href="#">#20</a>	11/04/2020
<b>31</b>	Wed, 11/04/2020	Chap. 9	Linear sound waves	Project topic	11/06/2020
<b>32</b>	Fri, 11/06/2020	Chap. 9	Sound sources and scattering; Non linear effects		
<b>33</b>	Mon, 11/09/2020	Chap. 9	Non linear effects in sound waves and shocks	<a href="#">#21</a>	11/11/2020
<b>34</b>	Wed, 11/11/2020	Chap. 10	Surface waves in fluids	<a href="#">#22</a>	11/16/2020
<b>35</b>	Fri, 11/13/2020	Chap. 10	Surface waves in fluids; soliton solutions		
<b>36</b>	Mon, 11/16/2020	Chap. 11	Heat conduction		
<b>37</b>	Wed, 11/18/2020	Chap. 12	Viscous effects		
<b>38</b>	Fri, 11/20/2020	Chap. 13	Elasticity		
<b>39</b>	Mon, 11/23/2020		Review		
	Wed, 11/25/2020		Thanksgiving Holiday		
	Fri, 11/27/2020		Thanksgiving Holiday		
<b>40</b>	Mon, 11/30/2020		Review		
	Wed, 12/02/2020		Presentations I		
	Fri, 12/04/2020		Presentations II		

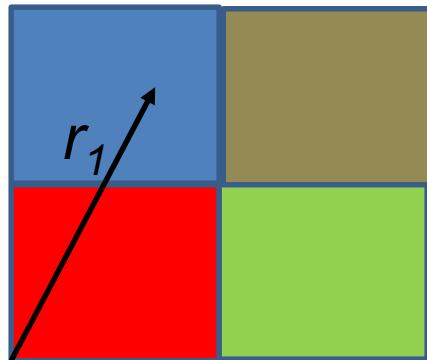
When would you like to sign up for the presentations?

Your questions –

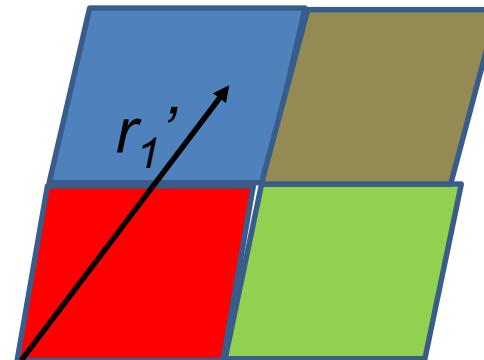
From Gao –

1. What is the difference between elastic stress tensor and the stress tensor in hydrodynamics?

# Brief introduction to elastic continua



reference



deformation

$$\mathbf{r}_1' = \mathbf{r}_1 + \mathbf{u}(\mathbf{r}_1)$$

$$\mathbf{r}_2' = \mathbf{r}_2 + \mathbf{u}(\mathbf{r}_2)$$

$$\mathbf{r}_2' - \mathbf{r}_1' \approx \mathbf{r}_2 - \mathbf{r}_1 + ((\mathbf{r}_2 - \mathbf{r}_1) \cdot \nabla) \mathbf{u}(\mathbf{r}_1) + \dots$$

# Brief introduction to elastic continua -- continued

Deformation components:

$$\frac{\partial u_i}{\partial x_j} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) + \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right)$$

$$\equiv \quad \epsilon_{ij}$$



elastic strain  
tensor

$$+ \quad O_{ij}$$



rotation of material

Here we have in mind that the materials in our analysis are isotropic so that  $\epsilon_{ij} = \epsilon_{ji}$ .

# Brief introduction to elastic continua -- continued

## Deformation components:

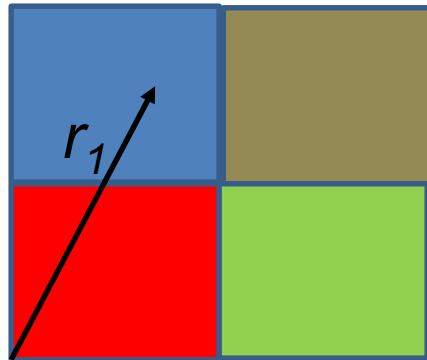
$$\frac{\partial u_i}{\partial x_j} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) + \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right)$$
$$\equiv \epsilon_{ij} \quad + \quad \textcolor{red}{X} O_{ij}$$



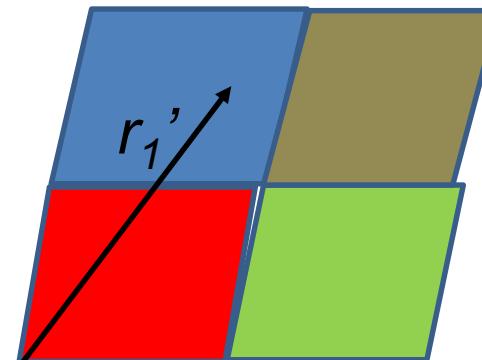
$$V = \mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) \quad V' = \mathbf{a}' \cdot (\mathbf{b}' \times \mathbf{c}') \quad V' = V(1 + \nabla \cdot \mathbf{u}) = V(1 + \text{Tr}(\boldsymbol{\epsilon}))$$

$$\nabla \cdot \mathbf{u} = \epsilon_{11} + \epsilon_{22} + \epsilon_{33} = \text{Tr}(\boldsymbol{\epsilon}) = \frac{dV}{V} = -\frac{d\rho}{\rho}$$

# Brief introduction to elastic continua -- continued



reference



deformation

$$\mathbf{r}_1' = \mathbf{r}_1 + \mathbf{u}(\mathbf{r}_1)$$

$$\mathbf{r}_2' = \mathbf{r}_2 + \mathbf{u}(\mathbf{r}_2)$$

$$\mathbf{r}_2' - \mathbf{r}_1' = \mathbf{r}_2 - \mathbf{r}_1 + ((\mathbf{r}_2 - \mathbf{r}_1) \cdot \nabla) \mathbf{u}(\mathbf{r}_1) + \dots$$

$$x_{2i}' - x_{1i}' \approx x_{2i} - x_{1i} + \sum_{j=1}^3 \epsilon_{ij} (x_{2j} - x_{1j}) \quad \epsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

