

Lecture 6: Coordinates and Change of Basis

Example:

$$\text{Let } S_1 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}, \beta_1 = \left\{ \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \end{bmatrix} \right\}$$

$$S_2 = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}, \beta_2 = \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \right\}$$

$$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} y \\ -5x+13y \\ -7x+16y \end{bmatrix}$$

1. Let $\vec{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. What is $[\vec{v}]_{\beta_1}$?

$$\Rightarrow \vec{v} = c_1 \begin{bmatrix} 3 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 5 \\ 2 \end{bmatrix}$$

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Coordinates

$$\Rightarrow \left[\begin{array}{cc|c} 3 & 5 & 1 \\ 1 & 2 & 1 \end{array} \right] \xrightarrow{-3R2} \left[\begin{array}{cc|c} 0 & -1 & -2 \\ 1 & 2 & 1 \end{array} \right] \xrightarrow{+2R1} \left[\begin{array}{cc|c} 0 & -1 & 2 \\ 1 & 0 & -3 \end{array} \right]$$

$$\Rightarrow c_1 = -3$$

$$c_2 = 2$$

$$\Rightarrow [\vec{v}]_{\beta_1} = \begin{bmatrix} -3 \\ 2 \end{bmatrix}$$

2. What is $[T(S_1, S_2)]$?

$$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ -5 \\ -7 \end{bmatrix}, T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 13 \\ 16 \end{bmatrix}$$

$$\Rightarrow [T(S_1, S_2)] = \begin{bmatrix} 0 & 13 \\ -5 & 16 \\ -7 & 16 \end{bmatrix}$$

3. What is $[T(\beta_1, \beta_2)]$?

$$T\left(\begin{bmatrix} 3 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix}, T\left(\begin{bmatrix} 5 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$$

$$\Rightarrow [T(\beta_1, \beta_2)] = \begin{bmatrix} 1 & 2 \\ -2 & 1 \\ -5 & -3 \end{bmatrix}$$

4. What is $[T(\beta_1, \beta_2)]$?

$$T\left(\begin{bmatrix} 3 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix}, T\left(\begin{bmatrix} 5 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$$

$$\Rightarrow c_1 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 5 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 2 \\ 0 & 2 & 1 & -2 & 1 \\ -1 & 2 & 2 & -5 & -3 \end{array} \right] \xrightarrow{+R_1} \left[\begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 2 \\ 0 & 2 & 1 & -2 & 1 \\ 0 & 1 & 2 & -4 & -1 \end{array} \right] \begin{array}{l} \uparrow +R_2 \\ \downarrow -2R_2 \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 2 & -3 & 1 \\ 0 & 1 & 2 & -4 & -1 \\ 0 & 0 & -3 & 6 & 3 \end{array} \right] \xrightarrow{-3R_3} \left[\begin{array}{ccc|ccc} 1 & 0 & 2 & -3 & 1 \\ 0 & 1 & 2 & -4 & -1 \\ 0 & 0 & 1 & -2 & -1 \end{array} \right] \xrightarrow{\begin{array}{l} -2R_1 \\ -2R_2 \end{array}} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 3 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & -2 & -1 \end{array} \right]$$

$$\Rightarrow \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} = 1 \cdot \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + 0 \cdot \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} - 2 \cdot \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix}_\beta$$

$$\begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix} = 3 \cdot \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + 1 \cdot \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} - 1 \cdot \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix}_\beta$$

$$\Rightarrow [T(\beta_1, \beta_2)] = \begin{bmatrix} 1 & 3 \\ 0 & 1 \\ -2 & -1 \end{bmatrix}$$

Change of Basis Example:

$$\text{Let } S_1 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}, \beta = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$$

1. What is $P = [I(\beta, S_1)]$?

$$I\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \quad I\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\Rightarrow P = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

2. What is $Q = [I(S_1, \beta)]$?

$$I\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 2 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}_\beta$$

$$I\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = -1 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 1 \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}_\beta$$

$$\Rightarrow Q = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

3. If $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x+y \\ -2x+4y \end{bmatrix}$, what is $[T(S_1, S_1)]$?

$$\Rightarrow T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$\Rightarrow [T(S_1, S_1)] = \begin{bmatrix} 1 & 1 \\ -2 & 4 \end{bmatrix}$$

4. What is $[T(\beta, \beta)]$?

$$\text{Let } D = [T(\beta, \beta)], \quad \tilde{T} = [T(S_1, S_1)]$$

Therefore, for all $\vec{v} \in \mathbb{R}^2$:

$$D \cdot [v]_p = Q \cdot \tilde{T} \cdot P [v]_p$$

$$\Rightarrow D = Q \tilde{T} P$$

$$\Rightarrow D = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \text{ (A diagonal matrix).}$$