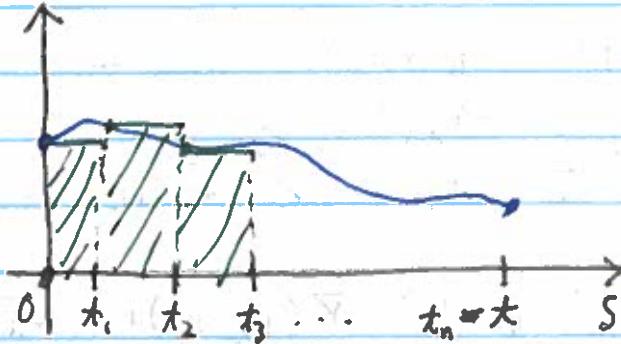


Lecture 13: The Ito Integral

Recall the Riemann integral is defined by

$$G(t) = \int_0^t g(s) ds = \lim_{n \rightarrow \infty} \sum_{j=0}^{n-1} g(t_j)(t_{j+1} - t_j)$$



Key idea:

Add up sum of functions for which we know the area and take limit.

Definition: A simple function on the interval $[0, t]$ is any function of the form:

$$\chi(s) = a_0 \mathbb{1}_{[0, t_1]}(t) + a_1 \mathbb{1}_{[t_1, t_2]}(t) + \dots + a_{n-1} \mathbb{1}_{[t_{n-1}, t_n]}(t),$$

$$\Rightarrow \int_0^t \chi(s) ds = a_0(t_1 - t_0) + a_1(t_2 - t_1) + \dots + a_{n-1}(t_n - t_{n-1}).$$

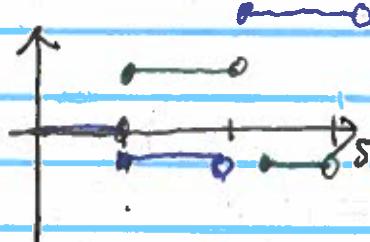
Definition: Let \mathcal{F}_t be a filtration. A simple random process on $[0, T]$ is any random variable of the form:

$$X_t = Y_0 \mathbb{1}_{[0, t_1]}(t) + Y_1 \mathbb{1}_{[t_1, t_2]}(t) + \dots + Y_{n-1} \mathbb{1}_{[t_{n-1}, t_n]}(t).$$

Where Y_j is \mathcal{F}_{t_j} measurable and $\mathbb{E}[Y_j^2] < \infty$. The space of all simple random variables is denoted $S(T)$.

Example:

$$X_s = \begin{cases} 0, & \text{if } s \in [0, \frac{1}{3}) \\ B_{\frac{1}{3}}, & \text{if } s \in [\frac{1}{3}, \frac{2}{3}) \\ B_{\frac{2}{3}}, & \text{if } s \in [\frac{2}{3}, 1] \end{cases}$$



Two different realizations

Definition- Let $X \in S(T)$ be a simple random process given by

$$X = I_0 \mathbf{1}_{[t_0, t_1)} + \dots + I_{n-1} \mathbf{1}_{[t_{n-1}, T]}$$

The Itô integral of X with respect to Brownian motion is given by:

$$\int_0^T X_s dB_s = I_0 \cdot (B_{t_1} - B_{t_0}) + I_1 \cdot (B_{t_2} - B_{t_1}) + \dots + I_{n-1} \cdot (B_{t_n} - B_{t_{n-1}}).$$

Example:

Taking X_s in the previous example we have:

$$I_s = \int_0^s X_t dB_t = \begin{cases} 0 & \text{if } t \in [0, \frac{1}{3}) \\ B_{\frac{1}{3}}(B_t - B_{\frac{1}{3}}) & \text{if } t \in [\frac{1}{3}, \frac{2}{3}) \\ B_{\frac{1}{3}}(B_{\frac{2}{3}} - B_{\frac{1}{3}}) + B_{\frac{2}{3}}(B_t - B_{\frac{2}{3}}) & \text{if } t \in [\frac{2}{3}, 1]. \end{cases}$$

