

## Announcements

1. Plan for next week – no class, take-home exam
2. Extra problem session? Thursday 9 PM?  
- Friday 3 PM?

3. Today's topics

AC circuits

Transformers

4. Convocation Thursday – former Senator, Presidential candidate Bill Bradley will speak

## Important facts to remember in analyzing AC circuits

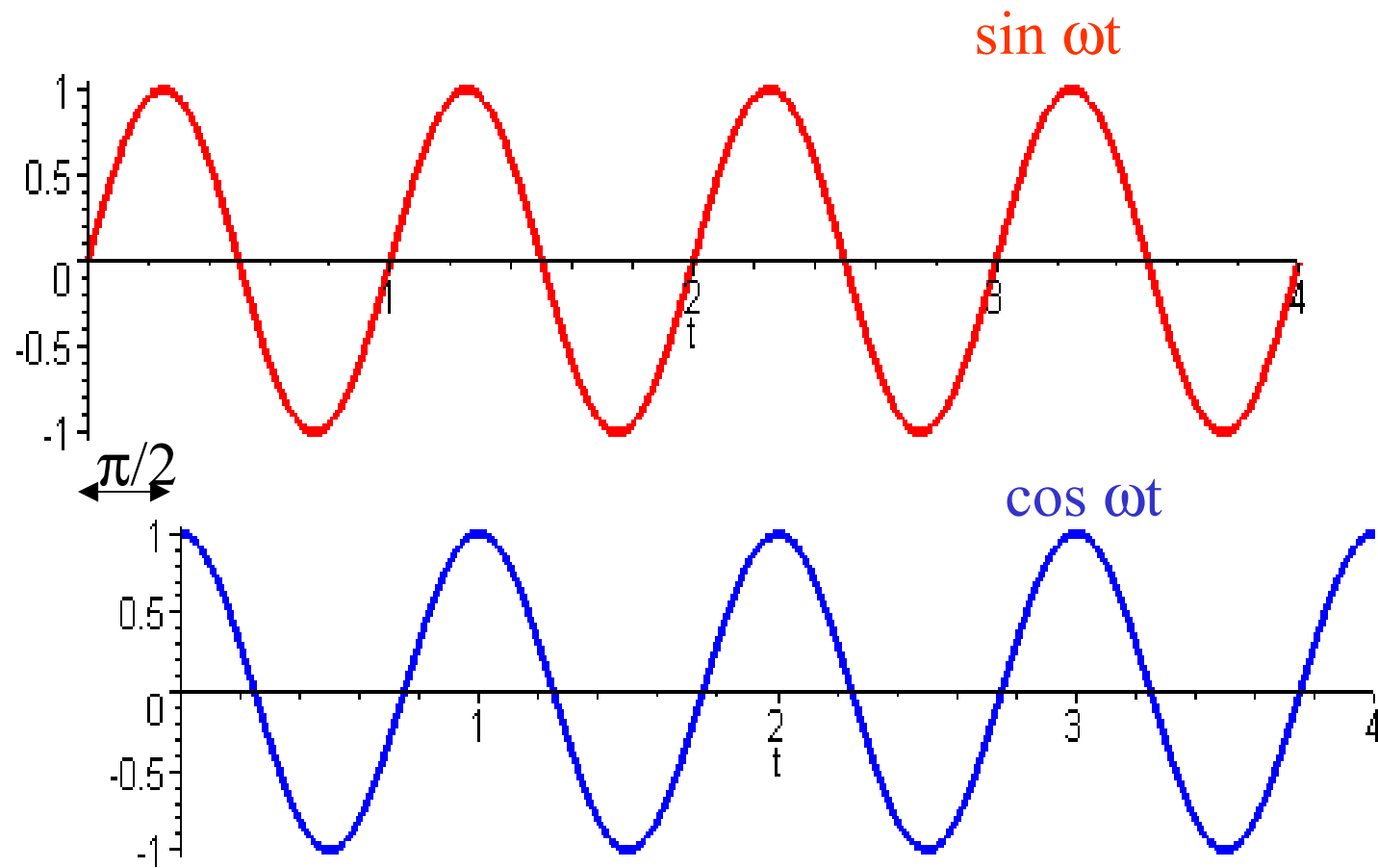
➤  $\Delta V_{\text{max}} = \sqrt{2} \Delta V_{\text{rms}}$

➤ Steady-state currents and voltages will have sinusoidal time dependence such as  $\sin \omega t$  or  $\cos \omega t$  or a linear combination of the two.

