

Lecture 13: Square Roots and Exponentials

Definition - $A \in M_{n \times n}(\mathbb{C})$ is called positive semidefinite if A is Hermitian and for all $\vec{v} \in \mathbb{C}^n$

$$\vec{v}^* A \vec{v} \geq 0.$$

A is called positive definite if $\vec{v}^* A \vec{v} = 0 \Leftrightarrow \vec{v} = 0$.

Theorem: If $A \in M_{n \times n}(\mathbb{C})$ is positive definite then the mapping $\langle \cdot, \cdot \rangle_A$ defined by

$$\langle \vec{x}, \vec{y} \rangle_A = \langle \vec{x}, A \vec{y} \rangle$$

is an inner product.

proof:

$$\begin{aligned} 1. \langle \vec{x}, \vec{y} \rangle_A &= \langle \vec{x}, A \vec{y} \rangle \\ &= \langle A \vec{y}, \vec{x} \rangle \\ &= \langle \vec{y}, A \vec{x} \rangle \\ &= \langle \vec{y}, \vec{x} \rangle_A \end{aligned}$$

$$\begin{aligned} 2. \langle \vec{x} + \vec{y}, \vec{z} \rangle_A &= \langle \vec{x} + \vec{y}, A \vec{z} \rangle \\ &= \langle \vec{x}, A \vec{z} \rangle + \langle \vec{y}, A \vec{z} \rangle \\ &= \langle \vec{x}, \vec{z} \rangle_A + \langle \vec{y}, \vec{z} \rangle_A \end{aligned}$$

$$\begin{aligned} 3. \langle \lambda \vec{x}, \vec{y} \rangle_A &= \langle \lambda \vec{x}, A \vec{y} \rangle \\ &= \lambda \langle \vec{x}, A \vec{y} \rangle \\ &= \lambda \langle \vec{x}, \vec{y} \rangle_A. \end{aligned}$$

$$\begin{aligned} 4. \langle \vec{x}, \vec{x} \rangle_A &= \langle \vec{x}, A \vec{x} \rangle \\ &\geq 0. \end{aligned}$$

Theorem - Let A be positive semidefinite with diagonalizer

$$A = U D U^*.$$

Then $\sqrt{A} = U D^{1/2} U^*$.

proof:

$$\sqrt{A} \cdot \sqrt{A} = U D^{1/2} U^* U D^{1/2} U^* = U D^{1/2} D^{1/2} U^* = U D U^*.$$

Polar Form - Let $A \in M_{n \times n}(\mathbb{C})$. Then there exists a unitary $Q \in M_{n \times n}(\mathbb{C})$ such that

$$A = Q \sqrt{A^* A}$$

proof:

Let A have the SVD, $A = U \Sigma V^*$. Let $Q = UV^*$ and $M = V \Sigma V^*$

$$\Rightarrow QM = UV^* V \Sigma V^* = U \Sigma V^* = A$$

Furthermore,

$$M^2 = V \Sigma V^* V \Sigma V^* = V \Sigma^2 V^* = A^* A$$

$$\Rightarrow \sqrt{A^* A} = M.$$

Definition - If $A \in M_{n \times n}(\mathbb{C})$ then

$$\exp(A) = I + A + \frac{1}{2!} A^2 + \frac{1}{3!} A^3 + \frac{1}{4!} A^4 + \dots$$

Example:

$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$

Find $\exp(A)$. We can diagonalize to simplify this process

$$\text{Tr}(A) = 2 + 2 = \lambda_1 + \lambda_2$$

$$\Rightarrow \lambda_1 + \lambda_2 = 4$$

$$\det(A) = 5 = \lambda_1 \lambda_2$$

$$\Rightarrow \lambda_1 = 4 - \lambda_2$$

$$\Rightarrow 5 = (4 - \lambda_2) \lambda_2$$

$$\Rightarrow 5 = 4\lambda_2 - \lambda_2^2$$

$$\Rightarrow \lambda_2^2 - 4\lambda_2 + 5 = 0$$

$$\Rightarrow \lambda_2 = \frac{4 \pm \sqrt{16 - 20}}{2}$$

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$$= 2 \pm i$$

$$\lambda_1 = 2 + i$$

$$\lambda_1 I - A = \begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \xrightarrow{-iR_1} \begin{bmatrix} i & 1 \\ 0 & 0 \end{bmatrix} \Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$\lambda_2 = 2 - i$$

