

Homework 6

Mathematical Modeling

Due: October 24, 2018

1 Problems for Everybody

1. Consider the following system of differential equations in Cartesian coordinates

$$\begin{cases} \dot{x} = f(x, y) \\ \dot{y} = g(x, y) \end{cases} .$$

Show that if the system is converted to polar coordinates (r, θ) that

$$\begin{cases} \dot{r} = \cos(\theta)\dot{x} + \sin(\theta)\dot{y} \\ \dot{\theta} = r^{-1}(\cos(\theta)\dot{y} - \sin(\theta)\dot{x}) \end{cases}$$

Hint: Start with the relationships $r^2 = x^2 + y^2$ and $\tan(\theta) = y/x$ and differentiate with respect to time.

2. Consider the following system of differential equations in polar coordinates

$$\begin{cases} \dot{r} = f(r, \theta) \\ \dot{\theta} = g(r, \theta) \end{cases} .$$

Show that if the system is converted to Cartesian coordinates (x, y) that

$$\begin{cases} \dot{x} = \frac{x}{\sqrt{x^2 + y^2}}\dot{r} - y\dot{\theta} \\ \dot{y} = \frac{y}{\sqrt{x^2 + y^2}}\dot{r} + x\dot{\theta} \end{cases} .$$

3. Consider the following system in polar coordinates

$$\begin{cases} \dot{r} = -r \\ \dot{\theta} = \frac{1}{\ln(r)} \end{cases} .$$

- (a) Show that $r(t) \rightarrow 0$ as $t \rightarrow \infty$ and $|\theta(t)| \rightarrow \infty$ as $t \rightarrow \infty$.
(b) Convert this system to Cartesian coordinates.
(c) Show that the linearized system predicts that the origin is a stable star. However, based off of part (a) how would you classify the origin?
4. Consider the system $\dot{x} = -y - x^3$ and $\dot{y} = x$. Show that the origin is a spiral, although the linearization predicts a center.

5. Consider the system $\ddot{x} = x - x^2$.
 - (a) Find and classify the fixed points.
 - (b) Sketch the phase portrait.
 - (c) Find an equation for the homoclinic orbit that separates closed and nonclosed trajectories.
6. Sketch the phase portrait for the system $\ddot{x} = ax - x^2$ for $a < 0$, $a = 0$, and $a > 0$.
7. Plot the phase portraits of the following gradient systems $\dot{\mathbf{x}} = -\nabla V(\mathbf{x})$.
 - (a) $V = x^2 + y^2$
 - (b) $V = x^2 - y^2$
 - (c) $V = e^x \sin(y)$
8. Show that the system $\dot{x} = y - x^3$, $\dot{y} = -x - y^3$ has no closed orbits, by constructing a Liapunov function $V = ax^2 + by^2$ with suitable a, b .
9. Consider the system $\dot{x} = x^2 - y - 1$, $\dot{y} = y(x - 2)$.
 - (a) Show that there are three fixed points and classify them.
 - (b) By considering three straight lines through pairs of fixed points, show that there are no closed orbits.
 - (c) Sketch the phase portrait.

2 Problems for MST 651 students only. Students in MST 351 can complete these problems for extra credit

1. Consider a glider flying at speed v at an angle θ to the horizontal. Its motion is governed by the dimensionless equations:

$$\begin{cases} \dot{v} = -\sin(\theta) - Dv^2 \\ v\dot{\theta} = -\cos(\theta) + v^2 \end{cases},$$

where the trigonometric terms represent the effects of gravity and the v^2 terms represent the effect of drag.

- (a) Suppose there is no drag ($D = 0$). Show that $v^3 - 3v \cos(\theta)$ is a conserved quantity. Sketch the phase portrait in this case and interpret your results. What does the flight path of the glider look like?
- (b) Investigate the case of positive drag ($D > 0$).