

# MTH 225: Homework #3

Due Date: February 09, 2024

1. Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  be the linear transformation with values

$$T\left(\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -2 \\ 1 \end{bmatrix}, \quad \text{and} \quad T\left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -1 \\ 2 \end{bmatrix}.$$

- (a) Find the matrix  $[T(\mathcal{B}, \mathcal{S}_2)]$  of  $T$  in the bases

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\} \quad \text{and} \quad \mathcal{S}_2 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

where  $[T(\mathcal{B}, \mathcal{S}_2)][\mathbf{v}]_{\mathcal{B}} = [T(\mathbf{v})]_{\mathcal{S}_2}$ .

- (b) Find the matrix  $[T(\mathcal{S}_1, \mathcal{S}_2)]$  of  $T$  in the standard bases

$$\mathcal{S}_1 = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} \quad \text{and} \quad \mathcal{S}_2 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\},$$

where  $[T(\mathcal{S}_1, \mathcal{S}_2)][\mathbf{v}]_{\mathcal{S}_1} = [T(\mathbf{v})]_{\mathcal{S}_2}$ .

2. Consider the two bases  $\mathcal{B}$  and  $\mathcal{S}$  of  $\mathbb{R}^2$  where

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\} \quad \text{and} \quad \mathcal{S} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}.$$

Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the linear transformation defined by

$$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x - 2y \\ 3x + y \end{bmatrix}.$$

- (a) Find the matrix representation of the identity linear transformation  $I : \mathbb{R}^2 \mapsto \mathbb{R}^2$  with respect to the input basis  $\mathcal{B}$  and output basis  $\mathcal{S}$ . That is, find the matrix  $P = [I(\mathcal{B}, \mathcal{S})]$  where  $P[\mathbf{v}]_{\mathcal{B}} = [\mathbf{v}]_{\mathcal{S}}$ .
- (b) Find the matrix representation of the identity linear transformation  $I : \mathbb{R}^2 \mapsto \mathbb{R}^2$  with respect to the input basis  $\mathcal{S}$  and output basis  $\mathcal{B}$ . That is, find the matrix  $Q = [I(\mathcal{S}, \mathcal{B})]$  where  $Q[\mathbf{v}]_{\mathcal{S}} = [\mathbf{v}]_{\mathcal{B}}$ .
- (c) Find the matrix  $A = [T(\mathcal{S}, \mathcal{S})]$ , where  $A[\mathbf{v}]_{\mathcal{S}} = [T(\mathbf{v})]_{\mathcal{S}}$ .
- (d) Find the matrix  $B = [T(\mathcal{S}, \mathcal{B})]$ , where  $B[\mathbf{v}]_{\mathcal{S}} = [T(\mathbf{v})]_{\mathcal{B}}$ .
- (e) Write  $B$  as a product of  $A$  and any of the matrices  $P$  and  $Q$  that are relevant.

3. Let  $T : P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$  be the linear transformation defined by  $T(a + bx + cx^2) = (a + c) + bx^2$ . Let  $\mathcal{S} = \{1, x, x^2\}$  be the standard basis of  $P_2(\mathbb{R})$ , and let  $\mathcal{B} = \{1 + x, x, 1 + x^2\}$  be another basis.

- (a) Find the matrix  $[T(\mathcal{S}, \mathcal{S})]$  of  $T$  with respect to  $\mathcal{S}$ .
- (b) Find the matrix  $[T(\mathcal{B}, \mathcal{B})]$  of  $T$  with respect to  $\mathcal{B}$ .
- (c) Find an invertible matrix  $P$  so that  $P[T(\mathcal{B}, \mathcal{B})]P^{-1} = [T(\mathcal{S}, \mathcal{S})]$ .