Effects of strain on a vector:

$$\mathbf{a}' = \mathbf{a} + a (\epsilon_{11} \hat{\mathbf{x}} + \epsilon_{21} \hat{\mathbf{y}} + \epsilon_{31} \hat{\mathbf{z}})$$

$$a' = |\mathbf{a}' \cdot \mathbf{a}'|^{1/2} \approx a (1 + \epsilon_{11})$$

# Deformation



$$\mathbf{a}' = \mathbf{a} + a(\epsilon_{11}\hat{\mathbf{x}} + \epsilon_{21}\hat{\mathbf{y}} + \epsilon_{31}\hat{\mathbf{z}})$$

$$\mathbf{b}' = \mathbf{b} + b(\epsilon_{12}\hat{\mathbf{x}} + \epsilon_{22}\hat{\mathbf{y}} + \epsilon_{32}\hat{\mathbf{z}})$$

$$\text{for } \mathbf{a} \cdot \mathbf{b} = 0 = ab \cos \theta \quad \Rightarrow \theta = \frac{\pi}{2}$$

$$\mathbf{a}' \cdot \mathbf{b}' \approx ab(\epsilon_{21} + \epsilon_{12}) = 2ab\epsilon_{12} = ab \cos \theta'$$

$$\begin{aligned} \cos \theta' &= \cos(\theta + (\theta' - \theta)) = \cos \theta \cos(\theta' - \theta) - \sin \theta \sin(\theta' - \theta) \\ &\approx -\sin \theta \sin(\theta' - \theta) \approx -(\theta' - \theta) \end{aligned}$$

$$\theta' \approx \theta - 2\epsilon_{12} = \frac{\pi}{2} - 2\epsilon_{12}$$

## Elastic stress tensor

$$-\sum_{j=1}^3 T_{ij} dA_j \Rightarrow i^{th} \text{ component of force acting on surface } \hat{\mathbf{n}} dA \equiv d\mathbf{A}$$

Generalization of Hooke's law,  $F_x = -kx$ :

Lame' coefficients :  $T_{ij} = -\lambda \delta_{ij} \nabla \cdot \mathbf{u} - \mu \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$

or :  $T_{ij} = -\lambda \delta_{ij} \text{Tr}(\epsilon) - 2\mu \epsilon_{ij}$

Note: the elastic stress tensor is quite different from the stress tensor that we encountered in the hydrodynamic analysis!

Your question -- What is the difference between elastic stress tensor and the stress tensor in hydrodynamics.

Recall Newton's second law for continuum system with density  $\rho$ , velocity components  $v_k$  and stress tensor  $T_{ij}$  :

$$\frac{\partial(\rho v_k)}{\partial t} = -\sum_{l=1}^3 \frac{\partial T_{kl}}{\partial x_l} + \rho f_k$$

This equation works both for the case of hydrodynamics and for elasticity. The stress tensor  $T_{kl}$  has the units of force/area.

# Ideal stress tensor for hydrodynamics (no viscosity)

$$T_{ij} \equiv \rho v_i v_j + p \delta_{ij}$$

Stress tensor for elastic medium with elastic coefficients  $\lambda$  and  $\mu$

$$T_{ij} = -\lambda \delta_{ij} \nabla \cdot \mathbf{u} - \mu \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

Similarities:

Equation of motion:  $\frac{\partial(\rho v_k)}{\partial t} = -\sum_{l=1}^3 \frac{\partial T_{kl}}{\partial x_l} + \rho f_k$

Differences:

For hydrodynamics,  $T$  represents stress due to motions of nearby fluid

For elasticity,  $T$  represents restoring forces due to displacements from equilibrium

# Elastic stress tensor relationships at equilibrium

$$T_{ij} = -\lambda \delta_{ij} \text{Tr}(\epsilon) - 2\mu \epsilon_{ij}$$

Note that:  $\text{Tr}(T) = -3 \left( \lambda + \frac{2}{3}\mu \right) \text{Tr}(\epsilon)$

$$K \equiv \text{bulk modulus} = -V \left( \frac{\partial p}{\partial V} \right)$$

Inverse Hooke's law:  $\epsilon_{ij} = -\frac{1}{2\mu} \left( T_{ij} - \frac{\lambda}{3\left(\lambda + \frac{2}{3}\mu\right)} \delta_{ij} \text{Tr}(T) \right)$

## Stress tensor -- continued

$$\epsilon_{ij} = -\frac{1}{2\mu} \left( T_{ij} - \frac{\lambda}{3\left(\lambda + \frac{2}{3}\mu\right)} \delta_{ij} \text{Tr}(T) \right)$$

In terms of bulk modulus:  $K = \lambda + \frac{2}{3}\mu$

$$\lambda = K - \frac{2}{3}\mu$$

$$\epsilon_{ij} = -\frac{1}{9K} \delta_{ij} \text{Tr}(T) - \frac{1}{2\mu} \left( T_{ij} - \frac{1}{3} \delta_{ij} \text{Tr}(T) \right)$$

$$\epsilon_{ij} = -\frac{1}{2\mu} \left( T_{ij} - \frac{\lambda}{3\left(\lambda + \frac{2}{3}\mu\right)} \delta_{ij} \text{Tr}(T) \right) = -\frac{1}{9K} \delta_{ij} \text{Tr}(T) - \frac{1}{2\mu} \left( T_{ij} - \frac{1}{3} \delta_{ij} \text{Tr}(T) \right)$$

Example -- hydrostatic pressure:  $T_{ij} = \delta_{ij} dp$

$$\text{Tr}(T) = 3dp$$

$$\epsilon_{ij} = -\frac{dp}{3\left(\lambda + \frac{2}{3}\mu\right)} \delta_{ij} \equiv -\frac{dp}{3K} \delta_{ij}$$

Note that:  $\text{Tr}(\epsilon) = \frac{dV}{V} = -\frac{dp}{K}$

$$\Rightarrow K = -V \frac{\partial p}{\partial V}$$

$$\epsilon_{ij} = -\frac{1}{2\mu} \left( T_{ij} - \frac{\lambda}{3\left(\lambda + \frac{2}{3}\mu\right)} \delta_{ij} \text{Tr}(T) \right) = -\frac{1}{9K} \delta_{ij} \text{Tr}(T) - \frac{1}{2\mu} \left( T_{ij} - \frac{1}{3} \delta_{ij} \text{Tr}(T) \right)$$

Example -- uniaxial pressure:  $T_{ij} = \begin{cases} dp & ij = zz \\ 0 & \text{otherwise} \end{cases}$

$$\epsilon_{zz} = -\frac{1}{E} T_{zz} \quad \text{in terms of Young's modulus}$$

$$E = \frac{9K\mu}{3K + \mu}$$

$$\epsilon_{xx} = \epsilon_{yy} = -\left( \frac{1}{9K} - \frac{1}{6\mu} \right) dp$$

Poisson ratio:  $\sigma = -\frac{\epsilon_{xx}}{\epsilon_{zz}} = -\frac{\epsilon_{yy}}{\epsilon_{zz}} = \frac{1}{2} \frac{3K - 2\mu}{3K + \mu}$

$$\epsilon_{ij} = -\frac{1}{9K} \delta_{ij} Tr(T) - \frac{1}{2\mu} \left( T_{ij} - \frac{1}{3} \delta_{ij} Tr(T) \right)$$

## Shear modulus

$$T_{ij} = \begin{cases} -f & \text{for } T_{xy} \text{ or } T_{yx} \\ 0 & \text{otherwise} \end{cases}$$

$$\epsilon_{xy} = \epsilon_{yx} = \frac{f}{2\mu}$$

Relationships between the elastic moduli:

