

## Lecture 13: Linearization and Stability

-  $\dot{x} = f(x)$

$x^*$  satisfies  $f(x^*) = 0$  (Equilibrium, Fixed Point).

-  $\dot{x} = \underbrace{f(x^*) + \nabla f|_{x^*}(x - x^*) + o(\|x - x^*\|)}$

Assuming  $f$  is analytic.

Recall:

We say  $g(x) = o(\|x - x^*\|)$  if

$$\lim_{x \rightarrow x^*} \frac{\|g(x)\|}{\|x - x^*\|} = 0$$

(i.e.  $g$  goes to 0 faster than  $\|x - x^*\|$ )

Letting  $y = x - x^*$  the linearized O.D.E is given by  
 $\dot{y} = \nabla f|_{x^*} y.$

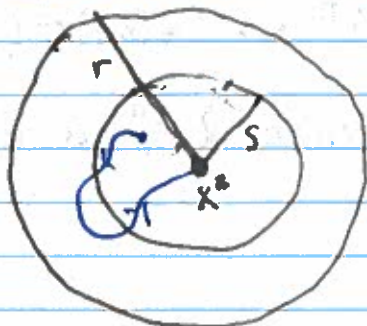
-  $x^*$  is hyperbolic if none of eigenvalues of  $\nabla f|_{x^*}$  have 0 real part.

- Sink (source) if eigenvalues have negative (positive) real parts.

- Saddle: if hyperbolic but not source or sink.

### Stability

- An equilibrium  $x^*$  is Lyapunov stable if for every  $B_r(x^*)$  there exists  $B_s(x^*)$  with  $s < r$  such that if  $x \in B_s(x^*)$  then  $\forall t \in \mathbb{R}^+$   $\gamma(t) \in B_r(x^*)$ .

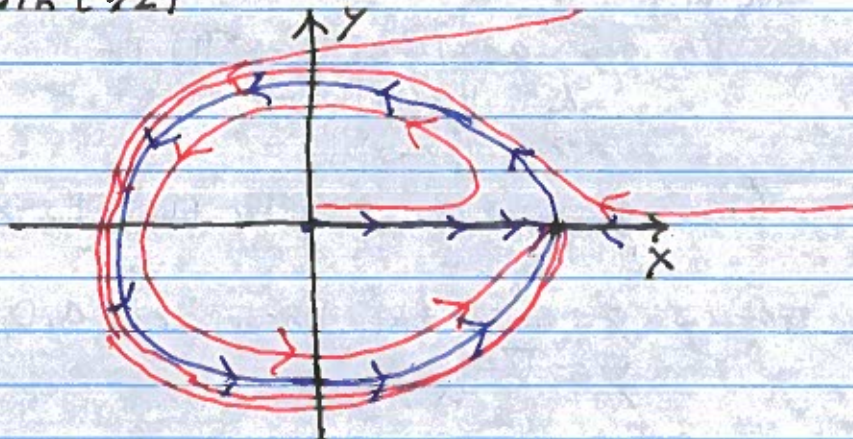


- A fixed point is asymptotically stable if it is Lyapunov stable and there exists  $B_r(x^*)$  such that if  $x \in B_r(x^*)$  then  $\lim_{t \rightarrow \infty} X(t) = x^*$ .

Example:

$$\dot{r} = r(1-r)$$

$$\dot{\theta} = \sin^2(\theta/2)$$



Gronwall's Inequality:

If

$$g(t) \leq c + \int_0^t k(s)g(s)ds,$$

where  $k \geq 0$  then

$$g(t) \leq c e^{\int_0^t k(s)ds}.$$

proof:

Let  $G(t) = c + \int_0^t k(s)g(s)ds$ . Then,

$$G'(t) = k(t)g(t)$$

$$\leq k(t)G(t)$$

$$\Rightarrow G'(t) - k(t)G(t) \leq 0$$

$$\Rightarrow e^{-\int_0^t k(s)ds} (G'(t) - k(t)G(t)) \leq 0$$

$$\Rightarrow \frac{d}{dt} (\exp(-\int_0^t k(s)ds) G(t)) \leq 0$$

$$\Rightarrow G(t) \leq G(0) \exp(-\int_0^t k(s)ds) = c \exp(-\int_0^t k(s)ds).$$

## Main Theorem

Let  $f \in C^1$  and have an equilibrium  $x^*$  such that the linear system

$$\dot{y} = \nabla f(x^*)y$$

is asymptotically stable. Then  $x^*$  is asymptotically stable for the system

$$\dot{x} = f(x).$$

proof:

By construction,  $\dot{x} = f(x)$  is equivalent to

$$\dot{y} = \nabla f(x^*)y + g(y) = Ay + g(y),$$

where  $g(y) = o(y)$ .

$$\Rightarrow y(t) = e^{*A}y_0 + \int_0^t e^{*(t-s)A}g(y(s))ds$$

For simplicity if  $A$  is diagonalizable

$$\begin{aligned}\|e^{*A}\| &= \|\nabla e^{*A}\nabla^{-1}\| \\ &\leq \|\nabla\| \|e^{*\lambda}\| \|\nabla^{-1}\| \\ &\leq e^{-*\lambda}\end{aligned}$$

where  $\lambda^* = \min\{|\lambda_1|, \dots, |\lambda_n|\}$ . Consequently,

$$\|y\| \leq \|y_0\| e^{-*\lambda^*} + e^{-*\lambda^*} \int_0^t e^{s\lambda^*} \|g(y(s))\| ds.$$

If  $\|y_0\| < \delta$  then  $\|g(y(s))\| < \varepsilon \|y\|$ . By continuity  $\|y(t)\| < \delta$  for  $t < \tau$  for some  $\tau$ . Therefore,

$$e^{*\lambda^*} \|y\| \leq \|y_0\| + \varepsilon \int_0^t e^{s\lambda^*} \|y\| ds$$

Define  $y = e^{*\lambda^*} \|y\|$ . By Gronwall's inequality it follows that:

$$\begin{aligned}y &\leq \|y_0\| e^{\varepsilon t} \\ \Rightarrow \|y\| &\leq \|y_0\| e^{-(\lambda^* - \varepsilon)t}\end{aligned}$$

$$\downarrow \\ \therefore \|y\| = 0.$$

$t \rightarrow \infty$