



PHY 712 Electrodynamics

11-11:50 AM MWF Olin 103

Notes for Lecture 25:

**Continue reading Chap. 11 –
Theory of Special Relativity**

- A. Lorentz transformation relations**
- B. Electromagnetic field transformations**
- C. Connection to Liénard-Wiechert potentials
for constant velocity sources**



21	Fri: 03/25/2022	Chap. 9	Radiation from localized oscillating sources	#18	03/30/2022
22	Mon: 03/28/2022	Chap. 9	Radiation from oscillating sources		
23	Wed: 03/30/2022	Chap. 9 & 10	Radiation and scattering	#19	04/01/2022
24	Fri: 04/01/2022	Chap. 11	Special Theory of Relativity	#20	04/04/2022
25	Mon: 04/04/2022	Chap. 11	Special Theory of Relativity	#21	04/06/2022
26	Wed: 04/06/2022	Chap. 11	Special Theory of Relativity		
27	Fri: 04/08/2022	Chap. 11	Special Theory of Relativity		

PHY 712 -- Assignment #21

April 4, 2022

Continue reading Chapter 11 in **Jackson** .

1. Derive the relationships between the component of the electric and magnetic field components $E_1, E_2, E_3, B_1, B_2,$ and B_3 as measured in the stationary frame of reference and the components $E'_1, E'_2, E'_3, B'_1, B'_2,$ and B'_3 measured in the moving frame of reference. Note that the reverse relationships are given in Eq. 11.148.

Comment on HW #18 --

PHY 712 -- Assignment #18

March 21, 2022

Start reading Chapter 9 in **Jackson** .

1. Problem 9.10 in **Jackson** lists the harmonic frequency dependent charge and current densities of a radiating H atom. Instead of answering **Jackson's** questions, calculate the exact scalar $\Phi(r)$ and vector potential $\mathbf{A}(r)$ fields for $r \gg a_0$ and compare your results with the scalar and vector potential fields calculated within the dipole approximation.

$$\rho(\mathbf{r}, t) = \frac{2e}{\sqrt{24\pi}a_0^4} Y_{10}(\hat{\mathbf{r}}) r e^{-3r/(2a_0) - i\omega_0 t}$$

$$\mathbf{J}(\mathbf{r}, t) = -i \frac{e^2}{4\pi\epsilon_0 \hbar} \left(\frac{\hat{\mathbf{r}}}{2} + \frac{a_0}{z} \hat{\mathbf{z}} \right) \rho(\mathbf{r}, t)$$

$$\omega_0 = \frac{3}{4} \frac{e^2}{8\pi\epsilon_0 \hbar a_0}$$

Given sources --

$$\rho(\mathbf{r}, t) = \frac{2e}{\sqrt{24\pi}a_0^4} Y_{10}(\hat{\mathbf{r}}) r e^{-3r/(2a_0) - i\omega_0 t}$$

$$\mathbf{J}(\mathbf{r}, t) = -i \frac{e^2}{4\pi\epsilon_0 \hbar} \left(\frac{\hat{\mathbf{r}}}{2} + \frac{a_0}{z} \hat{\mathbf{z}} \right) \rho(\mathbf{r}, t)$$

$$\omega_0 = \frac{3}{4} \frac{e^2}{8\pi\epsilon_0 \hbar a_0}$$

In order to evaluate the scalar or vector potential, you need to integrate over the sources. For the current density, we need to be careful.

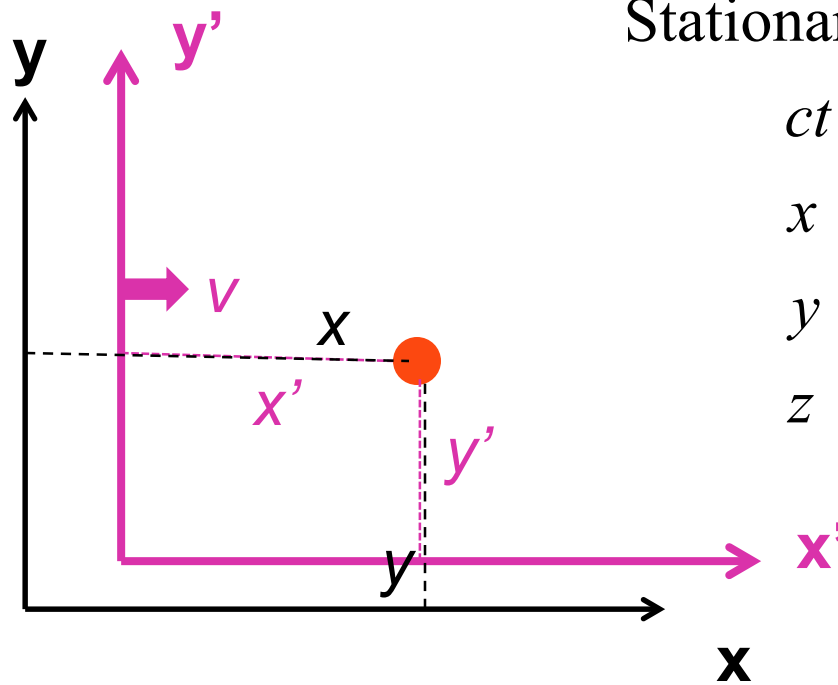
$$\hat{\mathbf{r}} = \sin \theta \cos \varphi \hat{\mathbf{x}} + \sin \theta \sin \varphi \hat{\mathbf{y}} + \cos \theta \hat{\mathbf{z}}$$