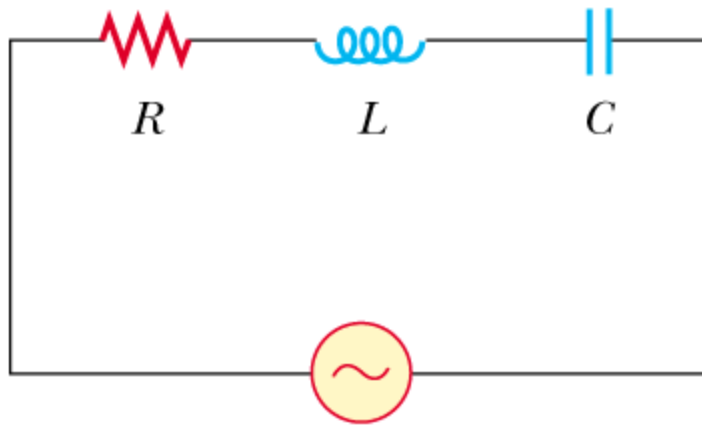
➤ Inductors and capacitors change the “phase” of the current relative to that of the emf.

➤ Solution of the circuit equations for  $I(t) \rightarrow$  equations must be satisfied for all times  $t$ .

DC circuits	AC circuits
<p><math>\mathcal{E} = \text{constant in time}</math></p> <p> <math>I = \begin{cases} \text{constant in time} \\ \text{constant} + I_0 e^{-t/\tau} \\ \text{damped oscillations} \end{cases}</math> </p> <p>Kirchhoff's rules apply</p>	<p><math>\mathcal{E} = \mathcal{E}_{\text{max}} \sin \omega t \text{ or } \mathcal{E}_{\text{max}} \cos \omega t</math></p> <p><math>I = \text{transients} + I_0 \sin (\omega t - \phi)</math></p> <p>Kirchhoff's rules apply</p>



## Example



Kirchhoff's rule:

$$-RI - L \frac{dI}{dt} - \frac{Q}{C} + \Delta V_{\max} \sin \omega t = 0$$

could also be  $\cos \omega t$



Differential equation:

$$-RI - L \frac{dI}{dt} - \frac{Q}{C} + \Delta V_{\max} \sin \omega t = 0$$

Solution form:  $I(t) = I_{\max} \sin(\omega t - \varphi)$

Strategy: substitute form into differential equation and demand the equality must be true at all times.

$$\begin{aligned} -RI_{\max} \sin(\omega t - \varphi) - \omega L I_{\max} \cos(\omega t - \varphi) + \frac{1}{\omega C} I_{\max} \cos(\omega t - \varphi) \\ + \Delta V_{\max} \sin \omega t = 0 \end{aligned}$$

$$\begin{aligned}
 & -RI_{\max} \sin(\omega t - \varphi) - \omega LI_{\max} \cos(\omega t - \varphi) + \frac{1}{\omega C} I_{\max} \cos(\omega t - \varphi) \\
 & + \Delta V_{\max} \sin \omega t = 0
 \end{aligned}$$

Strategy: group terms as factors of  $\sin \omega t$  and  $\cos \omega t$ , noting that:

$$\sin(\omega t - \varphi) = (\sin(\omega t) \cos \varphi - \cos(\omega t) \sin \varphi)$$

$$\cos(\omega t - \varphi) = (\cos(\omega t) \cos \varphi + \sin(\omega t) \sin \varphi)$$

$$\left( -RI_{\max} \cos(\varphi) - \omega LI_{\max} \sin(\varphi) + \frac{1}{\omega C} I_{\max} \sin(\varphi) + \Delta V_{\max} \right) \sin \omega t = 0$$

$$\left( +RI_{\max} \sin(\varphi) - \omega LI_{\max} \cos(\varphi) + \frac{1}{\omega C} I_{\max} \cos(\varphi) \right) \cos \omega t = 0$$

$$\Rightarrow \varphi = \tan^{-1} \left( \frac{\omega L - \frac{1}{\omega C}}{R} \right) \qquad I_{\max} = \frac{\Delta V_{\max}}{\sqrt{R^2 + \left( \omega L - \frac{1}{\omega C} \right)^2}}$$