Poisson's ratio:

$$\sigma = -\frac{\epsilon_{xx}}{\epsilon_{zz}} = \frac{1}{2} \frac{3K - 2\mu}{3K + \mu}$$

Young's modulus:

$$E = \frac{9K\mu}{3K + \mu}$$

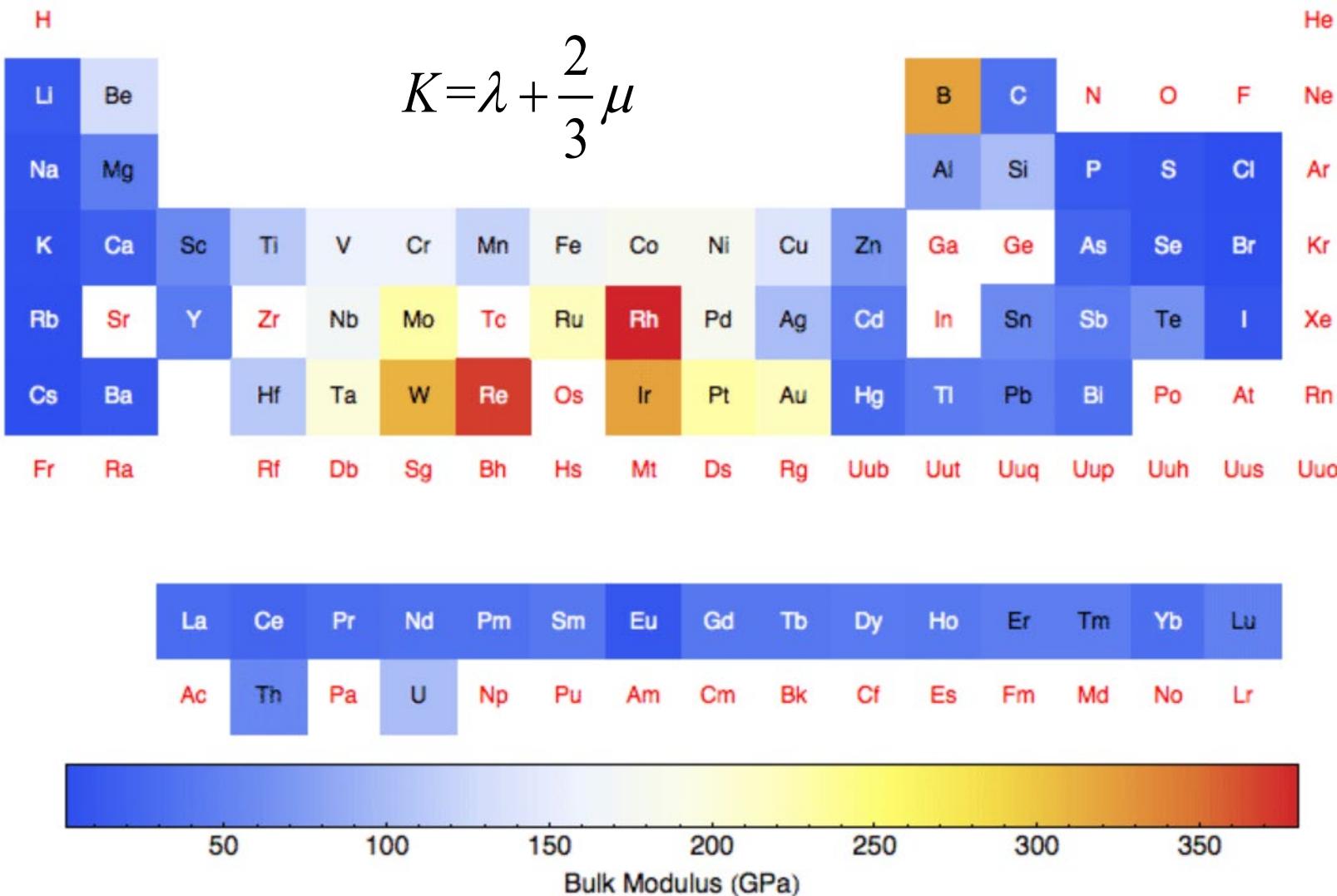
Shear modulus:  $\mu$

Relationships between elastic constants:

$$K = \frac{1}{3} \frac{E}{1 - 2\sigma}$$

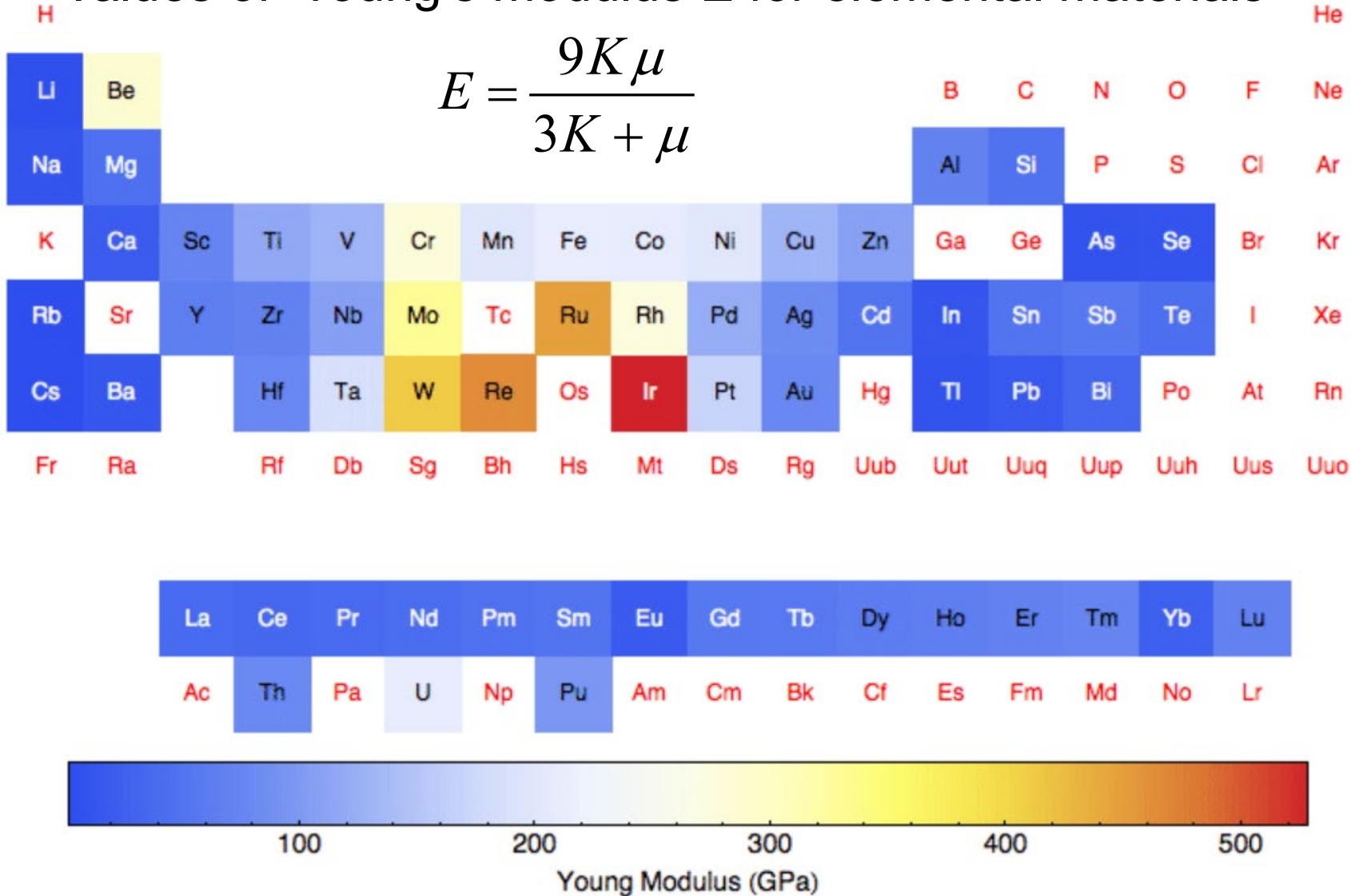
$$\mu = \frac{1}{2} \frac{E}{1 + \sigma}$$