Lorentz transformations

Convenient notation :

$$\beta_v \equiv \frac{v}{c}$$

$$\gamma_v \equiv \frac{1}{\sqrt{1 - \beta_v^2}}$$



Stationary frame

Moving frame

$$ct = \gamma(ct' + \beta x')$$

$$x = \gamma(x' + \beta ct')$$

$$y = y'$$

$$z = z'$$

Lorentz transformations -- continued

For the moving frame with $\mathbf{v} = v\hat{\mathbf{x}}$:

$$\mathcal{L}_v = \begin{pmatrix} \gamma_v & \gamma_v \beta_v & 0 & 0 \\ \gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathcal{L}_v^{-1} = \begin{pmatrix} \gamma_v & -\gamma_v \beta_v & 0 & 0 \\ -\gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \mathcal{L}_v \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} \quad \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \mathcal{L}_v^{-1} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

Notice:

$$c^2 t^2 - x^2 - y^2 - z^2 = c^2 t'^2 - x'^2 - y'^2 - z'^2$$

Velocity relationships

Consider: $u_x = \frac{u'_x + v}{1 + vu'_x / c^2}$ $u_y = \frac{u'_y}{\gamma_v (1 + vu'_x / c^2)}$ $u_z = \frac{u'_z}{\gamma_v (1 + vu'_x / c^2)}$.

Note that $\gamma_u \equiv \frac{1}{\sqrt{1 - (u/c)^2}} = \frac{1 + vu'_x / c^2}{\sqrt{1 - (u'/c)^2} \sqrt{1 - (v/c)^2}} = \gamma_v \gamma_{u'} (1 + vu'_x / c^2)$

$$\Rightarrow \gamma_u c = \gamma_v (\gamma_{u'} c + \beta_v \gamma_{u'} u'_x)$$

$$\Rightarrow \gamma_u u_x = \gamma_v (\gamma_{u'} u'_x + \gamma_{u'} v) = \gamma_v (\gamma_{u'} u'_x + \beta_v \gamma_{u'} c)$$

$$\Rightarrow \gamma_u u_y = \gamma_{u'} u'_y \quad \gamma_u u_z = \gamma_{u'} u'_z$$

$$\Rightarrow \begin{pmatrix} \gamma_u c \\ \gamma_u u_x \\ \gamma_u u_y \\ \gamma_u u_z \end{pmatrix} = \mathcal{L}_v \begin{pmatrix} \gamma_{u'} c \\ \gamma_{u'} u'_x \\ \gamma_{u'} u'_y \\ \gamma_{u'} u'_z \end{pmatrix}$$



Special theory of relativity and Maxwell's equations

Continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{J} = 0$$

Lorenz gauge condition:

$$\frac{1}{c} \frac{\partial \Phi}{\partial t} + \nabla \cdot \mathbf{A} = 0$$

Potential equations:

$$\frac{1}{c^2} \frac{\partial^2 \Phi}{\partial t^2} - \nabla^2 \Phi = 4\pi\rho$$

$$\frac{1}{c^2} \frac{\partial^2 \mathbf{A}}{\partial t^2} - \nabla^2 \mathbf{A} = \frac{4\pi}{c} \mathbf{J}$$

Field relations:

$$\mathbf{E} = -\nabla\Phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t}$$

$$\mathbf{B} = \nabla \times \mathbf{A}$$



More 4-vectors:

$$\alpha = \{0, 1, 2, 3\}$$

Time and position :

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \Rightarrow x^\alpha$$

Charge and current :

$$\begin{pmatrix} c\rho \\ J_x \\ J_y \\ J_z \end{pmatrix} \Rightarrow J^\alpha$$

Vector and scalar potentials :

$$\begin{pmatrix} \Phi \\ A_x \\ A_y \\ A_z \end{pmatrix} \Rightarrow A^\alpha$$



Lorentz transformations

$$\mathcal{L}_v = \begin{pmatrix} \gamma_v & \gamma_v \beta_v & 0 & 0 \\ \gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Time and space :

$$x^\alpha = \mathcal{L}_v x'^\alpha \equiv \mathcal{L}_v^{\alpha\beta} x'^\beta$$

Charge and current :

$$J^\alpha = \mathcal{L}_v J'^\alpha \equiv \mathcal{L}_v^{\alpha\beta} J'^\beta$$

Vector and scalar potential : $A^\alpha = \mathcal{L}_v A'^\alpha \equiv \mathcal{L}_v^{\alpha\beta} A'^\beta$