Summary:

$$-RI - L \frac{dI}{dt} - \frac{q}{C} + \Delta V_{\max} \sin \omega t = 0$$

$$I = I_{\max} \sin(\omega t - \phi)$$

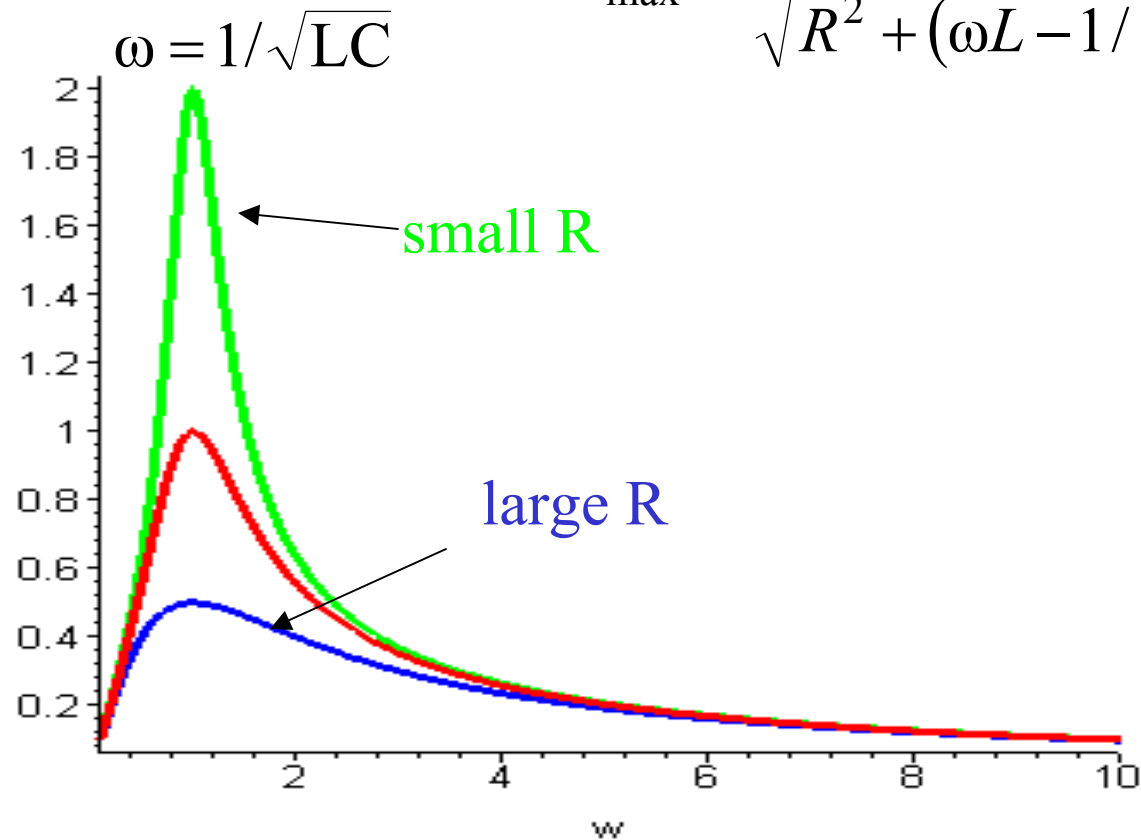
$$I_{\max} = \frac{\Delta V_{\max}}{Z} \quad Z \equiv \sqrt{R^2 + (\omega L - 1/\omega C)^2}$$

