

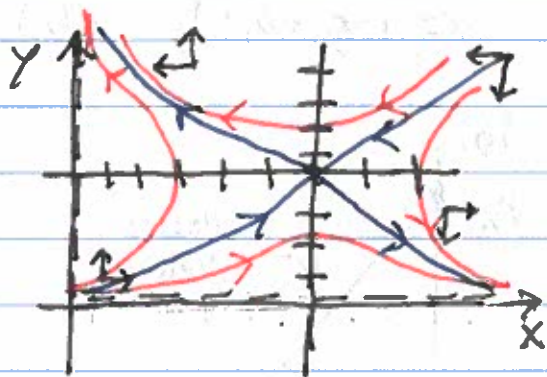
## Lecture 14: Lotka Volterra Systems

### Competition -

$\dot{x} = r_x x - a_x xy$ , species  $x$  and  $y$  have infinite resources  
 $\dot{y} = r_y y - a_y xy$  but are hostile to each other.

### Nullclines

1.  $\dot{x} = 0 \Rightarrow x = 0, y = r_x/a_x$
2.  $\dot{y} = 0 \Rightarrow y = 0, x = r_y/a_y$



### Jacobian

$$J = \begin{bmatrix} r_x - a_x y & -a_x x \\ -a_y y & r_y - a_y x \end{bmatrix}$$

$$J(0,0) = \begin{bmatrix} r_x & 0 \\ 0 & r_y \end{bmatrix} \Rightarrow \lambda_1 = r_x, \lambda_2 = r_y \text{ origin is unstable.}$$

$$J(r_y/a_y, r_x/a_x) = \begin{bmatrix} 0 & -r_y a_x/a_y \\ -r_x a_y/a_x & 0 \end{bmatrix} \Rightarrow \lambda_1, \lambda_2 = \pm \sqrt{r_x r_y} \Rightarrow \text{saddle.}$$

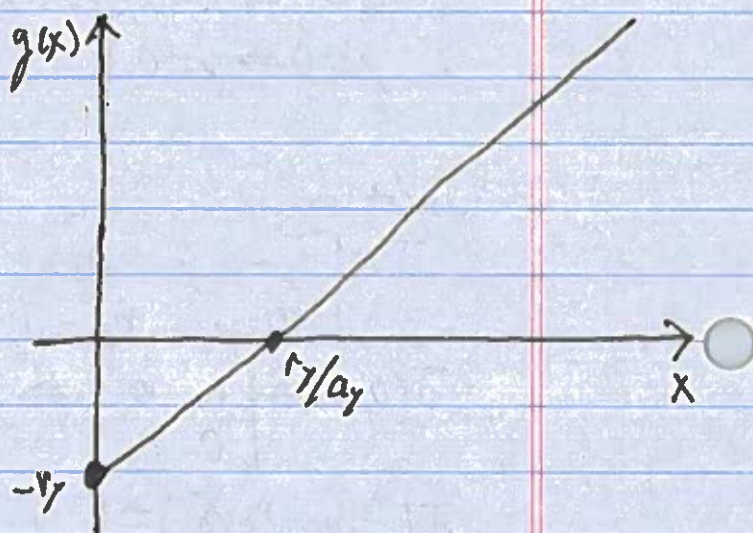
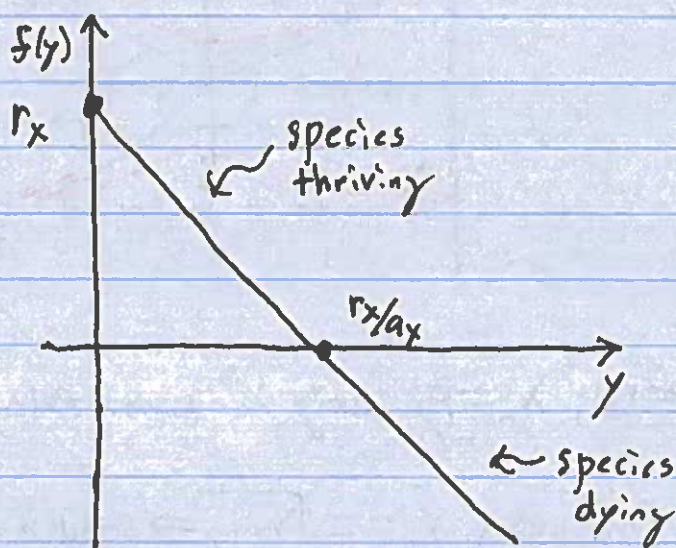
Hartmann-Grobman Theorem - If the Jacobian at a fixed point  $\bar{x}^*$  has eigenvalues with nonzero imaginary part, then  $\dot{\bar{x}} = F(\bar{x})$  is locally equivalent to  $\dot{\bar{x}} = J(\bar{x})$  near  $\bar{x}^*$ .