Notation:

$$\mathcal{L}_v^{\alpha\beta} x'^\beta \equiv \sum_{\beta=0}^3 \mathcal{L}_v^{\alpha\beta} x'^\beta$$



Repeated index
summation
convention



4-vector relationships

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} \Leftrightarrow \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix} \Leftrightarrow (A^0, \mathbf{A}): \text{ upper index 4 - vector } A^\alpha \text{ for } (\alpha = 0, 1, 2, 3)$$

Keeping track of signs - - lower index 4 - vector $A_\alpha = (A^0, -\mathbf{A})$

Derivative operators (defined with different sign convention):

$$\partial^\alpha = \left(\frac{\partial}{c\partial t}, -\nabla \right) \quad \partial_\alpha = \left(\frac{\partial}{c\partial t}, \nabla \right)$$



Special theory of relativity and Maxwell's equations

Continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{J} = 0 \quad \rightarrow \quad \partial_\alpha J^\alpha = 0$$

Lorenz gauge condition:

$$\frac{1}{c} \frac{\partial \Phi}{\partial t} + \nabla \cdot \mathbf{A} = 0 \quad \rightarrow \quad \partial_\alpha A^\alpha = 0$$

Potential equations:

$$\left. \begin{aligned} \frac{1}{c^2} \frac{\partial^2 \Phi}{\partial t^2} - \nabla^2 \Phi &= 4\pi\rho \\ \frac{1}{c^2} \frac{\partial^2 \mathbf{A}}{\partial t^2} - \nabla^2 \mathbf{A} &= \frac{4\pi}{c} \mathbf{J} \end{aligned} \right\} \partial_\alpha \partial^\alpha A^\beta = \frac{4\pi}{c} J^\beta$$

Field relations:

$$\mathbf{E} = -\nabla \Phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} \quad \rightarrow \quad ??$$
$$\mathbf{B} = \nabla \times \mathbf{A}$$



From the scalar and vector potentials, we can determine the \mathbf{E} and \mathbf{B} fields and then relate them to 4-vectors, finding --

$$\mathbf{E} = -\nabla\Phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} \quad E_x = -\frac{\partial\Phi}{\partial x} - \frac{\partial A_x}{c\partial t} = -(\partial^0 A^1 - \partial^1 A^0)$$

$$E_y = -\frac{\partial\Phi}{\partial y} - \frac{\partial A_y}{c\partial t} = -(\partial^0 A^2 - \partial^2 A^0)$$

$$E_z = -\frac{\partial\Phi}{\partial z} - \frac{\partial A_z}{c\partial t} = -(\partial^0 A^3 - \partial^3 A^0)$$

$$\mathbf{B} = \nabla \times \mathbf{A}$$

$$B_x = \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} = -(\partial^2 A^3 - \partial^3 A^2)$$

$$B_y = \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} = -(\partial^3 A^1 - \partial^1 A^3)$$

$$B_z = \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} = -(\partial^1 A^2 - \partial^2 A^1)$$



Field strength tensor

$$F^{\alpha\beta} \equiv (\partial^\alpha A^\beta - \partial^\beta A^\alpha)$$

For stationary frame

$$F^{\alpha\beta} \equiv \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix}$$

For moving frame

$$F'^{\alpha\beta} \equiv \begin{pmatrix} 0 & -E'_x & -E'_y & -E'_z \\ E'_x & 0 & -B'_z & B'_y \\ E'_y & B'_z & 0 & -B'_x \\ E'_z & -B'_y & B'_x & 0 \end{pmatrix}$$

Summary --

Field strength tensor $F^{\alpha\beta} \equiv (\partial^\alpha A^\beta - \partial^\beta A^\alpha)$

$$F^{\alpha\beta} \equiv \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix} \quad F'^{\alpha\beta} \equiv \begin{pmatrix} 0 & -E'_x & -E'_y & -E'_z \\ E'_x & 0 & -B'_z & B'_y \\ E'_y & B'_z & 0 & -B'_x \\ E'_z & -B'_y & B'_x & 0 \end{pmatrix}$$



➔ This analysis shows that the E and B fields must be treated as components of the field strength tensor and that in order to transform between inertial frames, we need to use the tensor transformation relationships:

Transformation of field strength tensor

$$F^{\alpha\beta} = \mathcal{L}_v^{\alpha\gamma} F^{\gamma\delta} \mathcal{L}_v^{\delta\beta} \quad \mathcal{L}_v = \begin{pmatrix} \gamma_v & \gamma_v \beta_v & 0 & 0 \\ \gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$F^{\alpha\beta} = \begin{pmatrix} 0 & -E'_x & -\gamma_v(E'_y + \beta_v B'_z) & -\gamma_v(E'_z - \beta_v B'_y) \\ E'_x & 0 & -\gamma_v(B'_z + \beta_v E'_y) & \gamma_v(B'_y - \beta_v E'_z) \\ \gamma_v(E'_y + \beta_v B'_z) & \gamma_v(B'_z + \beta_v E'_y) & 0 & -B'_x \\ \gamma_v(E'_z - \beta_v B'_y) & -\gamma_v(B'_y - \beta_v E'_z) & B'_x & 0 \end{pmatrix}$$



