

**PHY 712 Electrodynamics  
11-11:50 AM MWF Olin 107**

**Plan for Lecture 25:**

**Start reading Chap. 11**

- A. Equations in cgs (Gaussian) units**
- B. Special theory of relativity**
- C. Lorentz transformation relations**

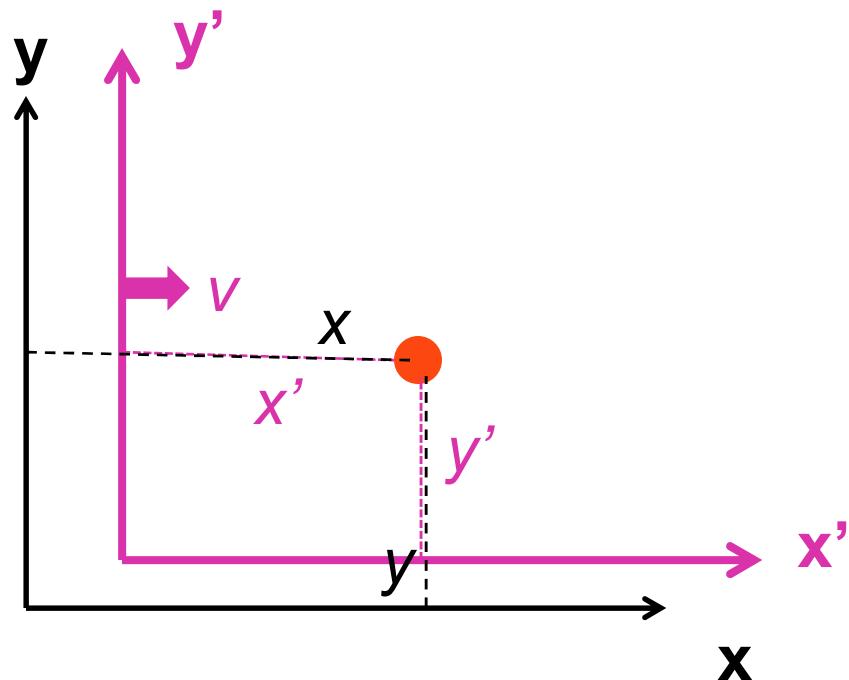
	03-13(Wed)	<i>Spring Break</i>		
	03-15(Fri)	<i>Spring Break</i>		
	03-18(Mon)	<i>APS Meeting</i>	(no class)	Exam
	03-20(Wed)	<i>APS Meeting</i>	(no class)	Exam
	03-22(Fri)	<i>APS Meeting</i>	(no class)	Exam
<b>25</b>	03-25(Mon)	Chap. 11	Lorentz transformations	<a href="#">#17</a>
<b>26</b>	03-27(Wed)	Chap. 11	Transformations between electromagnetic fields	<a href="#">#18</a>
<b>27</b>	03-28(Thur)	Chap. 11	Liénard-Wiechert potentials revisited	
	03-29(Fri)	<i>Good Friday</i>	(no class)	
<b>28</b>	04-01(Mon)	Chap. 14	Radiation by accelerated charges	
<b>29</b>	04-03(Wed)	Chap. 14	Radiation by accelerated charges	
<b>30</b>	04-05(Fri)	Chap. 14	Synchrotron radiation spectrum	
<b>31</b>	04-08(Mon)			
<b>32</b>	04-10(Wed)			
<b>33</b>	04-12(Fri)			
	04-15(Mon)		(no class -- presentation preparation)	
	04-17(Wed)		(no class -- presentation preparation)	
	04-19(Fri)		(no class -- presentation preparation)	
<b>34</b>	04-22(Mon)			
<b>35</b>	04-24(Wed)			
<b>36</b>	04-26(Fri)			
	04-29(Mon)		Student presentations	
	05-01(Wed)		Student presentations	

## Basic equations of electrodynamics

CGS (Gaussian)	SI
$\nabla \cdot \mathbf{D} = 4\pi\rho$	$\nabla \cdot \mathbf{D} = \rho$
$\nabla \cdot \mathbf{B} = 0$	$\nabla \cdot \mathbf{B} = 0$
$\nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t}$	$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$
$\nabla \times \mathbf{H} = \frac{4\pi}{c} \mathbf{J} + \frac{1}{c} \frac{\partial \mathbf{D}}{\partial t}$	$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$
$\mathbf{F} = q(\mathbf{E} + \frac{\mathbf{v}}{c} \times \mathbf{B})$	$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$
$u = \frac{1}{8\pi} (\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H})$	$u = \frac{1}{2} (\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H})$
$\mathbf{S} = \frac{c}{4\pi} (\mathbf{E} \times \mathbf{H})$	$\mathbf{S} = (\mathbf{E} \times \mathbf{H})$

## Notions of special relativity

- The basic laws of physics are the same in all frames of reference (at rest or moving at constant velocity).
- The speed of light in vacuum  $c$  is the same in all frames of reference.

