

Homework #4

#5.1.10

For each of the following systems, decide whether the origin is attracting, Liapunov stable, asymptotically stable, or none of the above.

Solution:

a.) $\dot{x} = y$
 $\dot{y} = -4x$

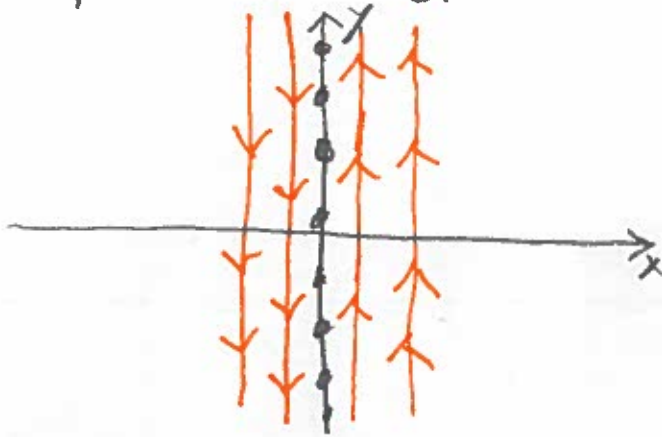
The origin is a linear center and hence Liapunov stable.

b.) $\dot{x} = 2y$
 $\dot{y} = x$

The origin is unstable and hence is neither.

c.) $\dot{x} = 0, \dot{y} = x$

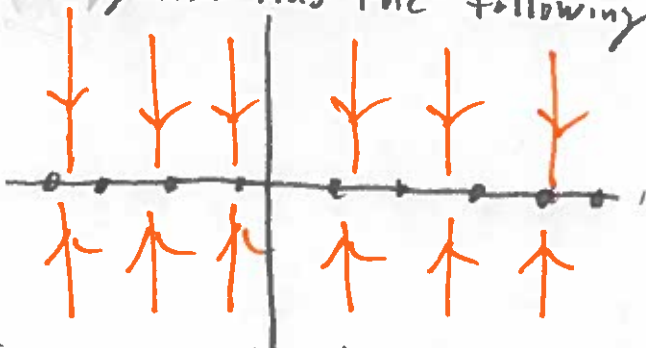
The system has eigenvalues $\lambda_1 = \lambda_2 = 0$ with a line of fixed points at $x=0$:



This system is also neither.

d.) $\dot{x} = 0, \dot{y} = -y$

This system has the following phase portrait:



This system is Liapunov stable.

e.) $\dot{x} = -x, \dot{y} = -5y$

The eigenvalues are all negative and hence the origin is asymptotically stable.

f.) $\dot{x} = x, \dot{y} = y$.

Both eigenvalues > 0 so the system is neither.

#5.3.4

Analyze the following system:

$$\dot{R} = aR + bJ$$

$$\dot{J} = -bR - aJ$$

Solution:

The eigenvalues satisfy

$$\lambda_1 + \lambda_2 = 0, \lambda_1 \lambda_2 = b^2 - a^2$$

$$\Rightarrow \lambda_1^2 = a^2 - b^2, \lambda_1 = -\lambda_2$$

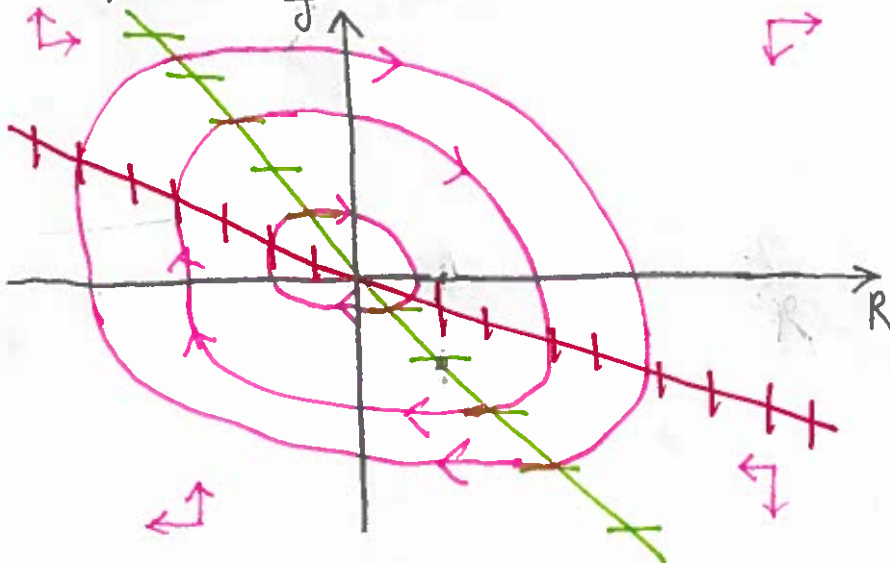
The null-clines are given by:

$$\dot{x}=0: J = -\frac{a}{b}R$$

$$\dot{y}=0: J = -\frac{b}{a}R$$

Case 1:

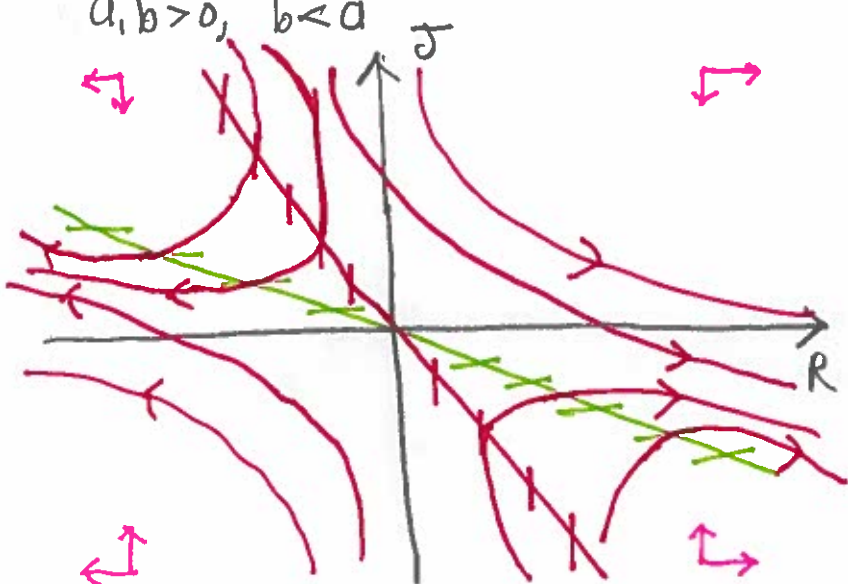
$$a, b > 0 \text{ and } b^2 > a^2$$



In this case Romeo and Juliet are only in love with each other a quarter of the time. Classic soap opera couple.

Case 2:

$$a, b > 0, \quad b^2 < a^2$$



In this either Juliet or Romeo falls in love with the other but the feelings are not returned.

Case 3:

$$a, b < 0, \quad \text{and} \quad b^2 > a^2$$

This case is the same as case 1 with the axis inverted.

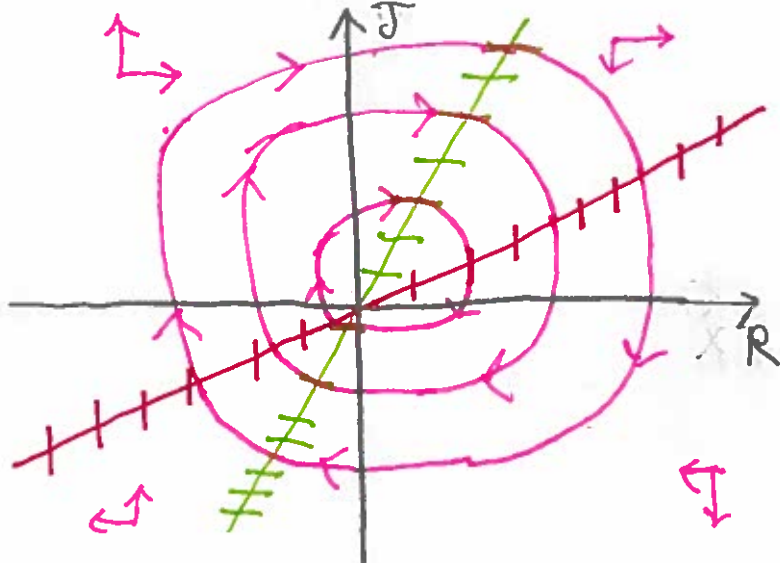
Case 4:

$$a, b < 0 \quad \text{and} \quad b^2 < a^2,$$

This case is the same as case 2 with the axis inverted.