Inverse transformation of field strength tensor

$$F'^{\alpha\beta} = \mathcal{L}_v^{-1\alpha\gamma} F^{\gamma\delta} \mathcal{L}_v^{-1\delta\beta} \quad \mathcal{L}_v^{-1} = \begin{pmatrix} \gamma_v & -\gamma_v \beta_v & 0 & 0 \\ -\gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$F'^{\alpha\beta} = \begin{pmatrix} 0 & -E_x & -\gamma_v(E_y - \beta_v B_z) & -\gamma_v(E_z + \beta_v B_y) \\ E_x & 0 & -\gamma_v(B_z - \beta_v E_y) & \gamma_v(B_y + \beta_v E_z) \\ \gamma_v(E_y - \beta_v B_z) & \gamma_v(B_z - \beta_v E_y) & 0 & -B_x \\ \gamma_v(E_z + \beta_v B_y) & -\gamma_v(B_y + \beta_v E_z) & B_x & 0 \end{pmatrix}$$

Summary of results:

$$E'_x = E_x$$

$$B'_x = B_x$$

$$E'_y = \gamma_v(E_y - \beta_v B_z)$$

$$B'_y = \gamma_v(B_y + \beta_v E_z)$$

$$E'_z = \gamma_v(E_z + \beta_v B_y)$$

$$B'_z = \gamma_v(B_z - \beta_v E_y)$$

Comparison of the two transformations

$$F^{\alpha\beta} = \mathcal{L}_v^{\alpha\gamma} F'^{\gamma\delta} \mathcal{L}_v^{\delta\beta} \quad \mathcal{L}_v = \begin{pmatrix} \gamma_v & \gamma_v \beta_v & 0 & 0 \\ \gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$F^{\alpha\beta} = \begin{pmatrix} 0 & -E'_x & -\gamma_v(E'_y + \beta_v B'_z) & -\gamma_v(E'_z - \beta_v B'_y) \\ E'_x & 0 & -\gamma_v(B'_z + \beta_v E'_y) & \gamma_v(B'_y - \beta_v E'_z) \\ \gamma_v(E'_y + \beta_v B'_z) & \gamma_v(B'_z + \beta_v E'_y) & 0 & -B'_x \\ \gamma_v(E'_z - \beta_v B'_y) & -\gamma_v(B'_y - \beta_v E'_z) & B'_x & 0 \end{pmatrix}$$

$$F'^{\alpha\beta} = \mathcal{L}_v^{-1\alpha\gamma} F^{\gamma\delta} \mathcal{L}_v^{-1\delta\beta} \quad \mathcal{L}_v^{-1} = \begin{pmatrix} \gamma_v & -\gamma_v \beta_v & 0 & 0 \\ -\gamma_v \beta_v & \gamma_v & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$F'^{\alpha\beta} = \begin{pmatrix} 0 & -E_x & -\gamma_v(E_y - \beta_v B_z) & -\gamma_v(E_z + \beta_v B_y) \\ E_x & 0 & -\gamma_v(B_z - \beta_v E_y) & \gamma_v(B_y + \beta_v E_z) \\ \gamma_v(E_y - \beta_v B_z) & \gamma_v(B_z - \beta_v E_y) & 0 & -B_x \\ \gamma_v(E_z + \beta_v B_y) & -\gamma_v(B_y + \beta_v E_z) & B_x & 0 \end{pmatrix}$$

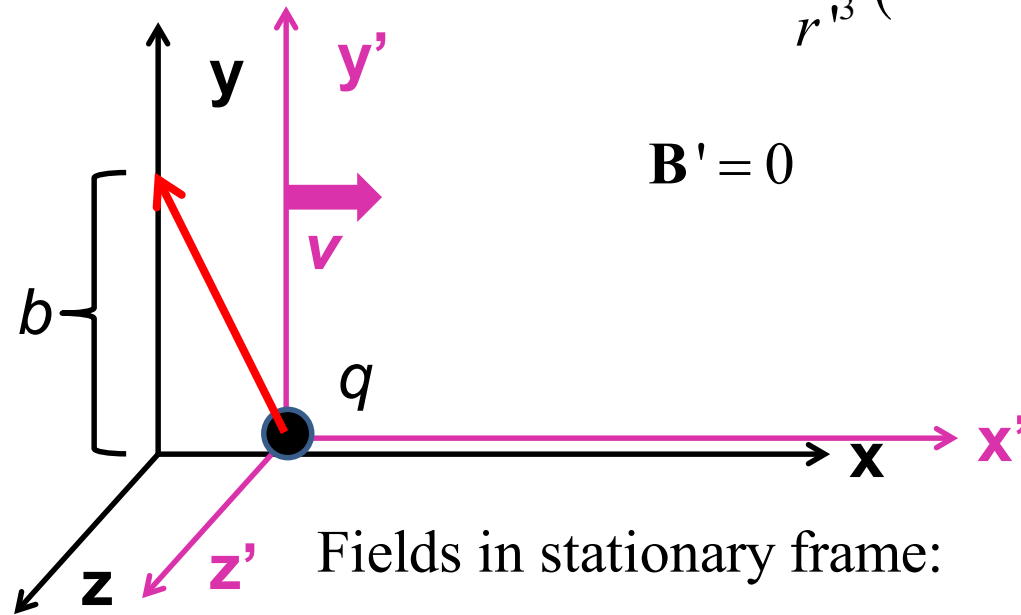


Example:

Fields in moving frame:

$$\mathbf{E}' = \frac{q}{r'^3} (x' \hat{\mathbf{x}} + y' \hat{\mathbf{y}}) = \frac{q(-vt' \hat{\mathbf{x}} + b \hat{\mathbf{y}})}{\left((-vt')^2 + b^2\right)^{3/2}}$$

$$\mathbf{B}' = 0$$



Fields in stationary frame:

$$E_x = E'_x$$

$$B_x = B'_x$$

$$E_y = \gamma_v (E'_y + \beta_v B'_z)$$

$$B_y = \gamma_v (B'_y - \beta_v E'_z)$$

$$E_z = \gamma_v (E'_z - \beta_v B'_y)$$

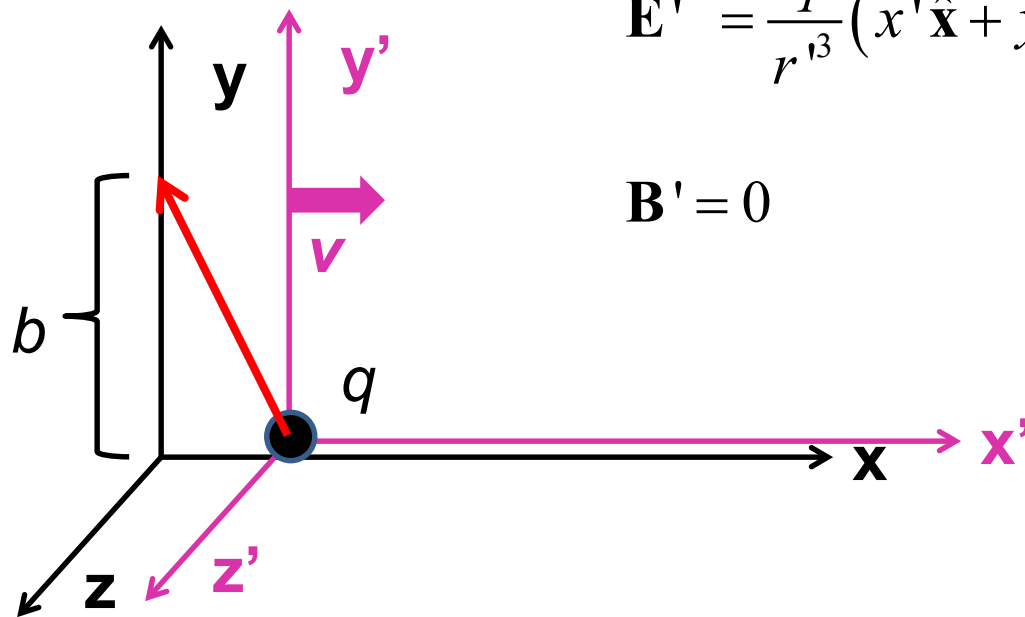
$$B_z = \gamma_v (B'_z + \beta_v E'_y)$$

Example:

Fields in moving frame:

$$\mathbf{E}' = \frac{q}{r'^3} (x' \hat{\mathbf{x}} + y' \hat{\mathbf{y}}) = \frac{q(-vt' \hat{\mathbf{x}} + b \hat{\mathbf{y}})}{\left((-vt')^2 + b^2\right)^{3/2}}$$

$$\mathbf{B}' = 0$$



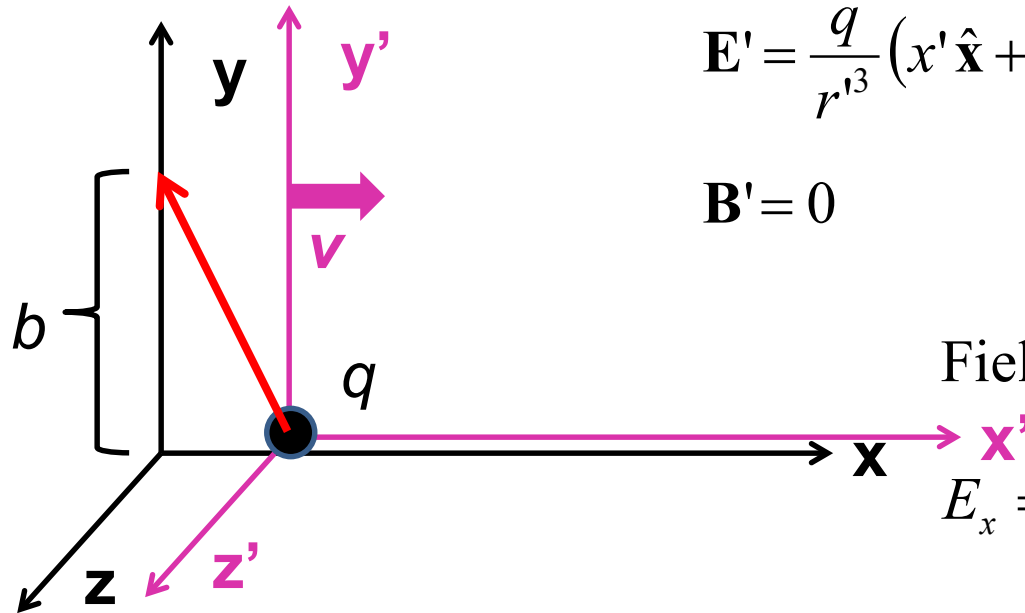
Fields in stationary frame:

$$E_x = E'_x = \frac{q(-vt')}{\left((-vt')^2 + b^2\right)^{3/2}}$$

$$E_y = \gamma_v (E'_y) = \frac{q(\gamma_v b)}{\left((-vt')^2 + b^2\right)^{3/2}}$$

$$B_z = \gamma_v (\beta_v E'_y) = \frac{q(\gamma_v \beta_v b)}{\left((-vt')^2 + b^2\right)^{3/2}}$$

Example:



Fields in moving frame :

$$\mathbf{E}' = \frac{q}{r'^3} (x' \hat{\mathbf{x}} + y' \hat{\mathbf{y}}) = \frac{q(-vt' \hat{\mathbf{x}} + b \hat{\mathbf{y}})}{\left((-vt')^2 + b^2\right)^{3/2}}$$

$$\mathbf{B}' = 0$$

Fields in stationary frame:

$$E_x = E'_x = \frac{q(-v\gamma_v t)}{\left((-v\gamma_v t)^2 + b^2\right)^{3/2}}$$

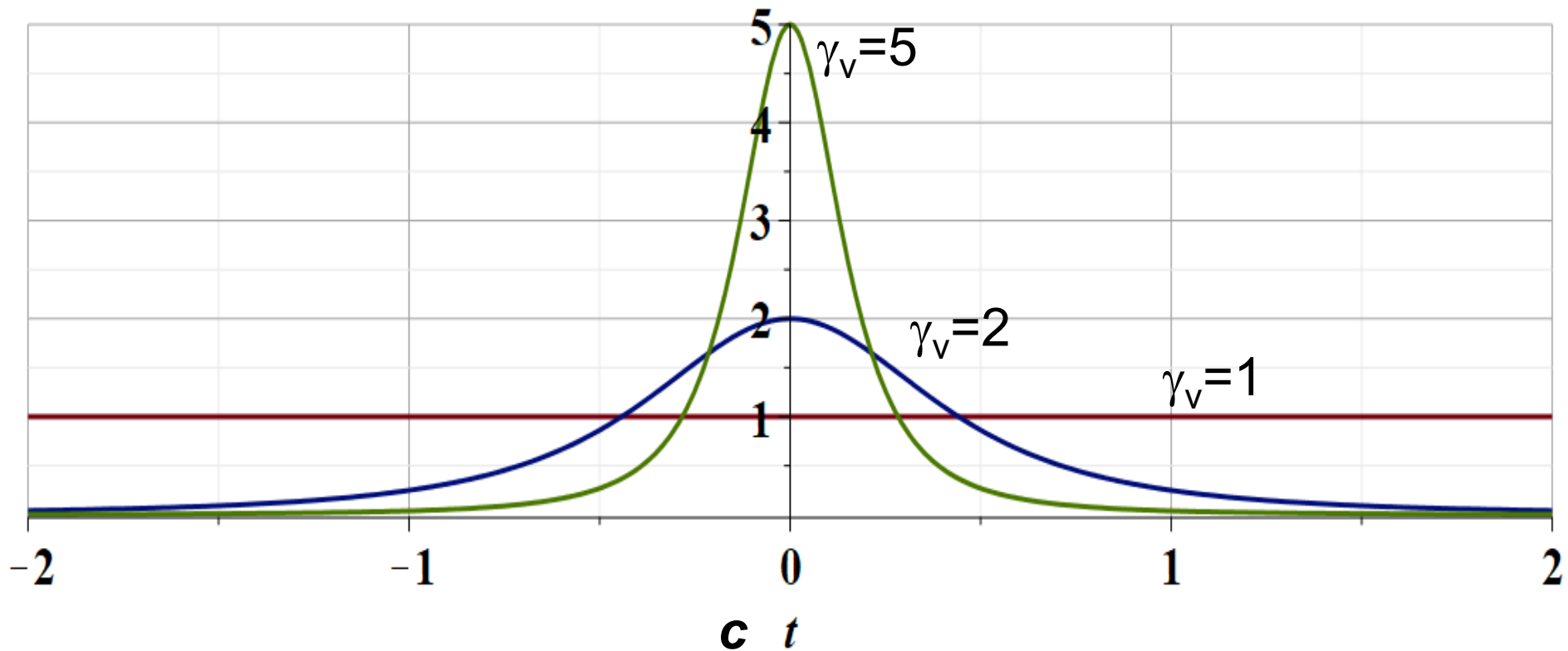
$$E_y = \gamma_v (E'_y) = \frac{q(\gamma_v b)}{\left((-v\gamma_v t)^2 + b^2\right)^{3/2}}$$

$$B_z = \gamma_v (\beta_v E'_y) = \frac{q(\gamma_v \beta_v b)}{\left((-v\gamma_v t)^2 + b^2\right)^{3/2}}$$

