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Events
 Colloquium: "Uncovering the Inner Lives of Electrons" - Wednesday, April 17, 2019, at 4:00 PM
 Paul W. Ayers, PhD Department of Chemistry and Chemical Biology, Wake Forest University, Canada
 George P. Williams, Jr. Lecture Hall, (Olin 101) Wednesday, April 17, 2019, at 4:00 PM There will ...

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Units - SI vs Gaussian

Below is a table comparing SI and Gaussian unit systems. The fundamental units for each system are so labeled and are used to define the derived units.

Variable	SI		Gaussian		SI/Gaussian
	Unit	Relation	Unit	Relation	
length	<i>m</i>	fundamental	<i>cm</i>	fundamental	100
mass	<i>kg</i>	fundamental	<i>gm</i>	fundamental	1000
time	<i>s</i>	fundamental	<i>s</i>	fundamental	1
force	<i>N</i>	<i>kg · m²/s²</i>	<i>dync</i>	<i>gm · cm²/s²</i>	10 ⁵
current	<i>A</i>	fundamental	<i>statampere</i>	<i>statcoulomb/s</i>	$\frac{1}{10c}$
charge	<i>C</i>	<i>A · s</i>	<i>statcoulomb</i>	$\sqrt{\text{dync} \cdot \text{cm}^2}$	$\frac{1}{10c}$

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Basic equations of electrodynamics

	CGS (Gaussian)	SI	
$\mathbf{D} = \mathbf{E} + 4\pi\mathbf{P} = \epsilon\mathbf{E}$	$\nabla \cdot \mathbf{D} = 4\pi\rho$	$\nabla \cdot \mathbf{D} = \rho$	$\mathbf{D} = \epsilon_0\mathbf{E} + \mathbf{P} = \epsilon\mathbf{E}$
$\mathbf{H} = \mathbf{B} - 4\pi\mathbf{M} = \frac{1}{\mu}\mathbf{B}$	$\nabla \cdot \mathbf{B} = 0$	$\nabla \cdot \mathbf{B} = 0$	$\mathbf{H} = \frac{1}{\mu_0}\mathbf{B} - \mathbf{M} = \frac{1}{\mu}\mathbf{B}$
	$\nabla \times \mathbf{E} = -\frac{1}{c}\frac{\partial \mathbf{B}}{\partial t}$	$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$	
	$\nabla \times \mathbf{H} = \frac{4\pi}{c}\mathbf{J} + \frac{1}{c}\frac{\partial \mathbf{D}}{\partial t}$	$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$	
	$\mathbf{F} = q(\mathbf{E} + \frac{\mathbf{v}}{c} \times \mathbf{B})$	$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$	
	$u = \frac{1}{8\pi}(\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H})$	$u = \frac{1}{2}(\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H})$	
	$\mathbf{S} = \frac{c}{4\pi}(\mathbf{E} \times \mathbf{H})$	$\mathbf{S} = (\mathbf{E} \times \mathbf{H})$	

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More relationships

<p>CGS (Gaussian)</p> $\mathbf{D} = \mathbf{E} + 4\pi\mathbf{P} = \epsilon\mathbf{E}$ $\mathbf{H} = \mathbf{B} - 4\pi\mathbf{M} = \frac{1}{\mu}\mathbf{B}$ $\mathbf{E} = -\nabla\Phi - \frac{1}{c}\frac{\partial\mathbf{A}}{\partial t}$ $\mathbf{B} = \nabla \times \mathbf{A}$ ϵ μ	\Leftrightarrow \Leftrightarrow	<p>MKS (SI)</p> $\mathbf{D} = \epsilon_0\mathbf{E} + \mathbf{P} = \epsilon\mathbf{E}$ $\mathbf{H} = \frac{1}{\mu_0}\mathbf{B} - \mathbf{M} = \frac{1}{\mu}\mathbf{B}$ $\mathbf{E} = -\nabla\Phi - \frac{\partial\mathbf{A}}{\partial t}$ $\mathbf{B} = \nabla \times \mathbf{A}$ ϵ / ϵ_0 μ / μ_0
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Notions of special relativity

- The basic laws of physics are the same in all frames of reference (at rest or moving at constant velocity).
- The speed of light in vacuum c is the same in all frames of reference.