# Values of bulk modulus K for elemental materials --



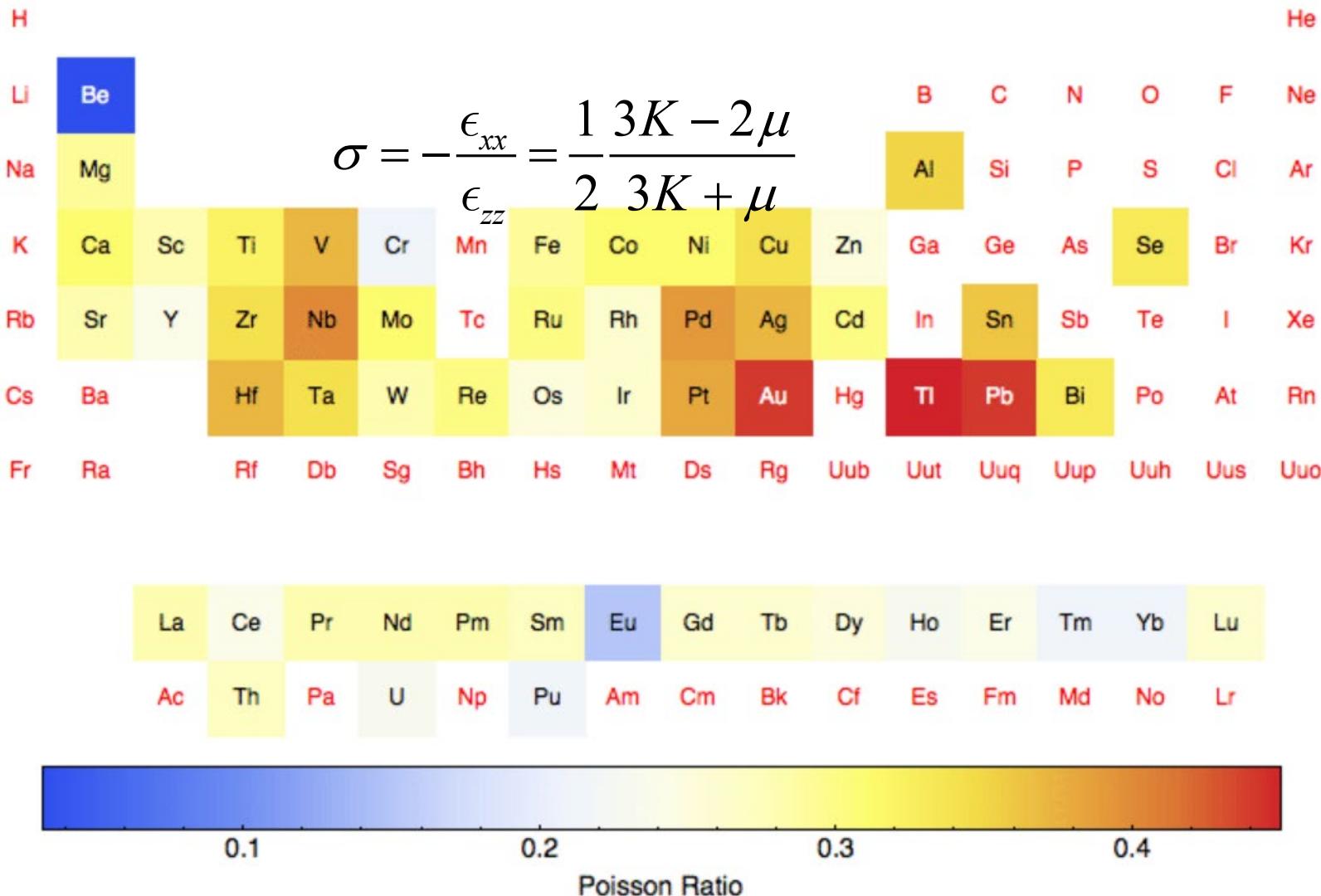
Up to date, curated data provided by [Mathematica's ElementData function](#) from [Wolfram Research, Inc.](#)