Expression in terms of consistent coordinates

$$t' = \gamma_v t$$

$$E_y = \frac{q(\gamma_v b)}{\left((-v\gamma_v t)^2 + b^2\right)^{3/2}} = \frac{q(\gamma_v b)}{\left((\gamma_v^2 - 1)c^2 t^2 + b^2\right)^{3/2}}$$





Examination of this system from the viewpoint of the
the Liénard-Wiechert potentials (temporarily keeping SI units)

$$\rho(\mathbf{r}, t) = q\delta^3(\mathbf{r} - \mathbf{R}_q(t)) \quad \mathbf{J}(\mathbf{r}, t) = q\dot{\mathbf{R}}_q(t)\delta^3(\mathbf{r} - \mathbf{R}_q(t)) \quad \dot{\mathbf{R}}_q(t) = \frac{d\mathbf{R}_q(t)}{dt}$$

$$\Phi(\mathbf{r}, t) = \frac{1}{4\pi\epsilon_0} \int \int d^3r' dt' \frac{\rho(\mathbf{r}', t')}{|\mathbf{r} - \mathbf{r}'|} \delta(t' - (t - |\mathbf{r} - \mathbf{r}'|/c))$$

$$\mathbf{A}(\mathbf{r}, t) = \frac{1}{4\pi\epsilon_0 c^2} \int \int d^3r' dt' \frac{\mathbf{J}(\mathbf{r}', t')}{|\mathbf{r} - \mathbf{r}'|} \delta(t' - (t - |\mathbf{r} - \mathbf{r}'|/c))$$

Evaluating integral over t' :

$$\int_{-\infty}^{\infty} dt' f(t') \delta(t' - (t - |\mathbf{r} - \mathbf{R}_q(t')|/c)) = \frac{f(t_r)}{1 - \frac{\mathbf{R}_q(t_r) \cdot (\mathbf{r} - \mathbf{R}_q(t_r))}{c |\mathbf{r} - \mathbf{R}_q(t_r)|}},$$



Examination of this system from the viewpoint of the the Liénard-Wiechert potentials – continued (SI units)

$$\Phi(\mathbf{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1}{R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}}$$

$$\mathbf{A}(\mathbf{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \frac{\mathbf{v}}{R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}}$$

$$\text{where } \mathbf{R} = \mathbf{r} - \mathbf{R}_q(t_r) \quad \mathbf{v} = \frac{d\mathbf{R}_q(t_r)}{dt_r}$$

$$\mathbf{E}(\mathbf{r}, t) = -\nabla\Phi(\mathbf{r}, t) - \frac{\partial\mathbf{A}(\mathbf{r}, t)}{\partial t}$$

$$\mathbf{B}(\mathbf{r}, t) = \nabla \times \mathbf{A}(\mathbf{r}, t)$$



Examination of this system from the viewpoint of the Liénard-Wiechert potentials – continued (SI units)

$$\mathbf{E}(\mathbf{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^3} \left[\left(\mathbf{R} - \frac{\mathbf{v}R}{c} \right) \left(1 - \frac{v^2}{c^2} \right) + \left(\mathbf{R} \times \left\{ \left(\mathbf{R} - \frac{\mathbf{v}R}{c} \right) \times \frac{\dot{\mathbf{v}}}{c^2} \right\} \right) \right]$$

$$\mathbf{B}(\mathbf{r}, t) = \frac{q}{4\pi\epsilon_0 c^2} \left[\frac{-\mathbf{R} \times \mathbf{v}}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^3} \left(1 - \frac{v^2}{c^2} + \frac{\dot{\mathbf{v}} \cdot \mathbf{R}}{c^2} \right) - \frac{\mathbf{R} \times \dot{\mathbf{v}} / c}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^2} \right]$$

$$\mathbf{B}(\mathbf{r}, t) = \frac{\mathbf{R} \times \mathbf{E}(\mathbf{r}, t)}{cR}.$$