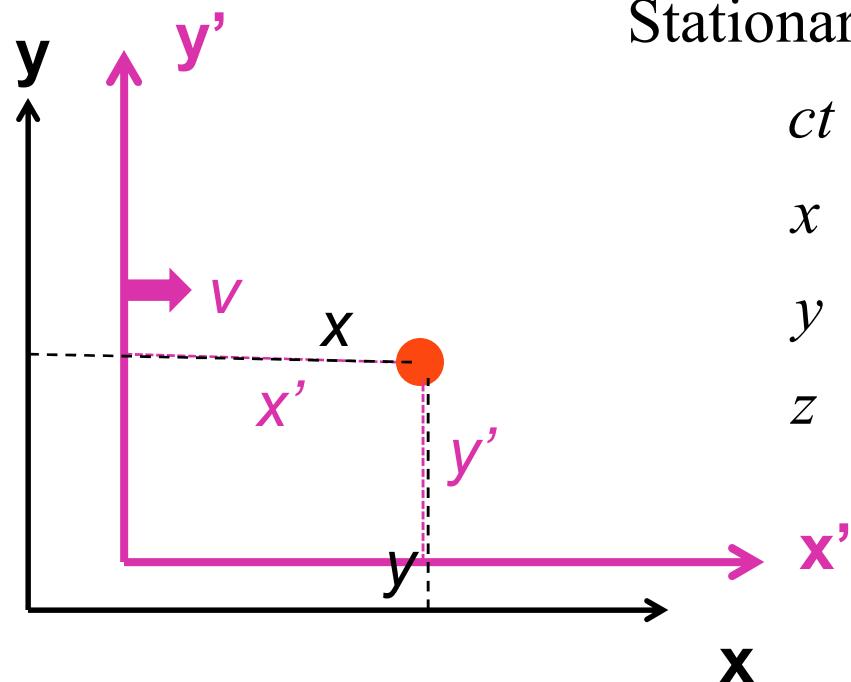


# Lorentz transformations

Convenient notation :

$$\beta \equiv \frac{v}{c}$$

$$\gamma \equiv \frac{1}{\sqrt{1-\beta^2}}$$



Stationary frame

$$ct$$

$$x$$

$$y$$

$$z$$

$$\mathbf{x'}$$

$$\mathbf{x}$$

Moving frame

$$= \gamma(ct' + \beta x')$$

$$= \gamma(x' + \beta ct')$$

$$= y'$$

$$= z'$$

## Lorentz transformations -- continued

For the moving frame with  $\mathbf{v} = v\hat{\mathbf{x}}$ :

$$\mathcal{L} = \begin{pmatrix} \gamma & \gamma\beta & 0 & 0 \\ \gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathcal{L}^{-1} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$
$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \mathcal{L} \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} \quad \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \mathcal{L}^{-1} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

Notice:

$$c^2t^2 - x^2 - y^2 - z^2 = c^2t'^2 - x'^2 - y'^2 - z'^2$$

## Examples of other 4-vectors applicable to the Lorentz transformation:

For the moving frame with  $\mathbf{v} = v\hat{\mathbf{x}}$ :

$$\mathcal{L} = \begin{pmatrix} \gamma & \gamma\beta & 0 & 0 \\ \gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathcal{L}^{-1} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix} = \mathcal{L} \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} \quad \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} = \mathcal{L}^{-1} \begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix} \quad \text{Note: } \omega t - \mathbf{k} \cdot \mathbf{r} = \omega' t' - \mathbf{k}' \cdot \mathbf{r}'$$

$$\begin{pmatrix} E \\ p_x c \\ p_y c \\ p_z c \end{pmatrix} = \mathcal{L} \begin{pmatrix} E' \\ p'_x c \\ p'_y c \\ p'_z c \end{pmatrix} \quad \begin{pmatrix} E' \\ p'_x c \\ p'_y c \\ p'_z c \end{pmatrix} = \mathcal{L}^{-1} \begin{pmatrix} E \\ p_x c \\ p_y c \\ p_z c \end{pmatrix} \quad \text{Note: } E^2 - p^2 c^2 = E'^2 - p'^2 c^2$$

# The Doppler Effect

For the moving frame with  $\mathbf{v} = v\hat{\mathbf{x}}$ :

$$\mathcal{L} = \begin{pmatrix} \gamma & \gamma\beta & 0 & 0 \\ \gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathcal{L}^{-1} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix} = \mathcal{L} \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} \quad \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} = \mathcal{L}^{-1} \begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix}$$