$$\lambda_2 I - A = \begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \xrightarrow{+iR_1} \begin{bmatrix} -i & 1 \\ 0 & 0 \end{bmatrix} \Rightarrow \vec{v}_2 = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$\text{Now, } A = V \Lambda V^{-1}$$

$$\Rightarrow \exp(A) = I + V \Lambda V^{-1} + \frac{1}{2!} V \Lambda^2 V^{-1} + \frac{1}{3!} V \Lambda^3 V^{-1} + \dots$$

$$= V (I + \Lambda + \frac{1}{2!} \Lambda^2 + \frac{1}{3!} \Lambda^3 + \dots) V^{-1}$$

$$= V \begin{pmatrix} 1 + \lambda_1 + \frac{1}{2!} \lambda_1^2 + \frac{1}{3!} \lambda_1^3 + \dots & 0 \\ 0 & 1 + \lambda_2 + \frac{1}{2!} \lambda_2^2 + \frac{1}{3!} \lambda_2^3 + \dots \end{pmatrix} V^{-1}$$

$$= V \begin{pmatrix} e^{\lambda_1} & 0 \\ 0 & e^{\lambda_2} \end{pmatrix} V^{-1}$$

$$= \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} e^{2+i} & 0 \\ 0 & e^{2-i} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}^{-1}$$

$$= e^2 \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} e^i & 0 \\ 0 & e^{-i} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}^{-1}$$

$$= e^2 \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} \cos(1) + i \sin(1) & 0 \\ 0 & \cos(1) - i \sin(1) \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & i \\ 1 & -i \end{bmatrix}$$

$$= \frac{e^2}{2} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} \cos(1) + i \sin(1) & i \cos(1) - \sin(1) \\ \cos(1) - i \sin(1) & -i \cos(1) - \sin(1) \end{bmatrix}$$

$$= \frac{e^2}{2} \begin{bmatrix} 2 \cos(1) & -2 \sin(1) \\ 2 \sin(1) & 2 \cos(1) \end{bmatrix}$$

$$= \begin{bmatrix} e^2 \cos(1) & -e^2 \sin(1) \\ e^2 \sin(1) & e^2 \cos(1) \end{bmatrix}$$

Theorem - If U is unitary, then $U = e^{iH}$ for some Hermitian matrix H .

Proof:

Since U is ^{unitarily} diagonalizable with eigenvalues λ_j satisfying $|\lambda_j| = 1$, there exists θ_j such that $\lambda_j = e^{i\theta_j}$. Therefore,

$$\begin{aligned} U &= R \Lambda R^* \\ &= R \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} R^* \\ &= R \begin{pmatrix} e^{i\theta_1} & & 0 \\ & \ddots & \\ 0 & & e^{i\theta_n} \end{pmatrix} R^* \end{aligned}$$

$$= \exp \left(R \begin{bmatrix} i\theta_1 & & 0 \\ & \ddots & \\ 0 & & i\theta_n \end{bmatrix} R^* \right)$$

$$= \exp \left(i R \begin{bmatrix} \theta_1 & & 0 \\ & \ddots & \\ 0 & & \theta_n \end{bmatrix} R^* \right)$$

$$\Rightarrow H = R \begin{bmatrix} \theta_1 & & 0 \\ & \ddots & \\ 0 & & \theta_n \end{bmatrix} R^*$$

Theorem - Let A be an $n \times n$ matrix with complex entries. There exists a Hermitian matrix H such that

$$A = e^{iH} \sqrt{A^* A}$$