

## Lecture 2: Orthogonality

### Inner Products

Let  $\vec{x}, \vec{y} \in \mathbb{C}^n$ , then

$$\vec{x}^* \vec{y} = \langle \vec{x}, \vec{y} \rangle = \sum_{i=1}^n \bar{x}_i y_i$$

Where  $\bar{x}_i$  denotes complex conjugate.

1.  $\|\vec{x}\| = \langle \vec{x}, \vec{x} \rangle^{1/2}$ ,

2.  $\langle \vec{x}, \vec{y} \rangle = \|\vec{x}\| \|\vec{y}\| \cos(\theta)$ .

Two vectors  $\vec{x}, \vec{y}$  are orthogonal if

$$\langle \vec{x}, \vec{y} \rangle = 0.$$

Theorem - The vectors in an orthogonal set  $S$  are linearly independent.

proof:

For contradiction, suppose  $S$  is not a linearly independent set. Then, there exists  $\vec{v}_k \in S$  and  $c_i$  such that

$$\vec{v}_k = \sum_{i \neq k} c_i \vec{v}_i$$

$$\Rightarrow \langle \vec{v}_k, \vec{v}_k \rangle = 0,$$

$$\Rightarrow \vec{v} = 0$$

a contradiction. ■

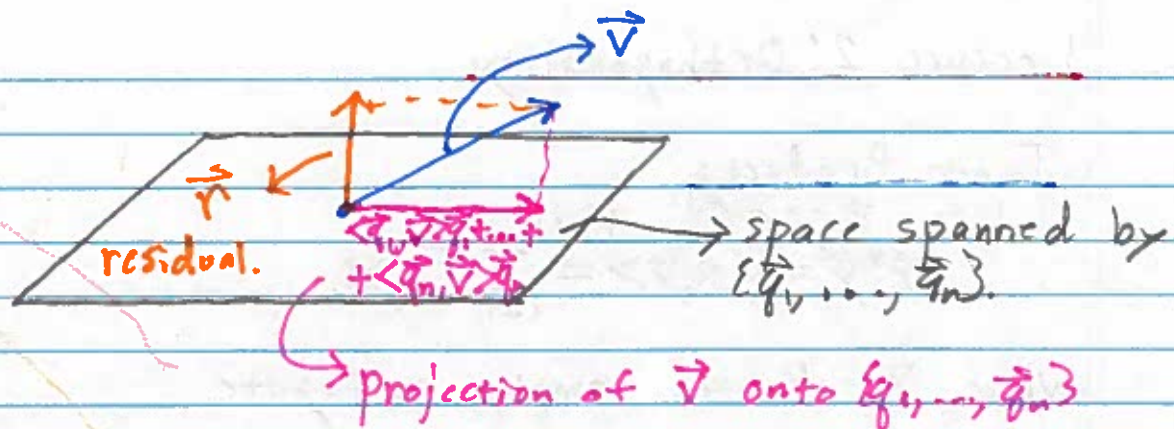
Components - Let  $\{\vec{q}_1, \dots, \vec{q}_n\}$  be an orthonormal set and let  $\vec{v} \in \mathbb{C}^n$ .

Define

$$\vec{r} = \vec{v} - (\langle \vec{q}_1, \vec{v} \rangle \vec{q}_1 + \dots + \langle \vec{q}_n, \vec{v} \rangle \vec{q}_n)$$

( $\vec{r}$  is called the residual)

$$\Rightarrow \langle \vec{q}_i, \vec{r} \rangle = \langle \vec{q}_i, \vec{v} \rangle - \langle \vec{q}_i, \vec{v} \rangle \langle \vec{q}_i, \vec{q}_i \rangle = 0.$$



If  $\{\vec{q}_i\}$  is a basis for  $\mathbb{C}^m$ , then

$$\vec{v} = \sum_{i=1}^m \langle \vec{q}_i, \vec{v} \rangle \vec{q}_i \rightarrow \text{project onto components}$$

$$= \sum_{i=1}^m (\vec{q}_i^T \vec{v}) \vec{q}_i$$

$$= \sum_{i=1}^m \vec{q}_i \vec{q}_i^T \vec{v}$$

$$= \sum_{i=1}^m \underbrace{(\vec{q}_i \vec{q}_i^T)}_{\text{matrices}} \vec{v}$$

(projections)  $\rightarrow$  sum of rank one matrices.

### Unitary Matrices:

A matrix is unitary if  $Q^T = Q^{-1}$ .

Proposition - The columns of a unitary matrix are orthonormal.

proof:

$$\langle \vec{q}_i, \vec{q}_j \rangle = \langle Q\vec{e}_i, Q\vec{e}_j \rangle$$

$$= (Q\vec{e}_i)^T \cdot Q\vec{e}_j$$

$$= \vec{e}_i^T Q^T \cdot Q\vec{e}_j$$

$$= \vec{e}_i^T Q^{-1} \cdot Q\vec{e}_j$$

$$= \vec{e}_i^T \cdot \vec{e}_j$$

$$= \begin{cases} 1 & \text{if } i=j \\ 0 & \text{o.w.} \end{cases}$$



## Matrices Revisited

In the previous proof I used the fact that the columns of the matrix  $Q$  are given by:

$$\vec{q}_i = Q\vec{e}_i.$$

This follows from:

$$\begin{aligned} Q\vec{x} &= Q(x_1\vec{e}_1 + \dots + x_n\vec{e}_n) \\ &= x_1 Q\vec{e}_1 + \dots + x_n Q\vec{e}_n \end{aligned}$$

### Result:

$Q\vec{x}$   $\rightarrow$  linear combination of columns of  $Q$ .

$Q^*\vec{b}$   $\rightarrow$  vector of coefficients of  $\vec{b}$  in the basis of columns of  $Q$ .

### Unitary Matrices preserve geometry:

$$\begin{aligned} \langle Q\vec{x}, Q\vec{y} \rangle &= (Q\vec{x})^T (Q\vec{y}) \\ &= \vec{x}^T Q^T Q\vec{y} \\ &= \vec{x}^T \vec{y} \\ &= \langle \vec{x}, \vec{y} \rangle \end{aligned}$$