It is a martingale. For example, take $t > \frac{2}{3}$ and $\frac{1}{3} \leq s < \frac{2}{3}$. Then,

$$\mathbb{E}[I_t | \mathcal{F}_s] = \mathbb{E}[B_{\frac{1}{3}}(B_{\frac{2}{3}} - B_{\frac{1}{3}}) + B_{\frac{2}{3}}(B_t - B_{\frac{2}{3}}) | \mathcal{F}_s]$$

$$\begin{aligned} &= B_{\frac{1}{3}} \mathbb{E}[(B_{\frac{2}{3}} - B_{\frac{1}{3}}) | \mathcal{F}_s] + \mathbb{E}[B_{\frac{2}{3}}(B_t - B_{\frac{2}{3}}) | \mathcal{F}_s] \\ &= B_{\frac{1}{3}} \mathbb{E}[(B_{\frac{2}{3}} - B_s + B_s - B_{\frac{1}{3}}) | \mathcal{F}_s] + \mathbb{E}[(B_{\frac{2}{3}} - B_s + B_s)(B_t - B_{\frac{2}{3}}) | \mathcal{F}_s] \\ &= B_{\frac{1}{3}} \mathbb{E}[(B_{\frac{2}{3}} - B_s) | \mathcal{F}_s] + B_{\frac{2}{3}} \mathbb{E}[B_s(B_t - B_{\frac{2}{3}}) | \mathcal{F}_s] \\ &\quad + \mathbb{E}[(B_{\frac{2}{3}} - B_s)(B_t - B_{\frac{2}{3}}) | \mathcal{F}_s] + \mathbb{E}[B_s(B_t - B_{\frac{2}{3}}) | \mathcal{F}_s] \\ &= B_{\frac{1}{3}} \mathbb{E}[B_{\frac{2}{3}} - B_s] + B_{\frac{2}{3}}(B_s - B_{\frac{1}{3}}) + (B_{\frac{2}{3}} - B_s) \mathbb{E}[B_t - B_{\frac{2}{3}} | \mathcal{F}_s] \\ &\quad + B_s \mathbb{E}[B_t - B_{\frac{2}{3}} | \mathcal{F}_s] \\ &= B_{\frac{1}{3}}(B_s - B_{\frac{1}{3}}) + (B_{\frac{2}{3}} - B_s) \mathbb{E}[B_t - B_{\frac{2}{3}}] + B_s \mathbb{E}[B_t - B_{\frac{2}{3}}] \\ &= B_{\frac{1}{3}}(B_s - B_{\frac{1}{3}}) = I_s. \end{aligned}$$

Theorem - Let B_t be a standard Brownian motion on $[0, T]$ defined on (Ω, \mathcal{F}, P) and $X_s, X'_s \in S(T)$. Then.

1. Linearity -

$$\int_0^t (aX_s + bX'_s) dB_s = a \int_0^t X_s dB_s + b \int_0^t X'_s dB_s.$$

2. Continuous Martingale - The process $\bar{Y}_t = \int_0^t X_s dB_s$ is a martingale for the Brownian filtration.

3. Ito Isometry - The random variable $\bar{Y}_t = \int_0^t X_s dB_s$

is in $L^2(\Omega, \mathcal{F}, P)$ with mean 0 ... variance

$$\begin{aligned} \mathbb{E}[\bar{Y}_t^2] &= \mathbb{E}\left[\left(\int_0^t X_s dB_s\right)^2\right] \\ &= \int_0^t \mathbb{E}[X_s^2] ds \\ &= \mathbb{E}\left[\int_0^t X_s^2 ds\right] \end{aligned}$$

Proof:

1. Trivial

2. Let $X_s \in S(T)$. Then,

$$X_t = \sum_{i=0}^n X_i \mathbf{1}_{[t_i, t_{i+1})}(t)$$

$$\begin{aligned} \Rightarrow \bar{Y}_t &= \int_0^t X_s dB_s \\ &= \sum_{i=0}^n X_i (B_{t_{i+1}} - B_{t_i}) \end{aligned}$$