4. Suppose  $\mathbf{v} \in V$  is a vector in some vector space  $V$  and  $T : V \rightarrow V$  a linear transformation such that  $\mathcal{B} = \{\mathbf{v}, T(\mathbf{v}), T^2(\mathbf{v}), \dots, T^{n-1}(\mathbf{v})\}$  is a basis for  $V$ .
- Show that there exists constants  $a_0, a_1, \dots, a_{n-1} \in \mathbb{R}$  such that
$$T^n(\mathbf{v}) = a_0\mathbf{v} + a_1T(\mathbf{v}) + \dots + a_{n-1}T^{n-1}(\mathbf{v}).$$
  - Find the matrix  $[T(\mathcal{B}, \mathcal{B})]$  of  $T$  with respect to  $\mathcal{B}$ .
  - When does  $T$  map onto  $V$  and when is  $T$  one-to-one?
  - Find the characteristic polynomial  $c_T(x)$  of  $T$ . (Hint: Do cases  $n = 2$  and  $3$  to get a conjecture and prove it by induction).
5. Suppose that the vector  $v = (1, 1) \in \mathbb{R}^2$  is an eigenvector of  $A \in \text{Mat}_{2 \times 2}(\mathbb{R})$  corresponding to the eigenvector  $\lambda$ . Draw on a graph the vectors  $v$  and  $Av$  for each of the following cases. (Make a separate graph for each part.)
- $\lambda > 1$ .
  - $\lambda = 1$ .
  - $0 < \lambda < 1$ .
  - $\lambda = 0$ .
  - $-1 < \lambda < 0$ .
  - $\lambda = -1$ .
  - $\lambda < -1$ .
6. Prove that  $0$  is an eigenvalue of  $T$  if and only if  $\text{Ker}(T)$ , the nullspace of  $T$ , is  $\neq \{0\}$ .
7. If  $\lambda$  is an eigenvalue for an  $n \times n$  matrix  $A$ , show that  $\lambda^2$  is an eigenvalue for  $A^2$ . More generally prove that if  $f(x)$  is any polynomial with coefficients in  $\mathbb{R}$ , then  $f(\lambda)$  is an eigenvalue for  $f(A)$ .
8. A matrix  $N$  is called *nilpotent* if  $N^k = 0$  for some positive integer  $k$ . Prove that the only possible eigenvalue of a nilpotent matrix is  $0$ .

Homework #3

#1

Solution:

$$(a) \text{ Since } T\left(\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, T\left(\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}, T\left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

it follows that

$$[T(\beta, S_2)] = \begin{bmatrix} 1 & -2 & -1 \\ 2 & 1 & 2 \end{bmatrix}$$

(b) Suppose

$$c_1 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 \end{bmatrix} - R1 \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 \end{bmatrix} - R2 \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 2 & 1 & -1 & 1 & 0 \end{bmatrix}/2$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & 0 \end{bmatrix} - R3 \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & 1 & 0 & -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\Rightarrow T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \frac{1}{2} \end{bmatrix}$$

$$T\left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}\right) = -\frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ \frac{1}{2} \end{bmatrix}$$

$$\Rightarrow [T(\beta, S_2)] = \begin{bmatrix} 1 & 0 & -2 \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

#2

$$\beta = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}, S = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}, T \left( \begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} x-2y \\ 3x+y \end{bmatrix}$$

Solution:

(a)  $I \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, I \left( \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$$\Rightarrow [I(\beta, S)] = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = P$$

(b)  $I \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$$I \left( \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\Rightarrow [I(S, \beta)] = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} = Q$$

(c)  $T \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, T \left( \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

$$\Rightarrow [T(S, \beta)] = \begin{bmatrix} 1 & -2 \\ 3 & 1 \end{bmatrix} = A$$

(d)  $c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

$$\Rightarrow \left[ \begin{array}{cc|cc} 1 & -1 & 1 & -2 \\ 1 & 1 & 3 & 1 \end{array} \right] \xrightarrow{-R_1} \left[ \begin{array}{cc|cc} 1 & -1 & 1 & -2 \\ 0 & 2 & 2 & 3 \end{array} \right] \xrightarrow{\frac{1}{2}R_2} \left[ \begin{array}{cc|cc} 1 & -1 & 1 & -2 \\ 0 & 1 & 1 & \frac{3}{2} \end{array} \right] + R_2$$

$$\Rightarrow \left[ \begin{array}{cc|cc} 1 & 0 & 2 & -\frac{1}{2} \\ 0 & 1 & 1 & \frac{3}{2} \end{array} \right]$$

$$\Rightarrow [T(S, \beta)] = \begin{bmatrix} 2 & -\frac{1}{2} \\ 1 & \frac{3}{2} \end{bmatrix} = B.$$

(e) Since  $[T(S, \beta)] = [I(S, \beta)][T(S, S)]$  it follows that

$$B = Q \cdot A$$

#3

Let  $T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$  be the linear transformation defined by  $T(ax+bx^2+cx^3) = (a+c)+bx^2$ . Let  $S = \{1, x, x^2\}$  be the standard basis of  $P_2(\mathbb{R})$  and  $\beta = \{1+x, x, 1+x^2\}$  be another basis.

(a) Find  $[T(S, S)]$ .

(b) Find  $[T(\beta, \beta)]$ .

(c) Find an invertible matrix  $P$  so that  $P[T(\beta, \beta)]P^{-1} = [T(S, S)]$ .