Examination of this system from the viewpoint of the
the Liénard-Wiechert potentials – (**Gaussian units**)

$$\mathbf{E}(\mathbf{r}, t) = \frac{q}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^3} \left[\left(\mathbf{R} - \frac{\mathbf{v}R}{c} \right) \left(1 - \frac{v^2}{c^2} \right) + \left(\mathbf{R} \times \left\{ \left(\mathbf{R} - \frac{\mathbf{v}R}{c} \right) \times \frac{\dot{\mathbf{v}}}{c^2} \right\} \right) \right]$$

$$\mathbf{B}(\mathbf{r}, t) = \frac{q}{c} \left[\frac{-\mathbf{R} \times \mathbf{v}}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^3} \left(1 - \frac{v^2}{c^2} + \frac{\dot{\mathbf{v}} \cdot \mathbf{R}}{c^2} \right) - \frac{\mathbf{R} \times \dot{\mathbf{v}} / c}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^2} \right]$$

$$\mathbf{B}(\mathbf{r}, t) = \frac{\mathbf{R} \times \mathbf{E}(\mathbf{r}, t)}{R}.$$



Examination of this system from the viewpoint of the the Liénard-Wiechert potentials – continued (**Gaussian units**)

$$\mathbf{E}(\mathbf{r}, t) = \frac{q}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^3} \left[\left(\mathbf{R} - \frac{\mathbf{v}R}{c} \right) \left(1 - \frac{v^2}{c^2} \right) \right]$$

For our example:

$$\mathbf{R}_q(t_r) = vt_r \hat{\mathbf{x}} \quad \mathbf{r} = b \hat{\mathbf{y}}$$

$$\mathbf{R} = b \hat{\mathbf{y}} - vt_r \hat{\mathbf{x}} \quad R = \sqrt{v^2 t_r^2 + b^2}$$

$$\mathbf{v} = v \hat{\mathbf{x}} \quad t_r = t - \frac{R}{c}$$

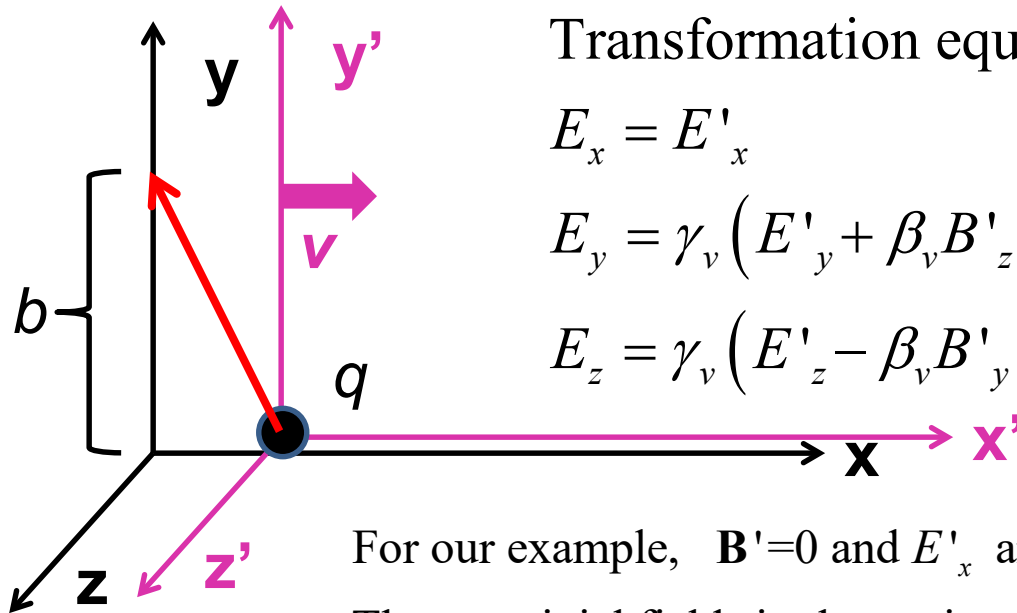
$$\mathbf{B}(\mathbf{r}, t) = \frac{q}{c} \left[\frac{-\mathbf{R} \times \mathbf{v}}{\left(R - \frac{\mathbf{v} \cdot \mathbf{R}}{c}\right)^3} \left(1 - \frac{v^2}{c^2} \right) \right]$$

This should be equivalent to the result given in Jackson (11.152):

$$\mathbf{E}(x, y, z, t) = \mathbf{E}(0, b, 0, t) = q \frac{-v\gamma t \hat{\mathbf{x}} + \gamma b \hat{\mathbf{y}}}{\left(b^2 + (v\gamma t)^2\right)^{3/2}}$$

$$\mathbf{B}(x, y, z, t) = \mathbf{B}(0, b, 0, t) = q \frac{\gamma \beta b \hat{\mathbf{z}}}{\left(b^2 + (v\gamma t)^2\right)^{3/2}}$$

Summary --



Transformation equations:

$$E_x = E'_x$$

$$E_y = \gamma_v (E'_y + \beta_v B'_z)$$

$$E_z = \gamma_v (E'_z - \beta_v B'_y)$$

$$B_x = B'_x$$

$$B_y = \gamma_v (B'_y - \beta_v E'_z)$$

$$B_z = \gamma_v (B'_z + \beta_v E'_y)$$

For our example, $\mathbf{B}'=0$ and E'_x and E'_y are nontrivial

The nontrivial fields in the stationary frame are

$$E_x = E'_x$$

$$E_y = \gamma_v E'_y$$

$$B_z = \gamma_v \beta_v E'_y$$