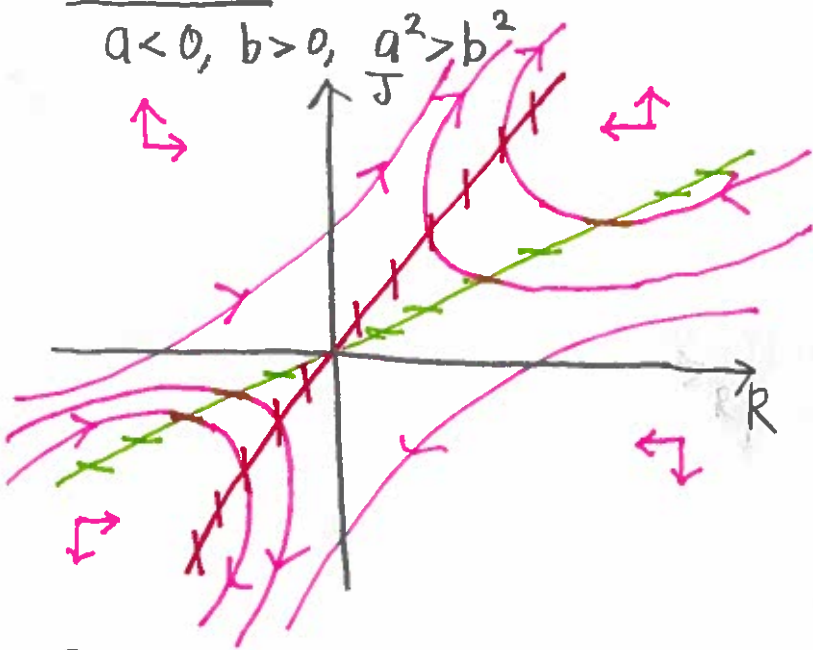
Case 5:

$$a < 0, \quad b > 0, \quad b^2 > a^2.$$



Case 6:

$$a < 0, b > 0, a^2 > b^2$$



In this case there is a chance for a happy couple depending on initial conditions!

Case 7:

$$b < 0, a > 0, b^2 > a^2$$

This case is the same as case 5 with the axis inverted.

Case 8:

$$b < 0, a > 0, a^2 < b^2$$

This case is the same as case 6 with the axis inverted.

#5.2.10

Plot the phase portrait for the system:

$$\begin{aligned} \dot{x} &= y \\ \dot{y} &= -x - 2y \end{aligned} \Rightarrow \dot{\vec{x}} = \begin{pmatrix} 0 & 1 \\ -1 & -2 \end{pmatrix} \vec{x}$$

Solution:

The eigenvalues satisfy

$$\lambda_1 + \lambda_2 = -2$$

$$\lambda_1 \lambda_2 = 1$$

$$\Rightarrow 1 + \lambda_1^2 = -2\lambda_1$$

$$\Rightarrow \lambda_1^2 + 2\lambda_1 + 1 = 0$$

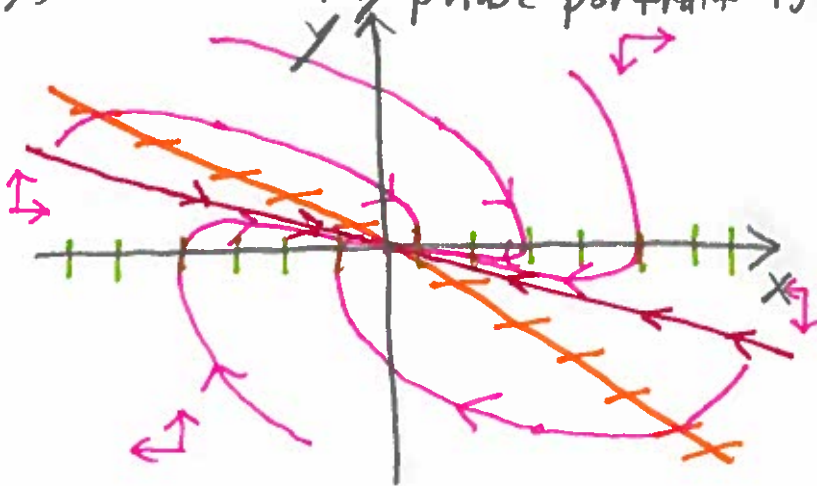
$$\Rightarrow \lambda_1 = \lambda_2 = -1$$

However there is only a single eigenvector $\vec{v} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$.
The null-lines are given by

$$\dot{x} = 0 \Rightarrow y = 0$$

$$\dot{y} = 0 \Rightarrow y = -\frac{1}{2}x.$$

Consequently, the resulting phase portrait is given by:



#5.2.13

Analyze the following system:
 $m\ddot{x} + b\dot{x} + kx = 0.$

Solution:

Let $v = \dot{x}$ then

$$\dot{x} = v$$

$$\dot{v} = -\frac{b}{m}v - \frac{k}{m}x$$

The eigenvalues satisfy:

$$\lambda_1 + \lambda_2 = -\frac{b}{m}$$

Let $\lambda_1 \lambda_2 = \frac{k}{m}$ which implies

$$\Rightarrow \lambda_1^2 + \frac{b}{m}\lambda_1 + \frac{k}{m} = 0$$

$$\Rightarrow \lambda_{1,2} = \frac{-b \pm \sqrt{b^2 - 4mk}}{2m}$$

Now since $-b + \sqrt{b^2 - 4mk} < 0$ if $b^2 - 4mk$ it follows that $R(\lambda_{1,2}) < 0$ for all parameter regimes. There are three cases!