# Values of Young's modulus E for elemental materials --



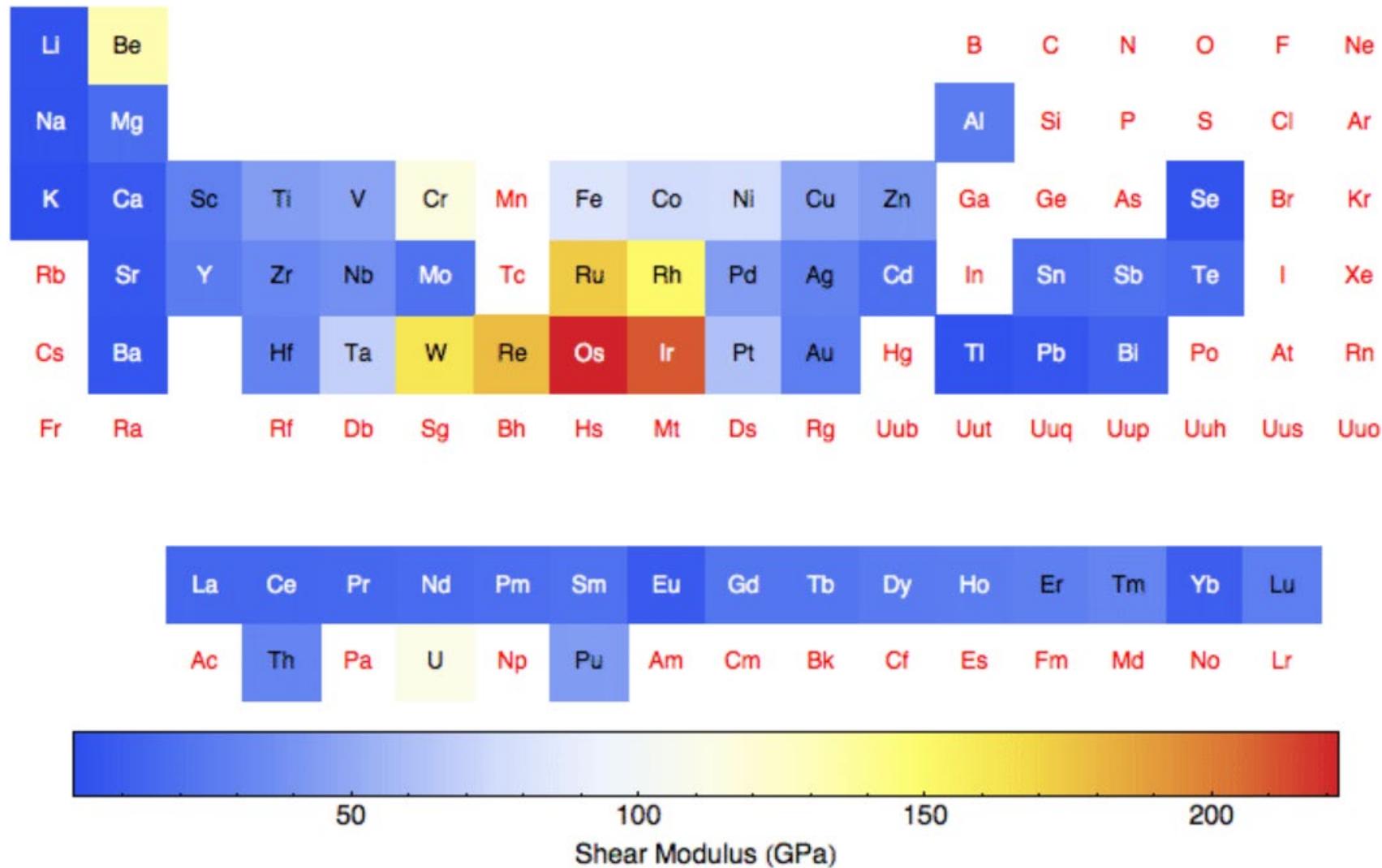
Up to date curated data provided by [Mathematica's ElementData function](#) from Wolfram Research, Inc.

# Values of Poisson ratio $\sigma$ for elemental materials --



Up to date, curated data provided by [Mathematica's ElementData function](#) from Wolfram Research, Inc.

# H Values of shear modulus $\mu$ for elemental materials -- He



Up to date, curated data provided by *Mathematica's ElementData* function from Wolfram Research, Inc.

## Summary -- Elastic stress tensor

$$-\sum_{j=1}^3 T_{ij} dA_j \Rightarrow i^{\text{th}} \text{ component of force acting on surface } \hat{\mathbf{n}} dA \equiv d\mathbf{A}$$

Generalization of Hooke's law,  $F_x = -kx$ :

Lame' coefficients :  $T_{ij} = -\lambda \delta_{ij} \nabla \cdot \mathbf{u} - \mu \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) = -\lambda \delta_{ij} \text{Tr}(\boldsymbol{\epsilon}) - 2\mu \epsilon_{ij}$

Bulk modulus:  $K = \lambda + \frac{2}{3}\mu$

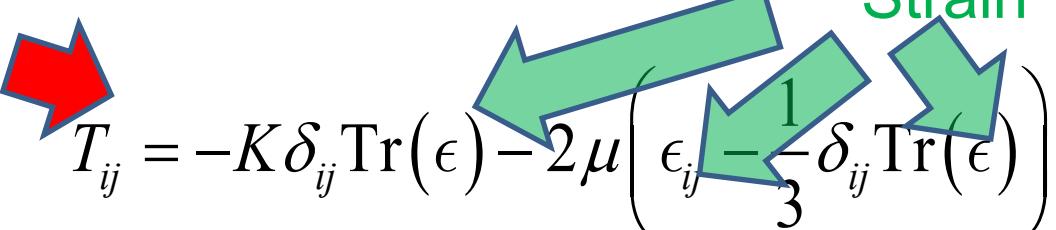
Young's modulus:  $E = \frac{9K\mu}{3K + \mu}$

Poisson ratio:  $\sigma = \frac{1}{2} \frac{3K - 2\mu}{3K + \mu}$

Shear modulus:  $\mu$

material-dependent  
empirical parameters

Hooke's Law:

$$T_{ij} = -K\delta_{ij}\text{Tr}(\epsilon) - 2\mu \left( \epsilon_{ij} - \frac{1}{3}\delta_{ij}\text{Tr}(\epsilon) \right)$$


Inverse Hooke's Law:

$$\epsilon_{ij} = -\frac{1}{9K}\delta_{ij}\text{Tr}(T) - \frac{1}{2\mu} \left( T_{ij} - \frac{1}{3}\delta_{ij}\text{Tr}(T) \right)$$

Elastic force:

$$F_i^{\text{elastic}} = \sum_{j=1}^3 \frac{\partial T_{ij}}{\partial x_j}$$

Elastic work due to distortion  $\delta\mathbf{u}$

$$\delta W^{\text{elastic}} = \int_V d^3x \mathbf{F}^{\text{elastic}} \cdot \delta\mathbf{u}$$

$$= \int_V d^3x \sum_{ij=1}^3 \frac{\partial T_{ij}}{\partial x_j} \delta u_i$$

$$= \sum_{ij=1}^3 \int_A dA_j T_{ij} \delta u_i - \sum_{ij=1}^3 \int_V d^3x T_{ij} \frac{\partial \delta u_i}{\partial x_j}$$

Elastic work due to distortion  $\delta\mathbf{u}$

$$\begin{aligned}\delta W^{\text{elastic}} &= \int_V d^3x \mathbf{F}^{\text{elastic}} \cdot \delta\mathbf{u} \\ &= \sum_{ij=1}^3 \int_A dA_j T_{ij} \delta u_i - \sum_{ij=1}^3 \int_V d^3x T_{ij} \frac{\partial \delta u_i}{\partial x_j} \\ &= \sum_{ij=1}^3 \int_A dA_j T_{ij} \delta u_i - \sum_{ij=1}^3 \int_V d^3x T_{ij} \epsilon_{ij}\end{aligned}$$

↑  
surface contribution      ↑  
bulk contribution

For large samples:  $\delta W^{\text{elastic}} = - \sum_{ij=1}^3 \int_V d^3x T_{ij} \epsilon_{ij}$