## Predator-Prey -

$\dot{x} = r_x x - a_x x y$ , species  $x$  grows without bound without species  $y$  but is preyed upon by species  $y$ . Species  $y$  undergoes pure death without species  $x$  and preys on species  $x$ .

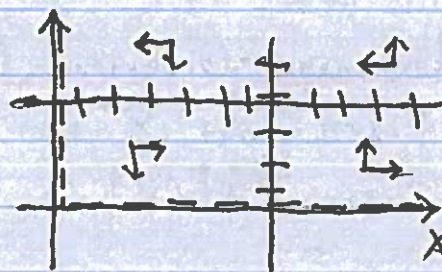
$\dot{y} = -r_y y + a_y x y$

$\Rightarrow \dot{x} = (r_x - a_x y) x = f(y) x \Rightarrow f, g$  are species dependent growth rates.  
 $\dot{y} = (-r_y + a_y x) y = g(x) y$



## Nullclines:

1.  $\dot{x} = 0, x = 0, y = r_x/a_x$
2.  $\dot{y} = 0, y = 0, x = r_y/a_y$



$$J(x, y) = \begin{bmatrix} r_x - a_x y & -a_x x \\ a_y y & -r_y + a_y x \end{bmatrix}$$

$\Rightarrow J(r_y/a_y, r_x/a_x) = \begin{bmatrix} 0 & -r_y a_y/a_x \\ r_x a_y/a_x & 0 \end{bmatrix} \Rightarrow \lambda_{1,2} = \pm i \sqrt{r_x r_y} \Rightarrow$  The linearization tells us nothing.

\* We need to do more work to deduce stability.

For this problem we have:

$$\frac{dy}{dx} = \frac{\dot{y}}{\dot{x}} = \frac{(-r_y + a_y x)y}{(r_x - a_x y)x}$$

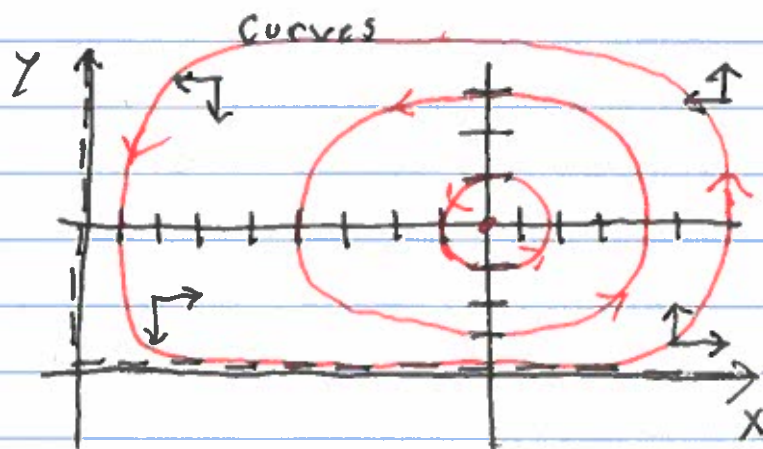
$$\Rightarrow \frac{(r_x - a_x y)}{y} \frac{dy}{dx} = \frac{(-r_y + a_y x)}{x}$$

$$\Rightarrow \int \left( \frac{r_x}{y} - a_x \right) dy = \int \left( \frac{-r_y}{x} + a_y \right) dx$$

$$\Rightarrow r_x h(y) - a_x y = -r_y h(x) + a_y x + E$$

$$\Rightarrow E(x, y) = r_x h(y) + r_y h(x) - a_x y - a_y x$$

level sets of this function correspond to solution



Nonlinear centers.