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Lorentz transformations

Convenient notation :

$$\beta \equiv \frac{v}{c}$$

$$\gamma \equiv \frac{1}{\sqrt{1-\beta^2}}$$

	Stationary frame		Moving frame
	ct	=	$\gamma(ct' + \beta x')$
	x	=	$\gamma(x' + \beta ct')$
	y	=	y'
	z	=	z'

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Lorentz transformations -- continued $\beta \equiv \frac{v}{c}$ $\gamma \equiv \frac{1}{\sqrt{1-\beta^2}}$

For the moving frame with $\mathbf{v} = v\hat{x}$:

$$\mathcal{L} = \begin{pmatrix} \gamma & \gamma\beta & 0 & 0 \\ \gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathcal{L}^{-1} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \mathcal{L} \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} \quad \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \mathcal{L}^{-1} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

Notice:
 $c^2t^2 - x^2 - y^2 - z^2 = c^2t'^2 - x'^2 - y'^2 - z'^2 = c^2\tau^2$ $\tau = \text{proper time}$

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Examples of other 4-vectors
applicable to the Lorentz transformation:

$\beta \equiv \frac{v}{c}$ $\gamma \equiv \frac{1}{\sqrt{1-\beta^2}}$

For the moving frame with $\mathbf{v} = v\hat{x}$:

$$\mathcal{L} = \begin{pmatrix} \gamma & \gamma\beta & 0 & 0 \\ \gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathcal{L}^{-1} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix} = \mathcal{L} \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} \quad \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} = \mathcal{L}^{-1} \begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix}$$

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Four-vectors:

Time and position: $\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \Rightarrow x^\alpha$ Frequency and wavevector: $\begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix} \Rightarrow k^\alpha$

Charge and current: $\begin{pmatrix} c\rho \\ J_x \\ J_y \\ J_z \end{pmatrix} \Rightarrow J^\alpha$

Vector and scalar potentials: $\begin{pmatrix} \Phi \\ A_x \\ A_y \\ A_z \end{pmatrix} \Rightarrow A^\alpha$

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4-vector relationships

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \Leftrightarrow \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix} \Leftrightarrow (A^\alpha, \mathbf{A}): \text{ upper index 4 - vector } A^\alpha \text{ for } (\alpha = 0, 1, 2, 3)$$

Keeping track of signs -- lower index 4 - vector $A_\alpha = (A^0, -\mathbf{A})$

Derivative operators (defined with different sign convention):

$$\partial^\alpha = \left(\frac{\partial}{c\partial t}, -\nabla \right) \quad \partial_\alpha = \left(\frac{\partial}{c\partial t}, \nabla \right)$$

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Algebra rules for Lorentz transformations

For the moving frame with $v = v\hat{x}$:

$$\mathcal{L} = \begin{pmatrix} \gamma & \gamma\beta & 0 & 0 \\ \gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathcal{L}^\dagger = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix} = \mathcal{L} \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} \quad \begin{pmatrix} \omega'/c \\ k'_x \\ k'_y \\ k'_z \end{pmatrix} = \mathcal{L}^\dagger \begin{pmatrix} \omega/c \\ k_x \\ k_y \\ k_z \end{pmatrix}$$

Using indices:

$$\mathcal{L}^\mu \rightarrow \text{row} \quad V \rightarrow \text{column} \quad k^\mu = \mathcal{L}^\mu_\nu k^\nu$$

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Example

Consider a wave in the moving frame:

$$k^\mu = \begin{pmatrix} \omega'/c \\ \omega'/c \\ 0 \\ 0 \end{pmatrix} \text{ in the stationary frame: } k^\mu = \mathcal{L}^\mu_\nu k'^\nu = \begin{pmatrix} \omega/c \\ \omega/c \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \omega = \omega' \sqrt{\frac{1+\beta}{1-\beta}}$$

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Special theory of relativity and Maxwell's equations

Continuity equation: $\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{J} = 0$

Lorentz gauge condition: $\frac{1}{c} \frac{\partial \Phi}{\partial t} + \nabla \cdot \mathbf{A} = 0$

