

Lecture 5: Complex and Repeated Eigenvalues

Complex Eigenvalues:

$$A \in \mathbb{R}^{n \times n}$$

1. If $\lambda = a + ib$ is an eigenvalue then $\lambda^* = a - ib$ is also an eigenvalue.

proof:

The operation $*$ satisfies $(\lambda^n)^* = (\lambda^*)^n$ thus for any polynomial

$$p(\lambda^*) = p(\lambda)^*$$

2. If \vec{v} is an eigenvector so is \vec{v}^* .

"Diagonalization by rotations"

Suppose $\lambda = a + ib$, $\vec{v} = \vec{u} + i\vec{w}$

$$\Rightarrow A\vec{v} = \lambda\vec{v}$$

$$\Rightarrow A(\vec{u} + i\vec{w}) = (a + ib)(\vec{u} + i\vec{w})$$

$$\Rightarrow A\vec{u} = a\vec{u} - b\vec{w} \Rightarrow \text{span}\{\vec{u}, \vec{w}\} \text{ is invariant.}$$

$$A\vec{w} = b\vec{u} + a\vec{w}$$

$$\Rightarrow A[\vec{u} | \vec{w}] = [\vec{u} | \vec{w}] \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

Exponential of "Rotation":

$$A = \begin{bmatrix} a & -b \\ b & a \end{bmatrix} = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix} + \begin{bmatrix} 0 & -b \\ b & 0 \end{bmatrix}$$

$$= a \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}_{\mathbf{I}} + b \underbrace{\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}}_{\sigma} \rightsquigarrow \text{rotation}$$

$$\Rightarrow [a\mathbf{I}, b\sigma] = ab\sigma - ab\sigma = 0$$

$$\Rightarrow \exp(A) = \exp(a\mathbf{I})\exp(b\sigma)$$

Note:

$$\sigma^2 = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} = -\mathbf{I} \quad (\sigma \sim i)$$

Multiple Eigenvalues:

- If λ_j is an eigenvalue of A with algebraic multiplicity n_j , the generalized eigenspace of λ_j is:

$$E_j = \text{NS}[(A - \lambda_j I)^{n_j}]$$

- A space E is invariant under T if for all $v \in E$, $T(v) \in E$.

- E_j is invariant.

proof:

Suppose $v \in E_j$
 $\Rightarrow (A - \lambda_j I)^{n_j} v = 0$

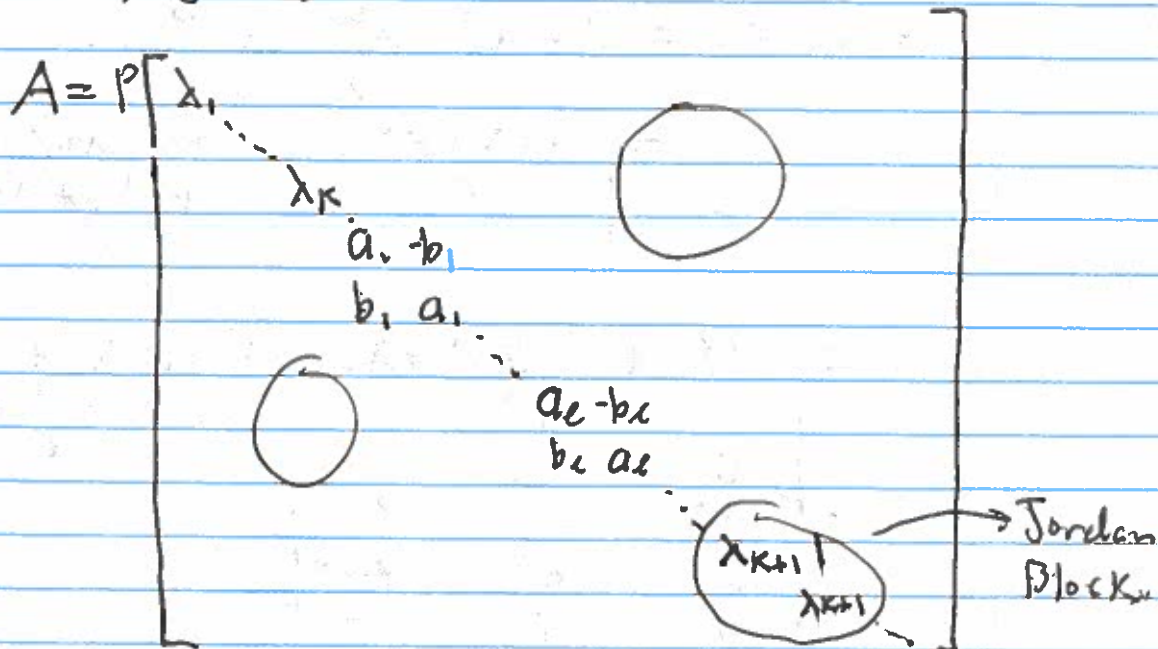
Now,

$$(A - \lambda_j I)^{n_j} A v = A (A - \lambda_j I)^{n_j} v = 0.$$

- A generalized eigenvector satisfies $(T - \lambda_j I)^{n_j} v_j = 0$ where n_j is the algebraic multiplicity.

Jordan Canonical Form -

$$\vec{x}(t) = e^{*A} \vec{x}_0$$



Suppose $J = \lambda I + N$,

$$N = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \quad \lambda I = \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}, \quad J = \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{bmatrix}$$

$$N^2 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad N^3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$[\lambda I, N] = 0$$

$$\begin{aligned} \Rightarrow J^2 &= (\lambda I + N)^2 \\ &= \lambda^2 I + 2\lambda N + N^2 \\ &= \begin{bmatrix} \lambda^2 & 2\lambda & 0 \\ 0 & \lambda^2 & 2\lambda \\ 0 & 0 & \lambda^2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} J^3 &= (\lambda I + N)^3 \\ &= \lambda^3 I + 3\lambda^2 N + 3\lambda N^2 \end{aligned}$$

$$J^4 = (\lambda I + N)^4 = \lambda^4 I + 4\lambda^3 N + 6\lambda^2 N^2$$

$$\Rightarrow \exp(tJ) = I + tJ + \frac{t^2 J^2}{2} + \frac{t^3 J^3}{6} + \dots$$

$$= \begin{bmatrix} 1 + t\lambda + \frac{t^2 \lambda^2}{2} + \dots & t + 2\lambda \frac{t^2}{2} + 3\lambda^2 \frac{t^3}{6} + \dots & \frac{t^2}{2} + 3\lambda \frac{t^3}{6} + \dots \\ 0 & 1 + t\lambda + \frac{t^2 \lambda^2}{2} + \dots & t + 2\lambda \frac{t^2}{2} + 3\lambda^2 \frac{t^3}{6} + \dots \\ 0 & 0 & 1 + t\lambda + \frac{t^2 \lambda^2}{2} + \dots \end{bmatrix}$$

$$= \begin{bmatrix} e^{\lambda t} & t(1 + \frac{t\lambda}{2} + \frac{t^2 \lambda^2}{6} + \dots) & \frac{t^2}{2}(1 + \lambda t + \dots) \\ 0 & e^{\lambda t} & t(1 + \frac{t\lambda}{2} + \frac{t^2 \lambda^2}{6} + \dots) \\ 0 & 0 & e^{\lambda t} \end{bmatrix}$$

$$= \begin{bmatrix} e^{\lambda t} & t e^{\lambda t} & \frac{t^2}{2} e^{\lambda t} \\ 0 & e^{\lambda t} & t e^{\lambda t} \\ 0 & 0 & e^{\lambda t} \end{bmatrix}$$