$$\tan \phi = \frac{\omega L - 1/\omega C}{R}$$

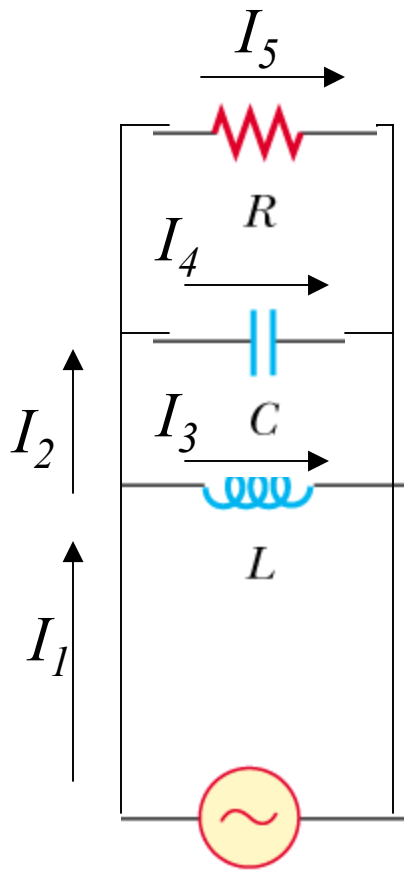


## Behavior of $I_{\max}$

$$I_{\max} = \frac{\Delta V_{\max}}{\sqrt{R^2 + (\omega L - 1/\omega C)^2}}$$



More complicated circuits can be analyzed in a similar way



$$-L \frac{dI_3}{dt} + \Delta V_{\max} \sin \omega t = 0$$

$$-L \frac{dI_3}{dt} + \frac{Q_4}{C} = 0$$

$$\frac{Q_4}{C} - RI_5 = 0$$

$$I_1 = I_2 + I_3$$

$$I_2 = I_4 + I_5$$

PHY 230 -- Electronics

Power delivered by generator in a circuit:

$$\mathcal{P}(t) = I(t) \Delta V(t) = I_{\max} \sin(\omega t - \phi) \Delta V_{\max} \sin(\omega t)$$

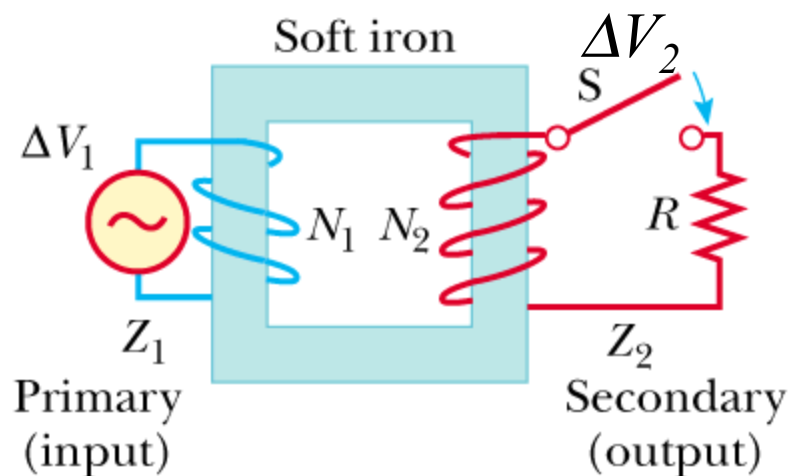
$$\langle \mathcal{P} \rangle_{\text{avg}} = I_{\max} \Delta V_{\max} \frac{1}{2} \cos(\phi)$$

Note that:

$$\cos \phi = \frac{R}{\sqrt{R^2 + (\omega L - 1/\omega C)^2}}$$

$$\rightarrow \langle \mathcal{P} \rangle_{\text{avg}} = \frac{1}{2} R I_{\max}^2 = R I_{\text{rms}}^2$$