Potential equations: $\frac{1}{c^2} \frac{\partial^2 \Phi}{\partial t^2} - \nabla^2 \Phi = 4\pi\rho$
 $\frac{1}{c^2} \frac{\partial^2 \mathbf{A}}{\partial t^2} - \nabla^2 \mathbf{A} = \frac{4\pi}{c} \mathbf{J}$

Field relations: $\mathbf{E} = -\nabla\Phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t}$
 $\mathbf{B} = \nabla \times \mathbf{A}$

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Lorentz transformations

$$\mathcal{L}(v) = \begin{pmatrix} \gamma_v & \gamma_v \beta_v & 0 & 0 \\ \gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Time and space: $x^\alpha = \mathcal{L}(v)x'^\alpha \equiv \mathcal{L}(v)^\alpha_\beta x'^\beta$

Charge and current: $J^\alpha = \mathcal{L}(v)J'^\alpha \equiv \mathcal{L}(v)^\alpha_\beta J'^\beta$

Vector and scalar potential: $A^\alpha = \mathcal{L}(v)A'^\alpha \equiv \mathcal{L}(v)^\alpha_\beta A'^\beta$

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4-vector relationships

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \Leftrightarrow \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix} \Leftrightarrow (A^0, \mathbf{A}): \text{upper index 4-vector } A^\alpha \text{ for } (\alpha = 0, 1, 2, 3)$$

Keeping track of signs -- lower index 4-vector $A_\alpha = (A^0, -\mathbf{A})$

Derivative operators (defined with different sign convention):

$$\partial^\alpha = \left(\frac{\partial}{c\partial t}, -\nabla \right) \quad \partial_\alpha = \left(\frac{\partial}{c\partial t}, \nabla \right)$$

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Special theory of relativity and Maxwell's equations

Continuity equation : $\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{J} = 0 \quad \rightarrow \quad \partial_\alpha J^\alpha = 0$

Lorentz gauge condition : $\frac{1}{c} \frac{\partial \Phi}{\partial t} + \nabla \cdot \mathbf{A} = 0 \quad \rightarrow \quad \partial_\alpha A^\alpha = 0$

Potential equations : $\left. \begin{aligned} \frac{1}{c^2} \frac{\partial^2 \Phi}{\partial t^2} - \nabla^2 \Phi &= 4\pi\rho \\ \frac{1}{c^2} \frac{\partial^2 \mathbf{A}}{\partial t^2} - \nabla^2 \mathbf{A} &= \frac{4\pi}{c} \mathbf{J} \end{aligned} \right\} \partial_\alpha \partial^\alpha A^\beta = \frac{4\pi}{c} J^\beta$

Field relations : $\mathbf{E} = -\nabla\Phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} \quad \rightarrow \quad ??$
 $\mathbf{B} = \nabla \times \mathbf{A}$

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Electric and Magnetic field relationships

$\mathbf{E} = -\nabla\Phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t}$

$E_x = -\frac{\partial \Phi}{\partial x} - \frac{\partial A_x}{c \partial t} = -(\partial^0 A^1 - \partial^1 A^0)$

$E_y = -\frac{\partial \Phi}{\partial y} - \frac{\partial A_y}{c \partial t} = -(\partial^0 A^2 - \partial^2 A^0)$

$E_z = -\frac{\partial \Phi}{\partial z} - \frac{\partial A_z}{c \partial t} = -(\partial^0 A^3 - \partial^3 A^0)$

$\mathbf{B} = \nabla \times \mathbf{A}$

$B_x = \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} = -(\partial^2 A^3 - \partial^3 A^2)$

$B_y = \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} = -(\partial^3 A^1 - \partial^1 A^3)$

$B_z = \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} = -(\partial^1 A^2 - \partial^2 A^1)$

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Field strength tensor $F^{\alpha\beta} \equiv (\partial^\alpha A^\beta - \partial^\beta A^\alpha)$

$F^{\alpha\beta} \equiv \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix}$

Transformation of field strength tensor

$F'^{\alpha\beta} = \mathcal{L}(\mathbf{v})^\alpha_\gamma F^{\gamma\delta} \mathcal{L}(\mathbf{v})^\delta_\beta$ $\mathcal{L}(\mathbf{v}) = \begin{pmatrix} \gamma_v & \gamma_v \beta_x & 0 & 0 \\ \gamma_v \beta_x & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