Bulk elastic energy:  $\delta W^{\text{elastic}} = -\sum_{ij=1}^3 \int_V d^3x T_{ij} \epsilon_{ij}$

Integrating from 0 to final strain  $\epsilon_{ij}$ :

$$\delta W^{\text{elastic}} = -\frac{1}{2} \sum_{ij=1}^3 T_{ij} \epsilon_{ij}$$

Hooke's Law:  $T_{ij} = -K \delta_{ij} \text{Tr}(\epsilon) - 2\mu \left( \epsilon_{ij} - \frac{1}{3} \delta_{ij} \text{Tr}(\epsilon) \right)$

$$\delta W^{\text{elastic}} = \frac{1}{2} K (\text{Tr } \epsilon)^2 + \mu \sum_{ij=1}^3 \left( \epsilon_{ij} - \frac{\delta_{ij}}{3} \text{Tr } \epsilon \right)^2$$

$$= \frac{1}{2} \lambda (\text{Tr } \epsilon)^2 + \mu \sum_{ij=1}^3 \epsilon_{ij}^2$$

Note that the two relations:

$$\delta W^{\text{elastic}} = \frac{1}{2} K (\text{Tr } \epsilon)^2 + \mu \sum_{ij=1}^3 \left( \epsilon_{ij} - \frac{\delta_{ij}}{3} \text{Tr } \epsilon \right)^2$$

$$T_{ij} = -K \delta_{ij} \text{Tr}(\epsilon) - 2\mu \left( \epsilon_{ij} - \frac{1}{3} \delta_{ij} \text{Tr}(\epsilon) \right)$$

Ensure that:  $\frac{\partial \delta W^{\text{elastic}}}{\partial \epsilon_{ij}} = -T_{ij}$

# Dynamical equations of motion

Recall Newton's second law for continuum system with density  $\rho$ , velocity components  $v_k$  and stress tensor  $T_{ij}$ :

$$\frac{\partial(\rho v_k)}{\partial t} = -\sum_{l=1}^3 \frac{\partial T_{kl}}{\partial x_l} + \rho f_k$$

↗ external force density

For our elastic medium:  $\rho$  does not vary in time

Velocity related to displacement:  $v_k = \frac{\partial u_k}{\partial t}$

Hooke's law:

$$\begin{aligned} T_{kl} &= -K\delta_{kl}\text{Tr}(\epsilon) - 2\mu\left(\epsilon_{kl} - \frac{1}{3}\delta_{kl}\text{Tr}(\epsilon)\right) \\ &= -K\delta_{kl}(\nabla \cdot \mathbf{u}) - 2\mu\left(\frac{1}{2}\left(\frac{\partial u_k}{\partial x_l} + \frac{\partial u_l}{\partial x_k}\right) - \frac{1}{3}\delta_{kl}(\nabla \cdot \mathbf{u})\right) \end{aligned}$$

$$\text{For: } T_{kl} = -K\delta_{kl}(\nabla \cdot \mathbf{u}) - 2\mu \left( \frac{1}{2} \left( \frac{\partial u_k}{\partial x_l} + \frac{\partial u_l}{\partial x_k} \right) - \frac{1}{3} \delta_{kl} (\nabla \cdot \mathbf{u}) \right)$$

$$\begin{aligned} \sum_{l=1}^3 \frac{\partial T_{kl}}{\partial x_l} &= - \left( K - \frac{2}{3}\mu \right) \sum_{l=1}^3 \left( \delta_{kl} \frac{\partial(\nabla \cdot \mathbf{u})}{\partial x_l} \right) - \mu \sum_{l=1}^3 \frac{\partial^2 u_l}{\partial x_k \partial x_l} - \mu \sum_{l=1}^3 \frac{\partial^2 u_k}{\partial^2 x_l} \\ &= - \left( K + \frac{1}{3}\mu \right) \sum_{l=1}^3 \frac{\partial^2 u_l}{\partial x_k \partial x_l} - \mu \sum_{l=1}^3 \frac{\partial^2 u_k}{\partial^2 x_l} \end{aligned}$$

$$\frac{\partial(\rho v_k)}{\partial t} = - \sum_{l=1}^3 \frac{\partial T_{kl}}{\partial x_l} + \rho f_k \quad v_k = \frac{\partial u_k}{\partial t}$$

$$\rho \frac{\partial^2 u_k}{\partial t^2} = \left( K + \frac{1}{3}\mu \right) \sum_{l=1}^3 \frac{\partial^2 u_l}{\partial x_k \partial x_l} + \mu \sum_{l=1}^3 \frac{\partial^2 u_k}{\partial^2 x_l} + \rho f_k$$

$$\text{Vector form: } \rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \left( K + \frac{1}{3}\mu \right) \nabla(\nabla \cdot \mathbf{u}) + \mu \nabla^2 \mathbf{u} + \rho \mathbf{f}$$

# Dynamical equations of elastic continuum

$$\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mu \nabla^2 \mathbf{u} + \left( K + \frac{1}{3} \mu \right) \nabla (\nabla \cdot \mathbf{u}) + \rho \mathbf{f}$$

In the absence of external forces, this reduces to two decoupled wave equations representing longitudinal and transverse modes:

$$\mathbf{u} = \mathbf{u}_l + \mathbf{u}_t$$

$$\text{where } \nabla \times \mathbf{u}_l = 0 \quad \text{and} \quad \nabla \cdot \mathbf{u}_t = 0$$

$$c_l = \left( \frac{K + \frac{4}{3} \mu}{\rho} \right)^{1/2} \quad \text{and} \quad c_t = \left( \frac{\mu}{\rho} \right)^{1/2}$$

# Typical velocities of longitudinal sound waves

Material  $c_l$  (m/s)

Aluminum, shear - longitudinal wave	3100 - 6400
Beryllium	12890
Brass	3475
Brick	4176
Concrete	3200 - 3600
Copper	4600
Cork	366 - 518
Diamond	12000
Glass	3962
Glass, Pyrex	5640
Gold	3240
Granite	5950
Hardwood	3962
Iron	5130
Lead	1960 - 2160
Lucite	2680
Rubber, butyl	1830
Rubber	40 - 150
Silver	3650
Steel	6100
Steel, stainless	5790
Titanium	6070
Wood (hard)	3960
Wood	3300 - 3600

[http://www.engineeringtoolbox.com/sound-speed-solids-d\\_713.html](http://www.engineeringtoolbox.com/sound-speed-solids-d_713.html)

air:  $c_l = 343 \text{ m/s}$

water:  $c_l = 1433 \text{ m/s}$

from:

<https://pangea.stanford.edu/courses/gp262/Notes/5.Elasticity.pdf>

Mineral	Density	Young's Modulus	Bulk Modulus	Shear Modulus	Vp	Vs	Poisson's Ratio
Quartz	2.6500	95.756	36.600	45.000	6.0376	4.1208	0.063953
Calcite	2.7100	84.293	76.800	32.000	6.6395	3.4363	0.31707
Dolomite	2.8700	116.57	94.900	45.000	7.3465	3.9597	0.29527
Clay (kaolinite)	1.5800	3.2034	1.5000	1.4000	1.4597	0.94132	0.14407
Muscovite	2.7900	100.84	61.500	41.100	6.4563	3.8381	0.22673
Feldspar (Albite)	2.6300	69.010	75.600	25.600	6.4594	3.1199	0.34786
Halite	2.1600	37.242	24.800	14.900	4.5474	2.6264	0.24972
Anhydrite	2.9800	74.431	56.100	29.100	5.6432	3.1249	0.27888
Pyrite	4.9300	305.85	147.40	132.50	8.1076	5.1842	0.15417
Siderite	3.9600	134.51	123.70	51.000	6.9576	3.5887	0.31876
gas	0.00065000	0.0000	0.00013000	0.0000	0.44721	0.0000	0.50000
water	1.0000	0.0000	2.2500	0.0000	1.5000	0.0000	0.50000
oil	0.80000	0.0000	1.0200	0.0000	1.1292	0.0000	0.50000

C.1

**densities in g/cm<sup>3</sup>**

**moduli in GPa**

**velocities in km/s**

# Dynamical equations of elastic continuum

$$\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mu \nabla^2 \mathbf{u} + \left( K + \frac{1}{3} \mu \right) \nabla (\nabla \cdot \mathbf{u}) + \rho \mathbf{f}$$

In absense of external force:

$$\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mu \nabla^2 \mathbf{u} + \left( K + \frac{1}{3} \mu \right) \nabla (\nabla \cdot \mathbf{u})$$

Suppose:  $\mathbf{u} = \mathbf{u}_l + \mathbf{u}_t$

where  $\nabla \times \mathbf{u}_l = 0$  and  $\nabla \cdot \mathbf{u}_t = 0$

$$\rho \frac{\partial^2 (\mathbf{u}_l + \mathbf{u}_t)}{\partial t^2} = \mu \nabla^2 (\mathbf{u}_l + \mathbf{u}_t) + \left( K + \frac{1}{3} \mu \right) \nabla (\nabla \cdot \mathbf{u}_l)$$

# Dynamical equations of elastic continuum

Transverse component:

$$\rho \frac{\partial^2 \mathbf{u}_t}{\partial t^2} = \mu \nabla^2 \mathbf{u}_t \quad \frac{\partial^2 \mathbf{u}_t}{\partial t^2} = \frac{\mu}{\rho} \nabla^2 \mathbf{u}_t \equiv c_t^2 \nabla^2 \mathbf{u}_t$$

Transverse wave velocity:

$$c_t = \sqrt{\frac{\mu}{\rho}}$$

Longitudinal component:  $\rho \frac{\partial^2 \mathbf{u}_l}{\partial t^2} = \mu \nabla^2 \mathbf{u}_l + \left( K + \frac{1}{3} \mu \right) \nabla (\nabla \cdot \mathbf{u}_l)$

Note that the longitudinal wave has its displacement along its propagation direction  $x_p$ , so that  $\mathbf{u}_l(x_p) \equiv u_l(x_p) \hat{\mathbf{x}}_p$

$$\Rightarrow \rho \frac{\partial^2 u_l}{\partial t^2} = \mu \frac{\partial^2 u_l}{\partial x_p^2} + \left( K + \frac{1}{3} \mu \right) \frac{\partial^2 u_l}{\partial x_p^2} = \left( K + \frac{4}{3} \mu \right) \frac{\partial^2 u_l}{\partial x_p^2}$$

# Dynamical equations of elastic continuum

Longitudinal component -- continued:

$$\rho \frac{\partial^2 u_l}{\partial t^2} = \left( K + \frac{4}{3} \mu \right) \frac{\partial^2 u_l}{\partial x_p^2}$$

$$\frac{\partial^2 u_l}{\partial t^2} = \left( \frac{K}{\rho} + \frac{4}{3} \frac{\mu}{\rho} \right) \frac{\partial^2 u_l}{\partial x_p^2} \equiv c_l^2 \frac{\partial^2 u_l}{\partial x_p^2}$$

Longitudinal wave velocity:  $c_l = \sqrt{\frac{K}{\rho} + \frac{4}{3} \frac{\mu}{\rho}}$

Transverse component:

$$\rho \frac{\partial^2 \mathbf{u}_t}{\partial t^2} = \mu \nabla^2 \mathbf{u}_t \quad \frac{\partial^2 \mathbf{u}_t}{\partial t^2} = \frac{\mu}{\rho} \nabla^2 \mathbf{u}_t \equiv c_t^2 \nabla^2 \mathbf{u}_t$$

Transverse wave velocity:  $c_t = \sqrt{\frac{\mu}{\rho}}$

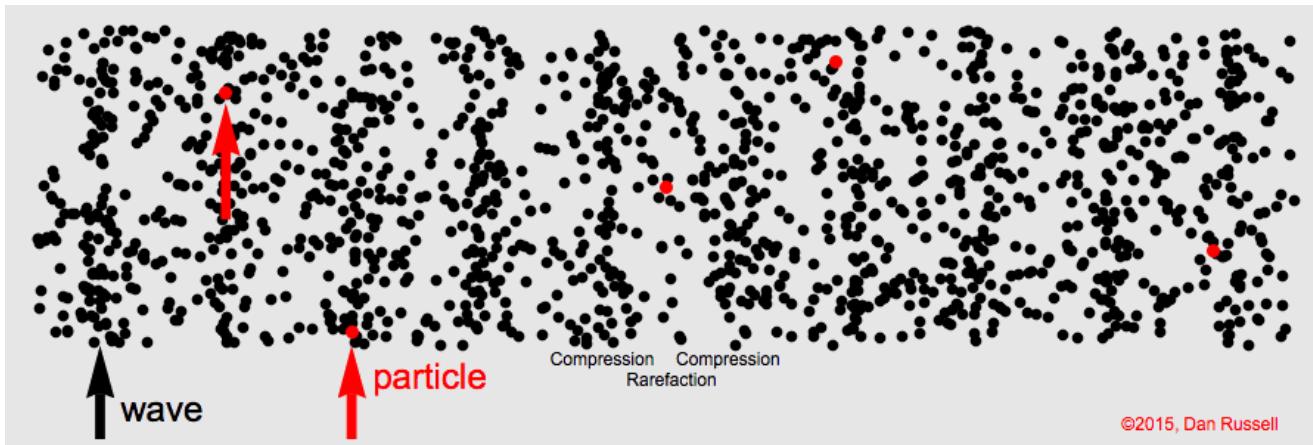
# Some values:

Substance	Density (g/cm <sup>3</sup> )	V <sub>I</sub> (m/s)	V <sub>s</sub> (m/s)	Substance	Density (g/cm <sup>3</sup> )	V <sub>I</sub> (m/s)	V <sub>s</sub> (m/s)
<b>Metals</b>							
Aluminum, rolled	2.7	6420	3040	Tin, rolled	7.3	3320	1670
Beryllium	1.87	12890	8880	Titanium	4.5	6070	3125
Brass (70 Cu, 30 Zn)	8.6	4700	2110	Tungsten, annealed	19.3	5220	2890
Copper, annealed	8.93	4760	2325	Tungsten Carbide	13.8	6655	3980
Copper, rolled	8.93	5010	2270	Zinc, rolled	7.1	4210	2440
Gold, hard-drawn	19.7	3240	1200	Various			
Iron, Armco	7.85	5960	3240	Fused silica	2.2	5968	3764
Lead, annealed	11.4	2160	700	Glass, pyrex	2.32	5640	3280
Lead, rolled	11.4	1960	690	Glass, heavy silicate flint	3.88	3980	2380
Molybdenum	10.1	6250	3350	Lucite	1.18	2680	1100
Monel metal	8.90	5350	2720	Nylon 6-6	1.11	2620	1070
Nickel (unmagnetized)	8.85	5480	2990	Polyethylene	0.90	1950	540
Nickel	8.9	6040	3000	Polystyrene	1.06	2350	1120
Platinum	21.4	3260	1730				
Silver	10.4	3650	1610				
Steel, mild	7.85	5960	3235				
Steel, 347 Stainless	7.9	5790	3100				

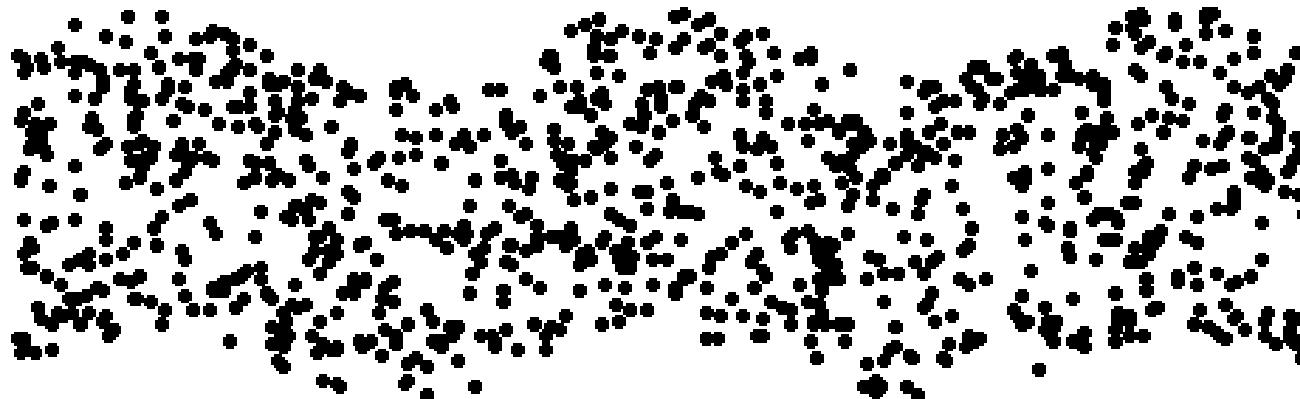
Animations from website:

<https://www.acs.psu.edu/drussell/demos/waves/wavemotion.html>

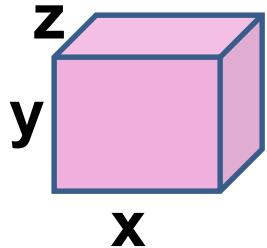
Longitudinal wave (p or “primary”)



Transverse wave (s or “secondary”)

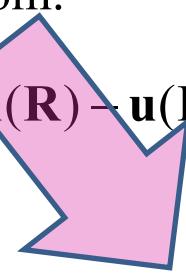


# Elasticity in solids



We imagine that near equilibrium, the solid can be described in terms of a potential function  $\phi(\{\mathbf{R}\})$  where  $\{\mathbf{R}\}$  represents the positions of each atom:

$$E = \sum_{\mathbf{R}} \phi(\{\mathbf{R}\}) + \frac{1}{2} \sum_{\mathbf{R}\mathbf{R}'} (\mathbf{u}(\mathbf{R}) - \mathbf{u}(\mathbf{R}')) \cdot \nabla \phi(\{\mathbf{R}\}) + \frac{1}{4} \sum_{\mathbf{R}\mathbf{R}'} ((\mathbf{u}(\mathbf{R}) - \mathbf{u}(\mathbf{R}')) \cdot \nabla)^2 \phi(\{\mathbf{R}\}) + \dots$$



vanishes at equilibrium

$$\delta W^{\text{elastic}} = \frac{1}{4} \sum_{ij} (\mathbf{u}_i(\mathbf{R}) - \mathbf{u}_i(\mathbf{R}')) \frac{\partial^2 \phi(\{\mathbf{R}\})}{\partial u_i \partial u_j} (\mathbf{u}_j(\mathbf{R}) - \mathbf{u}_j(\mathbf{R}'))$$

$$\delta W^{\text{elastic}} = \frac{1}{4} \sum_{\substack{\mathbf{R}\mathbf{R}' \\ ij}} (u_i(\mathbf{R}) - u_i(\mathbf{R}')) \frac{\partial^2 \phi(\{\mathbf{R}\})}{\partial u_i \partial u_j} (u_j(\mathbf{R}) - u_j(\mathbf{R}'))$$

Note that  $\mathbf{u}(\mathbf{R}') \approx \mathbf{u}(\mathbf{R}') + (\mathbf{R}' - \mathbf{R}) \cdot \nabla \mathbf{u}(\mathbf{R})$

In terms of strain coefficients  $\epsilon_{ij}$ :

$$\delta W^{\text{elastic}} = \frac{1}{2} \sum_{ijkl} \epsilon_{ij} c_{ijkl} \epsilon_{kl}$$

where coefficients  $c_{ijkl}$  are composed of permutations of  $R_i \frac{\partial^2 \phi}{\partial u_j \partial u_k} R_l$

For the most general case  $c_{ijkl}$  have 21 distinct terms, for a cube there are only 3 unique terms.

## Simplified notation:

$xx \rightarrow 1$

$yy \rightarrow 2$

$zz \rightarrow 3$

$yz \rightarrow 4$

$zx \rightarrow 5$

$xy \rightarrow 6$

For cubic crystals, the unique coefficients are:

$$C_{11} = c_{xxxx}$$

$$C_{12} = c_{xxyy}$$

$$C_{44} = c_{yzyz}$$

Some typical values (Ref. Ashcroft and Mermin (1976))

	$C_{11}$ (GPa)	$C_{12}$ (GPa)	$C_{44}$ (GPa)
Na	7.0	6.1	4.5
Al	107	61	28
Fe	234	136	118
Si	166	64	80
NaCl	48.7	12.4	12.6