Note:  $\omega t - \mathbf{k} \cdot \mathbf{r} = \omega' t' - \mathbf{k}' \cdot \mathbf{r}'$

$$\omega'/c = \gamma(\omega/c - \beta k_x)$$

$$k'_y = k_y$$

$$k'_x = \gamma(k_x - \beta \omega/c)$$

$$k'_z = k_z$$

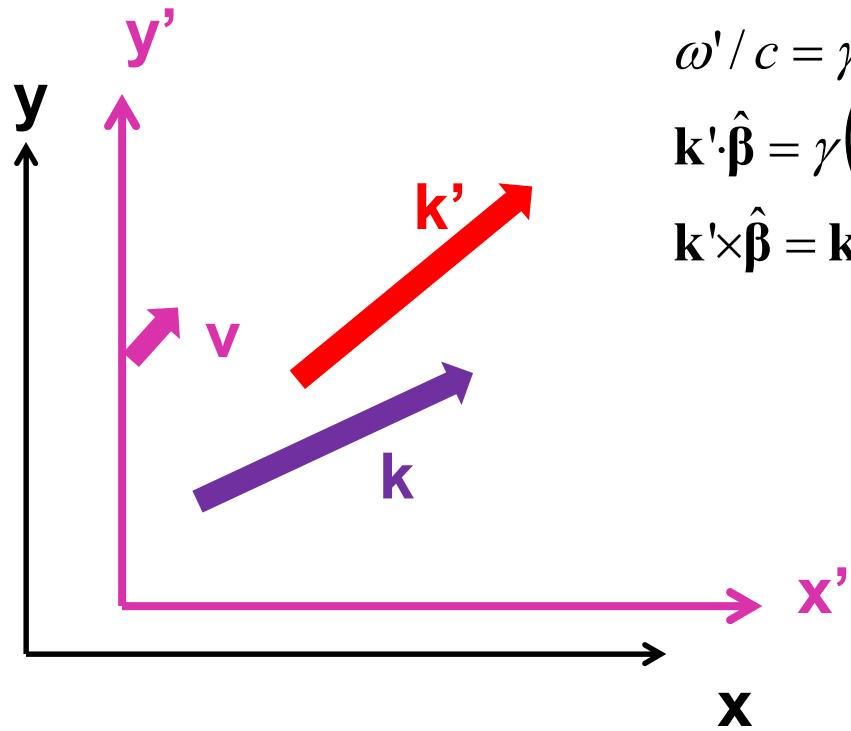
## The Doppler Effect -- continued

$$\omega'/c = \gamma(\omega/c - \beta k_x)$$

$$k'_y = k_y$$

$$k'_x = \gamma(k_x - \beta \omega/c)$$

$$k'_z = k_z$$



More generally:

$$\omega'/c = \gamma(\omega/c - \beta \cdot \mathbf{k}) \equiv \gamma(\omega/c - \beta k \cos \theta)$$

$$\mathbf{k}' \cdot \hat{\beta} = \gamma(\mathbf{k} \cdot \hat{\beta} - \beta \omega/c) \equiv k' \cos \theta' = \gamma(k \cos \theta - \beta \omega/c)$$

$$\mathbf{k}' \times \hat{\beta} = \mathbf{k} \times \hat{\beta}$$

$$\text{For } \theta = 0: \quad (k = \omega/c)$$

$$\omega' = \omega \gamma(1 - \beta) \quad \Rightarrow \omega' = \omega \sqrt{\frac{1 - \beta}{1 + \beta}}$$

$$\text{For } \theta \neq 0: \quad (k = \omega/c)$$

$$\tan \theta' = \frac{\sin \theta}{\gamma(\cos \theta - \beta)}$$

Electromagnetic Doppler Effect (θ=0)

$$\omega' = \omega \sqrt{\frac{1-\beta}{1+\beta}} \quad \beta \equiv \frac{v_{\text{source}} - v_{\text{detector}}}{c}$$

Sound Doppler Effect (θ=0)

$$\omega' = \omega \left( \frac{1 \pm v_{\text{detector}} / c_s}{1 \mp v_{\text{source}} / c_s} \right)$$

## Lorentz transformation of the velocity

Stationary frame	Moving frame
$ct$	$= \gamma(ct' + \beta x')$
$x$	$= \gamma(x' + \beta ct')$
$y$	$= y'$
$z$	$= z'$

For an infinitesimal increment:

Stationary frame	Moving frame
$cdt$	$= \gamma(cdt' + \beta dx')$
$dx$	$= \gamma(dx' + \beta cdt')$
$dy$	$= dy'$
$dz$	$= dz'$

## Lorentz transformation of the velocity -- continued

Stationary frame	Moving frame
$cdt$	$= \gamma(cdt' + \beta dx')$
$dx$	$= \gamma(dx' + \beta cdt')$
$dy$	$= dy'$
$dz$	$= dz'$

Define :  $u_x \equiv \frac{dx}{dt}$   $u_y \equiv \frac{dy}{dt}$   $u_z \equiv \frac{dz}{dt}$

$$u'_x \equiv \frac{dx'}{dt'} \quad u'_y \equiv \frac{dy'}{dt'} \quad u'_z \equiv \frac{dz'}{dt'}$$

$$\frac{dx}{dt} = \frac{\gamma(dx' + \beta c dt')}{\gamma(dt' + \beta dx'/c)} = \frac{u'_x + v}{1 + vu'_x/c^2} = u_x$$

$$\frac{dy}{dt} = \frac{dy'}{\gamma(dt' + \beta dx'/c)} = \frac{u'_{y'}}{\gamma(1 + vu'_{x'}/c^2)} = u_y$$

Example of velocity variation with  $\beta$ :

