

## Lecture 7: QR Factorization

$$A \in \mathbb{R}^{m \times n}$$

$$A = [\vec{a}_1 | \dots | \vec{a}_n]$$

### Gram-Schmidt:

$$\vec{q}_1 = \frac{\vec{a}_1}{r_{11}}$$

$$\vec{q}_2 = \frac{\vec{a}_2 - r_{12}\vec{q}_1}{r_{22}}$$

$$\vec{q}_3 = \frac{\vec{a}_3 - r_{13}\vec{q}_1 - r_{23}\vec{q}_2}{r_{33}}$$

$\vdots$

$$\vec{q}_n = \frac{\vec{a}_n - r_{1n}\vec{q}_1 - r_{2n}\vec{q}_2 - \dots - r_{(n-1)n}\vec{q}_{(n-1)}}{r_{nn}}$$

$$A = \underbrace{[\vec{q}_1 | \dots | \vec{q}_n]}_{m \times n} \underbrace{\begin{bmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ 0 & r_{22} & \dots & r_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & r_{nn} \end{bmatrix}}_{\text{upper triangular.}} \Bigg\}^{n \times n}$$

$$A = \tilde{Q} \tilde{R} \quad (\text{reduced QR})$$

$$\downarrow$$
$$A = Q R \quad (\text{Full QR append rows and columns})$$

### Algorithm (Math Version):

$$\vec{q}_1 = \frac{\vec{a}_1}{r_{11}}$$

$$r_{ij} = \vec{q}_i^* \vec{a}_j$$

$$\vec{q}_2 = \frac{\vec{a}_2 - r_{12}\vec{q}_1}{r_{22}}$$

$$\|r_{jj}\| = \|\vec{a}_j - \sum_{i=1}^{j-1} r_{ij}\vec{q}_i\|_2$$

$$\vec{q}_3 = \frac{\vec{a}_3 - r_{13}\vec{q}_1 - r_{23}\vec{q}_2}{r_{33}}$$

$\vdots$

$$\vec{q}_n = \frac{\vec{a}_n - \sum_{i=1}^{n-1} r_{in}\vec{q}_i}{r_{nn}}$$

Algorithm (Pseudo Code):

```
for j=1 to n
   $\vec{v}_j = \vec{a}_j$ 
  for i=1 to j-1
     $r_{ij} = \vec{q}_i \cdot \vec{a}_j$ 
     $\vec{v}_j = \vec{v}_j - r_{ij} \vec{q}_i$ 
  end
   $r_{jj} = \|\vec{v}_j\|_2$ 
   $\vec{q}_j = \vec{v}_j / r_{jj}$ 
```

end.

Solving Equations by QR.

$$A\vec{x} = \vec{b}$$

↓

$$QR\vec{x} = \vec{b}$$

$$R\vec{x} = Q^*\vec{b}$$

→ easy inverse!

$$\text{Let } \vec{y} = Q^*\vec{b}$$

$$\Rightarrow R\vec{x} = \vec{y}$$

Solve  $R\vec{x} = \vec{y}$  by substitution.