## Transformer devices



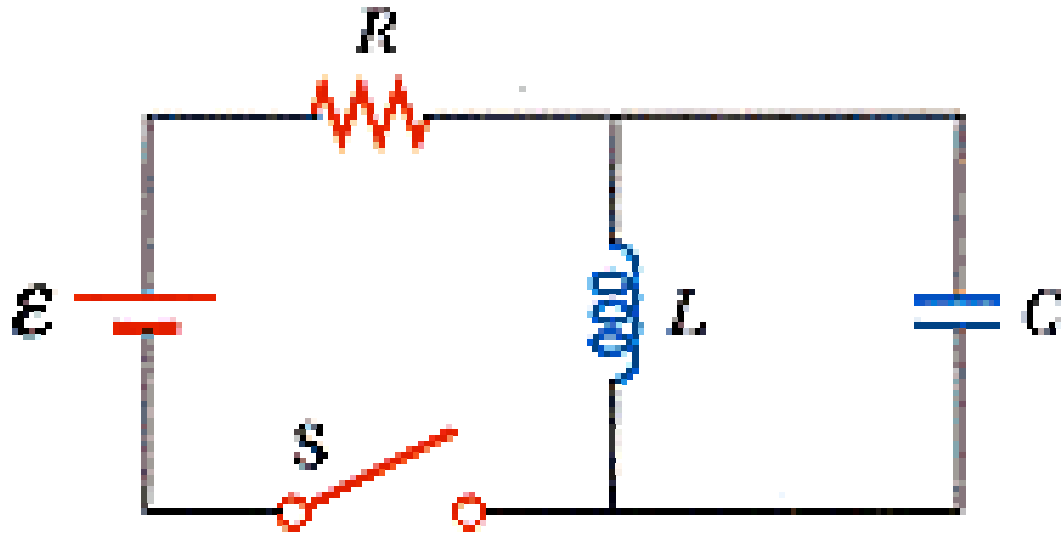
$$\Delta V_1 = -N_1 \frac{d\Phi_B}{dt}$$

$$\Delta V_2 = -N_2 \frac{d\Phi_B}{dt}$$

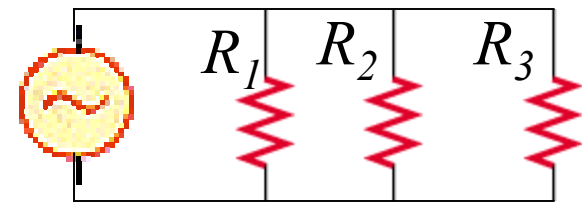
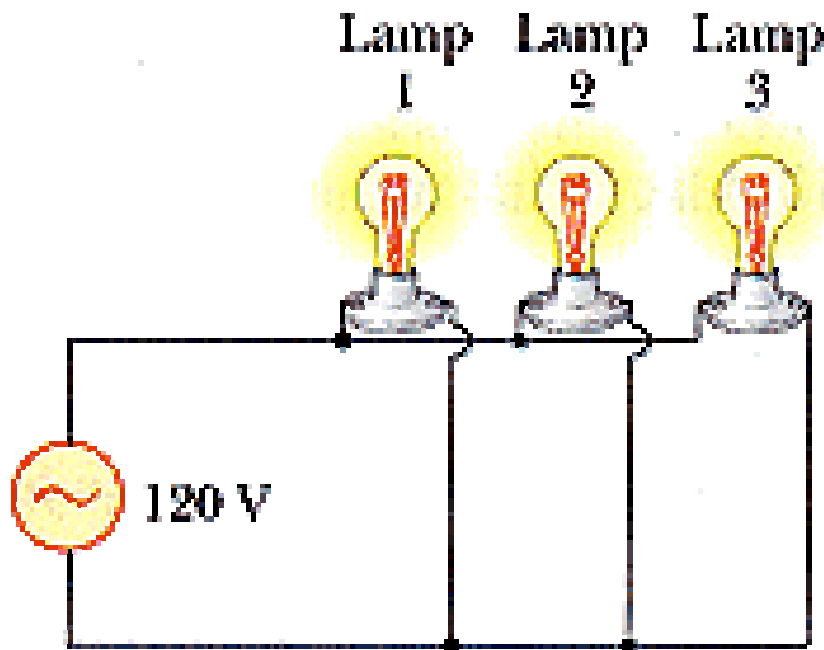
$$-\frac{d\Phi_B}{dt} = \frac{\Delta V_1}{N_1} = \frac{\Delta V_2}{N_2}$$

$$\Delta V_2 = \frac{N_2}{N_1} \Delta V_1 \quad \rightarrow \text{step up or step down the voltage}$$

## Homework problem -- DC circuits



## Homework problem – AC circuits



$$I_{rms} = \frac{\Delta V_{rms}}{Z}$$

$$Z = R_{eq} = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}}$$