Solution:

(a)  $T(1) = 1, T(x) = x^2, T(x^2) = 1$

$$\Rightarrow [T(S, S)] = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

(b).  $T(1+x) = 1+x^2, T(x) = x^2, T(1+x^2) = 2$ . Since

$$1+x^2 = 0 \cdot (1+x) + 0 \cdot x^2 + 1 \cdot (1+x^2)$$

$$x^2 = -1 \cdot (1+x) + 1 \cdot x + 1 \cdot (1+x^2)$$

$$2 = 2 \cdot (1+x) - 2 \cdot x + 0 \cdot (1+x^2)$$

it follows that

$$[T(\beta, \beta)] = \begin{bmatrix} 0 & -1 & 2 \\ 0 & 1 & -2 \\ 1 & 1 & 0 \end{bmatrix}$$

(c). Since  $[I(\beta, S)][T(\beta, \beta)][I(S, \beta)] = [T(S, S)]$  it follows that  $P = [I(\beta, S)]$ . Now,

$$I(1+x) = 1+x, I(x) = x, I(1+x^2) = 1+x^2$$

$$\Rightarrow P = [I(\beta, S)] = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

#4.

Suppose  $\vec{v} \in V$  is a vector in some vector space  $V$  and  $T: V \rightarrow V$  a linear transformation such that  $\beta = \{\vec{v}, T(\vec{v}), T^2(\vec{v}), \dots, T^{n-1}(\vec{v})\}$  is a basis for  $V$ .

(a) Show that there exists constants  $a_0, a_1, \dots, a_{n-1} \in \mathbb{R}$  such that

$$T^n(\vec{v}) = a_0 \vec{v} + \dots + a_{n-1} T^{n-1}(\vec{v})$$

(b) Find the matrix  $[T(\beta, \beta)]$ .

(c) When does  $T$  map onto  $V$  and when is  $T$  one-to-one.

(d) Find the characteristic polynomial  $C_T(x)$  of  $T$ .

Solution:

(a) Since  $T^{(n)}(\vec{v}) \in V$  and  $\beta$  is a basis there exists  $a_0, \dots, a_{n-1}$  such that

$$T^{(n)}(\vec{v}) = a_0 \vec{v} + \dots + a_{n-1} T^{n-1}(\vec{v}).$$

(b). Since  $T(\vec{v}) = T(\vec{v})$ ,  $T(T(\vec{v})) = T^2(\vec{v})$ , ...,  $T(T^{n-1}(\vec{v})) = T^n(\vec{v})$  it follows that

$$[T(\beta, \beta)] = \begin{bmatrix} 0 & 0 & \dots & 0 & a_0 \\ 1 & 0 & \dots & 0 & a_1 \\ 0 & 1 & \dots & \vdots & \vdots \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & a_{n-2} \\ 0 & 0 & \dots & 1 & a_{n-1} \end{bmatrix}$$

(c) Since  $\det([T(\beta, \beta)]) = (-1)^{n+1} a_0$  it follows that  $[T(\beta, \beta)]$  is one-to-one and onto if and only if  $a_0 \neq 0$ .

(d) For  $n=2$  we have

$$[T(\beta, \beta)] = \begin{bmatrix} 0 & a_0 \\ 1 & a_1 \end{bmatrix} \Rightarrow \det(\lambda I - [T(\beta, \beta)]) = \det \begin{pmatrix} \lambda & -a_0 \\ -1 & \lambda - a_1 \end{pmatrix} = \lambda(\lambda - a_1) - a_0$$

For  $n=3$  we have

$$\begin{aligned} [T(\beta, \beta)] &= \begin{bmatrix} 0 & 0 & a_0 \\ 1 & 0 & a_1 \\ 0 & 1 & a_2 \end{bmatrix} \Rightarrow \det(\lambda I - [T(\beta, \beta)]) = \det \begin{pmatrix} \lambda & 0 & -a_0 \\ -1 & \lambda & -a_1 \\ 0 & -1 & \lambda - a_2 \end{pmatrix} \\ &= \lambda(\lambda(\lambda - a_2) - a_1) - a_0 \\ &= \lambda^3 - a_2 \lambda^2 - a_1 \lambda - a_0 \end{aligned}$$

#6.

Prove that 0 is an eigenvalue of T if and only if  $\ker(T) \neq \{0\}$ .

Solution:

( $\Rightarrow$ ) If 0 is an eigenvalue of T then there exists  $\vec{v} \in V$  such that  $T\vec{v} = 0 \cdot \vec{v} \Rightarrow \vec{v} \in \ker(T)$ .

( $\Leftarrow$ ) If  $\vec{v} \in \ker(T)$  then  $T\vec{v} = 0 = 0 \cdot \vec{v}$  and thus 0 is an eigenvalue of T. ■

#8

A matrix N is called nilpotent if  $N^k = 0$  for some positive integer k. Prove that the only possible eigenvalue of a nilpotent matrix is 0.

Solution:

Let  $\lambda$  be an eigenvalue of N with eigenvector  $\vec{v}$ . Therefore,

$$N\vec{v} = \lambda\vec{v}$$

$$\Rightarrow N^k\vec{v} = \lambda^k\vec{v} = 0 = 0 \cdot \vec{v}$$

$$\Rightarrow \lambda = 0.$$