1. $b^2 > 4mk$ Overdamped

2. $b^2 = 4mk$ Critically damped

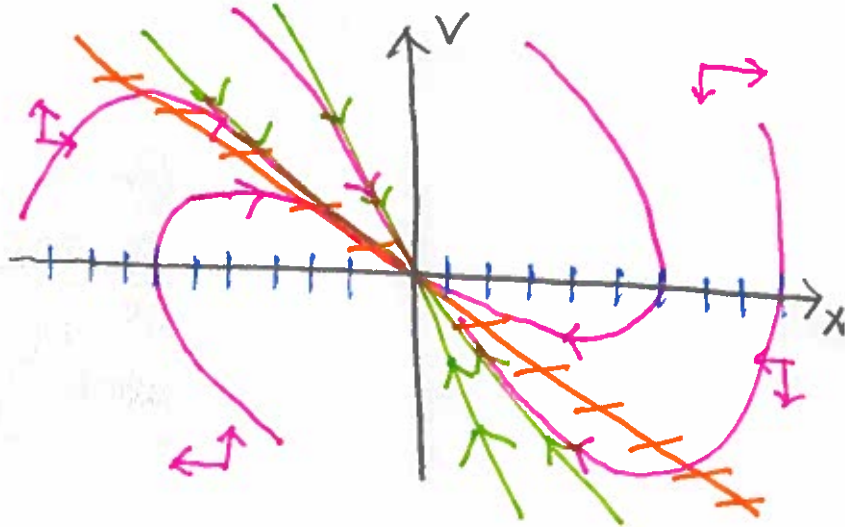
3. $b^2 < 4mk$ Underdamped vibrations

In terms of null-clines we have

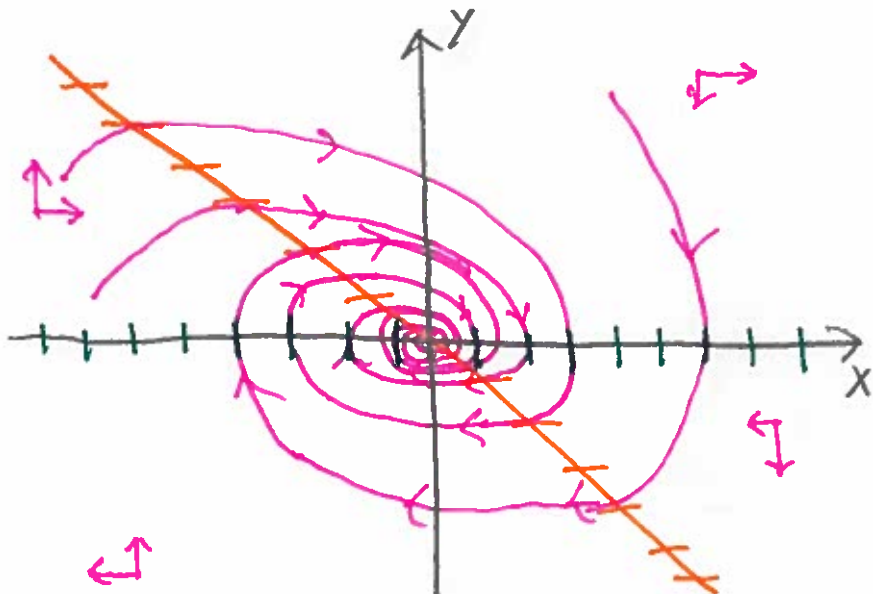
$$N1: v=0, \dot{x}=0$$

$$N2: v = -\frac{k}{b}x, \dot{y}=0$$

Case 1: $b^2 \geq 4mk$



Case 2: $b^2 < 4mk$



#6.2.2

Consider the system

$$\dot{x} = y$$

$$\dot{y} = -x + (1 - x^2 - y^2)y$$

Show that if $|\vec{x}_0| < 1$ then $|\vec{x}(t)| < 1$ for all t .

Solution:

Let $x(t) = \sin(t)$, $y(t) = \cos(t)$. Then,

$$\dot{x}(t) = \cos(t) = y(t)$$

$$\dot{y}(t) = -\sin(t)$$

while

$$-x + (1 - x^2 - y^2)y = -\sin(t) + (1 - \cos^2(t) - \sin^2(t))\cos(t) = -\sin(t)$$

Hence, $\dot{y} = -x + (1 - x^2 - y^2)y$. Therefore, the unit circle is a solution and therefore by existence and uniqueness if $|\vec{x}_0| < 1$ its corresponding solution curve $\vec{x}(t)$ must lie inside the unit circle.