## Summary of time dependent theory equations

## Time dependent perturbation expansion

Now suppose that the perturbation depends on time,  $\mathcal{H}(\mathbf{r},t) = \mathcal{H}_0(\mathbf{r}) + \mathcal{H}_1(\mathbf{r},t)$ . The differential equation we must solve is

$$i\hbar \frac{\partial \Phi(\mathbf{r},t)}{\partial t} = \mathcal{H}(\mathbf{r},t)\Phi(\mathbf{r},t).$$
 (1)

We will again assume that we know all of the eigenvalues and eigenfunctions of the reference Hamiltonian

$$\mathcal{H}_0 \Phi_n^0 = E_n^0 \Phi_n^0. \tag{2}$$

In this case, the time dependence of the zero order eigenfunctions takes the form:

$$\Phi_n^0(\mathbf{r},t) = \phi_n^0(\mathbf{r}) e^{-iE_n^0 t/\hbar}.$$
 (3)

The spatial functions  $\phi_n^0(\mathbf{r})$  form a complete orthonormal set of functions. The full solution is expected to take the form

$$\Phi(\mathbf{r},t) = \sum_{n} a_n(t)\phi_n^0(\mathbf{r})e^{-iE_n^0t/\hbar},$$
(4)

where the coefficients  $a_n(t)$  are to be determined from solution of the first order differential equation:

$$\frac{da_n(t)}{dt} = \frac{1}{i\hbar} \sum_m a_m(t) e^{i(E_n^0 - E_m^0)t/\hbar} \langle \phi_n^0 | \mathcal{H}_1 | \phi_m^0 \rangle.$$
 (5)

At this point, we have not made any approximations. In order to proceed, we expand the coefficients as a sum of orders of approximation:

$$a_n(t) = a_n^{(0)}(t) + a_n^{(1)}(t) + a_n^{(2)}(t) \dots$$
 (6)

In general we will assume that the system is initially in a well-defined state of the zero order Hamiltonian:

$$a_m^{(0)}(t) = \delta_{nm}. (7)$$

The equation for the first order coefficient then takes the form:

$$a_n^{(1)}(t) = \frac{1}{i\hbar} \int_{-\infty}^t dt' e^{i(E_n^0 - E_m^0)t'/\hbar} \langle \phi_n^0 | \mathcal{H}_1 | \phi_m^0 \rangle (t').$$
 (8)

Thus the first order coefficients can be determined from a knowledge of the matrix elements of the time-dependent perturbation  $\mathcal{H}_1(\mathbf{r},t)$ . Higher order corrections can be determined from the lower order coefficients.

We will consider the first order coefficients for the case in which there is a harmonic time dependence which is "turned on" at time t = 0:

$$\mathcal{H}_1(\mathbf{r},t) = V(\mathbf{r}) \left( e^{i\omega t} + e^{-i\omega t} \right) \Theta(t), \tag{9}$$

where  $\Theta(t)$  denotes the Heaviside step function. If the system is initially (t < 0) in the zero order state  $\Phi_n^0$ , the effects of the perturbation to first order in V is given by

$$\Phi_n(\mathbf{r}, t) \approx \phi_n^0(\mathbf{r}) e^{-iE_n^0 t/\hbar} + \sum_m a_m^{(1)}(t) \phi_m^0(\mathbf{r}) e^{-iE_m^0 t/\hbar},$$
(10)

where

$$a_m^{(1)}(t) = -\frac{V_{mn}}{i\hbar} \left[ \frac{e^{i(\omega_{mn} + \omega)t} - 1}{\omega_{mn} + \omega} - \frac{e^{i(\omega_{mn} - \omega)t} - 1}{\omega_{mn} - \omega} \right]. \tag{11}$$

In this expression,  $\omega_{mn} \equiv \frac{E_m^0 - E_n^0}{\hbar}$ . For large times t, it can be shown that the squared modulus of the exitation coefficient  $a_m^{(1)}(t)$  determines the transition rate:

$$R_{n\to m} = \frac{|a_m^{(1)}(t)|^2}{t} \approx \frac{2\pi}{\hbar^2} |V_{mn}|^2 \left(\delta(\omega_{mn} + \omega) + \delta(\omega_{mn} - \omega)\right), \tag{12}$$

or

$$R_{n\to m} \approx \frac{2\pi}{\hbar} |V_{mn}|^2 \left( \delta(E_m^0 - E_n^0 + \hbar\omega) + \delta(E_m^0 - E_n^0 - \hbar\omega) \right). \tag{13}$$