$F'^{\alpha\beta} = \begin{pmatrix} 0 & -E'_x & -\gamma_v(E'_y + \beta_x B'_z) & -\gamma_v(E'_z - \beta_x B'_y) \\ E'_x & 0 & -\gamma_v(B'_z + \beta_x E'_y) & \gamma_v(B'_y - \beta_x E'_z) \\ \gamma_v(E'_y + \beta_x B'_z) & \gamma_v(B'_z + \beta_x E'_y) & 0 & -B'_x \\ \gamma_v(E'_z - \beta_x B'_y) & -\gamma_v(B'_y - \beta_x E'_z) & B'_x & 0 \end{pmatrix}$

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Inverse transformation of field strength tensor

$$F'^{\alpha\beta} = \mathcal{L}(\mathbf{v})^{-1\alpha}_{\gamma} F'^{\gamma\delta} \mathcal{L}(\mathbf{v})^{-1\beta}_{\delta}$$

$$\mathcal{L}(\mathbf{v})^{-1} = \begin{pmatrix} \gamma_v & -\gamma_v \beta_v & 0 & 0 \\ -\gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$F'^{\alpha\beta} = \begin{pmatrix} 0 & -E_x & -\gamma_v(E_y - \beta_v B_z) & -\gamma_v(E_z + \beta_v B_y) \\ E_x & 0 & -\gamma_v(B_z - \beta_v E_y) & \gamma_v(B_y + \beta_v E_z) \\ \gamma_v(E_y - \beta_v B_z) & \gamma_v(B_z - \beta_v E_y) & 0 & -B_x \\ \gamma_v(E_z + \beta_v B_y) & -\gamma_v(B_y + \beta_v E_z) & B_x & 0 \end{pmatrix}$$

Summary of results:

$$E'_x = E_x \qquad B'_x = B_x$$

$$E'_y = \gamma_v(E_y - \beta_v B_z) \qquad B'_y = \gamma_v(B_y + \beta_v E_z)$$

$$E'_z = \gamma_v(E_z + \beta_v B_y) \qquad B'_z = \gamma_v(B_z - \beta_v E_y)$$

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Comparison of the two transformations

$$F'^{\alpha\beta} = \mathcal{L}(\mathbf{v})^{\alpha}_{\gamma} F'^{\gamma\delta} \mathcal{L}(\mathbf{v})^{\beta}_{\delta}$$

$$\mathcal{L}(\mathbf{v}) = \begin{pmatrix} \gamma_v & \gamma_v \beta_v & 0 & 0 \\ \gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$F'^{\alpha\beta} = \begin{pmatrix} 0 & -E'_x & -\gamma_v(E'_y + \beta_v B'_z) & -\gamma_v(E'_z - \beta_v B'_y) \\ E'_x & 0 & -\gamma_v(B'_z + \beta_v E'_y) & \gamma_v(B'_y - \beta_v E'_z) \\ \gamma_v(E'_y + \beta_v B'_z) & \gamma_v(B'_z + \beta_v E'_y) & 0 & -B'_x \\ \gamma_v(E'_z - \beta_v B'_y) & -\gamma_v(B'_y - \beta_v E'_z) & B'_x & 0 \end{pmatrix}$$

$$F'^{\alpha\beta} = \mathcal{L}(\mathbf{v})^{-1\alpha}_{\gamma} F'^{\gamma\delta} \mathcal{L}(\mathbf{v})^{-1\beta}_{\delta}$$

$$\mathcal{L}(\mathbf{v})^{-1} = \begin{pmatrix} \gamma_v & -\gamma_v \beta_v & 0 & 0 \\ -\gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$F'^{\alpha\beta} = \begin{pmatrix} 0 & -E_x & -\gamma_v(E_y - \beta_v B_z) & -\gamma_v(E_z + \beta_v B_y) \\ E_x & 0 & -\gamma_v(B_z - \beta_v E_y) & \gamma_v(B_y + \beta_v E_z) \\ \gamma_v(E_y - \beta_v B_z) & \gamma_v(B_z - \beta_v E_y) & 0 & -B_x \\ \gamma_v(E_z + \beta_v B_y) & -\gamma_v(B_y + \beta_v E_z) & B_x & 0 \end{pmatrix}$$

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