Now,

$$\begin{aligned} \mathbb{E}[X_i (B_{t_{i+1}} - B_{t_i}) | \mathcal{F}(s)] &= \begin{cases} X_i (B_{t_{i+1}} - B_{t_i}), & \text{if } s > i+1 \\ X_i \mathbb{E}[B_{t_{i+1}} | \mathcal{F}(B_s)] - X_i B_{t_i}, & \text{if } i < s < i+1 \\ \mathbb{E}[X_i (B_{t_{i+1}} - B_{t_i}) | \mathcal{F}(B_s)], & \text{if } s < i. \end{cases} \end{aligned}$$

$$= \begin{cases} X_i (B_{t_{i+1}} - B_{t_i}), & \text{if } s > i+1 \\ X_i (B_s - B_{t_i}), & \text{if } i < s < i+1 \end{cases}$$

$$\begin{cases} \cancel{\mathbb{E}[X_i \mathbb{E}[B_{t_{i+1}} - B_i | \mathcal{F}(B_s)] | \mathcal{F}(B_s)]} & \text{if } s < i \end{cases}$$

$$\begin{aligned} \Rightarrow \mathbb{E}[\bar{Y}_t | \mathcal{F}(B_s)] &= X_0 (B_{t_1} - B_0) + X_1 (B_{t_2} - B_1) + \dots + X_n (B_s - B_{t_n}) \\ &= \bar{Y}_s. \end{aligned}$$

$$\begin{aligned}
 3. \text{ Since } \mathbb{E}[Z_j(B_{t_{j+1}} - D_{t_j})] &= \mathbb{E}[\mathbb{E}[Z_j(B_{t_{j+1}} - D_{t_j}) | \sigma(B_{t_j})]] \\
 &= \mathbb{E}[Z_j \mathbb{E}[B_{t_{j+1}} - D_{t_j} | \sigma(B_{t_j})]] \\
 &= \mathbb{E}[Z_j \cdot 0] \\
 &= 0.
 \end{aligned}$$

Therefore, $\mathbb{E}[Y_t] = \mathbb{E}\left[\sum_{j=0}^n Z_j (B_{t_{j+1}} - D_{t_j})\right] = 0.$

Now,

$$\begin{aligned}
 \mathbb{E}[Y_t^2] &= \mathbb{E}[(S^* \sum_s X_s dB_s)^2] \\
 &= \mathbb{E}\left[\left(\sum_j Z_j (B_{t_{j+1}} - D_{t_j})\right)^2\right] \\
 &= \mathbb{E}\left[\sum_{i,j} Z_i Z_j (B_{t_{i+1}} - D_{t_i})(B_{t_{j+1}} - D_{t_j})\right]
 \end{aligned}$$

If $t_i \neq t_j$ and without loss of generality $t_i < t_j$, then

$$\begin{aligned}
 \mathbb{E}[Z_i Z_j (B_{t_{i+1}} - D_{t_i})(B_{t_{j+1}} - D_{t_j})] &= \mathbb{E}[Z_i Z_j (B_{t_{i+1}} - D_{t_i}) \mathbb{E}[B_{t_{j+1}} - D_{t_j} | \sigma(B_{t_i})]] \\
 &= \mathbb{E}[Z_i Z_j (B_{t_{i+1}} - D_{t_i}) \cdot 0] \\
 &= 0.
 \end{aligned}$$

If $t_i = t_j$, then

$$\begin{aligned}
 \mathbb{E}[Z_i Z_i (B_{t_{i+1}} - D_{t_i})(B_{t_{i+1}} - D_{t_i})] &= \mathbb{E}[Z_i^2 (B_{t_{i+1}} - D_{t_i})^2] \\
 &= \mathbb{E}[Z_i^2 \mathbb{E}[(B_{t_{i+1}} - D_{t_i})^2 | \sigma(B_{t_i})]] \\
 &= \mathbb{E}[Z_i^2 (t_{i+1} - t_i)] \\
 &= (t_{i+1} - t_i) \mathbb{E}[Z_i^2]
 \end{aligned}$$

Therefore,

$$\mathbb{E}[Y_t^2] = \sum_{i=0}^{n-1} \mathbb{E}[Z_i^2] (t_{i+1} - t_i) = S^* \mathbb{E}[X_s^2] ds.$$

Definition - The Ito integral for any "integrable" stochastic process is the limit

$$S^* \sum_s X_s dB_s = \lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} X_i (B_{t_{i+1}} - B_{t_i}).$$

All of the previous three properties hold for this limit.

