

Lecture 10: Numerical Solutions to the Wave Equation.

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

$$u(t, 0) = \alpha(x)$$

$$u(t, l) = \beta(x)$$

$$u(0, x) = f(x)$$

$$u_t(0, x) = g(x)$$

Discretization:

$$t_j = j \Delta t \quad x_i = i \Delta x$$

$$u_{tt}(t_j, x_i) = \frac{u_{j+1,i} - 2u_{j,i} + u_{j-1,i}}{\Delta t^2}$$

$$u_{xx}(t_j, x_i) = \frac{u_{j,i+1} - 2u_{j,i} + u_{j,i-1}}{\Delta x^2}$$

$$\Rightarrow u_{j+1,i} = \frac{\Delta t^2}{c^2 \Delta x^2} (u_{j,i+1} - 2u_{j,i} + u_{j,i-1}) + 2u_{j,i} - u_{j-1,i}$$

The CFL condition is

$$\frac{\Delta t}{c \Delta x} < 1$$

Initialization:

The above scheme does not work when $j=1$.

One idea is to use the derivative to approximate $u_{2,i}$:

$$\left. \frac{du}{dt} \right|_{t=0} = \frac{u_{2,i} - u_{1,i}}{\Delta t} + \mathcal{O}(\Delta t) = g(x_i)$$

$$\Rightarrow u_{2,i} = \Delta t g(x_i) + u_{1,i}$$

However, this is a $\mathcal{O}(\Delta t)$ approximation, not $\mathcal{O}(\Delta t^2)$.

Alternative:

$$\frac{u(\Delta t, x_i) - u(0, x_i)}{\Delta t} = \frac{du(0, x_i)}{dt} + \frac{1}{2} \frac{d^2 u(0, x_i)}{dt^2} \Delta t + O(\Delta t^2)$$

$$= g(x_m) + \frac{c^2}{2} \frac{d^2 u(0, x_i)}{dx^2} \Delta t + O(\Delta t^2)$$

$$= g(x_m) + \frac{c^2}{2} f''(x_i) \Delta t + O(\Delta t^2)$$

$$\Rightarrow u_{2,i} = u_{1,i} + \Delta t g(x_m) + \frac{c^2 \Delta t^2}{2} f''(x_i)$$

In vector notation

$$\vec{u}_1 = f(x)$$

$$\vec{u}_2 = \vec{u}_1 + \Delta t g(x) + \frac{c^2 \Delta t^2}{2} f''(x)$$

$$\vec{u}_{j+1} = \frac{\Delta t^2}{c^2 \Delta x^2} D \vec{u}_j + 2\vec{u}_j - \vec{u}_{j-1}$$

$$D = \begin{bmatrix} -2 & 1 & 0 & \cdots & 0 & 0 & 0 \\ 1 & -2 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 1 & -2 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -2 & 1 & 0 \\ 0 & 0 & 0 & \cdots & 1 & -2 & 1 \\ 0 & 0 & 0 & \cdots & 0 & 1 & -2 \end{bmatrix}$$