Corollary: Let B_s be standard Brownian motion. Then,

$$1. \mathbb{E}[(S^+_0 X_s dB_s)(S^+_0 Y_s dB_s)] = \int_0^{\min\{B_s, t\}} \mathbb{E}[X_s^2] ds$$

$$2. \mathbb{E}[(S^+_0 X_s dB_s)(S^+_0 Y_s d\bar{B}_s)] = \int_0^t \mathbb{E}[X_s Y_s] ds.$$

Proof

$$\begin{aligned} 2. \mathbb{E}[(S^+_0 (X_s + Y_s) dB_s)^2] &= \int_0^t \mathbb{E}[(X_s + Y_s)^2] ds \\ &= \int_0^t (\mathbb{E}[X_s^2] + 2\mathbb{E}[X_s Y_s] + \mathbb{E}[Y_s^2]) ds \end{aligned}$$

However,

$$\begin{aligned} \mathbb{E}[(S^+_0 (X_s + Y_s) dB_s)^2] &= \mathbb{E}[(S^+_0 X_s dB_s + S^+_0 Y_s dB_s)^2] \\ &= \mathbb{E}[S^+_0 X_s dB_s]^2 + 2\mathbb{E}[(S^+_0 X_s dB_s)(S^+_0 Y_s dB_s)] \\ &\quad + \mathbb{E}[(S^+_0 Y_s dB_s)^2] \\ &= \int_0^t \mathbb{E}[X_s^2] ds + 2\mathbb{E}[S^+_0 X_s dB_s (S^+_0 Y_s dB_s)] \\ &\quad + \int_0^t \mathbb{E}[Y_s^2] ds \\ \Rightarrow \mathbb{E}[(S^+_0 X_s dB_s)(S^+_0 Y_s dB_s)] &= \int_0^t \mathbb{E}[X_s Y_s] ds. \end{aligned}$$

Example:

$$I_t = \int_0^t B_s dB_s, \quad J_t = \int_0^t B_s^2 dB_s.$$

$$\mathbb{E}[I_t] = 0, \quad \mathbb{E}[J_t] = 0$$

$$\mathbb{E}[I_t^2] = \mathbb{E}[(\int_0^t B_s dB_s)^2] = \int_0^t \mathbb{E}[B_s^2] ds = \int_0^t s ds = t^2/2.$$

$$\mathbb{E}[J_t^2] = \mathbb{E}[(\int_0^t B_s^2 dB_s)^2] = \int_0^t \mathbb{E}[B_s^4] ds = \int_0^t 3s^2 ds = t^3/2$$

$$\mathbb{E}[I_t J_t] = \mathbb{E}[(\int_0^t B_s dB_s)(\int_0^t B_s^2 dB_s)] = \mathbb{E}[\int_0^t B_s \mathbb{E}[B_s^3] ds] = 0.$$

Example:

$$\bar{X}_t = \int_0^t B_s dB_s \text{ and let } \bar{Y}_t = \int_0^t \bar{X}_s dB_s.$$

$$\Rightarrow \mathbb{E}[\bar{X}_t] = 0$$

$$\Rightarrow \mathbb{E}[\bar{Y}_t^2] = \int_0^t \mathbb{E}[\bar{X}_s^2] ds$$

$$= \int_0^t \int_0^s \mathbb{E}[B_u^2] du ds$$

$$= \int_0^t \int_0^s v du ds$$

$$= t^3/6.$$

Corollary: Let B_t be a standard Brownian motion, and f be a function such that $\int_0^T f'(x) dx < \infty$. Then

$$\bar{X}_t = \int_0^t f(s) dB_s$$

is a Gaussian process with mean 0 and covariance.

$$\text{Cov}(\bar{X}_t, \bar{X}_{t'}) = \int_0^{\min\{t, t'\}} f(s)^2 ds.$$

Proof:

The approximation by a simple function is

$$\int_0^t f(s) dB_s = \sum_{j=0}^{n-1} f(t_j) (B_{t_{j+1}} - B_{t_j}).$$

Sum of Gaussians \Rightarrow Gaussian.