

Lecture #14: Singular Value Decomposition

Theorem - Let $A \in M_{n \times n}(\mathbb{C})$ then there exists unitary matrices $U \in M_{n \times n}(\mathbb{C})$, $V \in M_{n \times n}(\mathbb{C})$ such that

$$A = U \Sigma V^*$$

where

$$\Sigma = \begin{bmatrix} \sigma_1 & & & 0 \\ & \sigma_2 & & \\ & & \ddots & \\ 0 & & & \sigma_r & & 0 \\ & & & & 0 & \ddots & 0 \end{bmatrix}$$

$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r$ and r is the rank of A . The quantities $\sigma_1, \dots, \sigma_r$ are called the singular values of A .

proof:

Let $\{\vec{v}_1, \dots, \vec{v}_r\}$ be an orthonormal basis of eigenvectors of A^*A with eigenvalues $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r$. Consequently, $\{A\vec{v}_1, \dots, A\vec{v}_r\}$ is an orthogonal basis for $\text{im}(A)$. Consequently, letting

$$\vec{u}_i = \frac{1}{\|A\vec{v}_i\|} A\vec{v}_i = \frac{1}{\sigma_i} A\vec{v}_i$$

it follows that $\{\vec{u}_1, \dots, \vec{u}_r\}$ is an orthonormal basis for $\text{im}(A)$. Extending to $\{\vec{u}_1, \dots, \vec{u}_m\}$ we obtain an orthonormal basis for $\mathbb{C}^m$ and defining $U = [\vec{u}_1 | \dots | \vec{u}_m]$, $V = [\vec{v}_1 | \dots | \vec{v}_n]$ it follows that

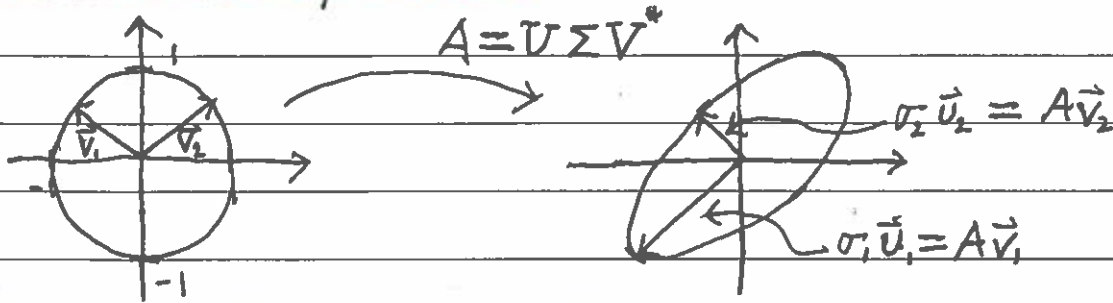
$$\begin{aligned} AV &= U\Sigma \\ \Rightarrow A &= U\Sigma V^* \end{aligned}$$

Definition - The factorization

$$A = U\Sigma V^*$$

is called the singular value decomposition.

Geometric Interpretation



$$[A] [\vec{v}_1 | \dots | \vec{v}_n] = [\vec{u}_1 | \dots | \vec{u}_n] \begin{bmatrix} \sigma_1 & & 0 \\ & \ddots & \\ 0 & & \sigma_n \end{bmatrix}$$

$\underbrace{\quad}_{V} \quad \underbrace{\quad}_{U} \quad \underbrace{\quad}_{\Sigma}$
unitary

Tips on finding the SVD

$$-A^*A = V \Sigma V^* U \Sigma V^* \\ = V \Sigma^2 V^*$$

$\Rightarrow \vec{v}_1, \dots, \vec{v}_n$ are eigenvectors of A^*A

$\Rightarrow \sigma_1^2, \dots, \sigma_n^2$ are eigenvalues of A^*A

$\Rightarrow \sigma_1 \vec{u}_1 = A \vec{v}_1, \dots, \sigma_n \vec{u}_n = A \vec{v}_n$

Examples

$$1. A = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix}, A \vec{e}_1 = \begin{bmatrix} 3 \\ 0 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix}, A \vec{e}_2 = \begin{bmatrix} 0 \\ -2 \end{bmatrix} = 2 \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$\Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \vec{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \vec{u}_2 = \begin{bmatrix} 0 \\ -1 \end{bmatrix}, \sigma_1 = 3, \sigma_2 = 2$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$2. B = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}, A\vec{e}_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix}, A\vec{e}_2 = \begin{bmatrix} 0 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\Rightarrow \vec{v}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \vec{u}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \vec{u}_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \sigma_1 = 3, \sigma_2 = 2$$

$$\Rightarrow B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$3. C = \begin{bmatrix} 0 & 2 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}, A\vec{e}_1 = 0, A\vec{e}_2 = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\vec{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \vec{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \vec{u}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \vec{u}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \sigma_1 = 2, \sigma_2 = 0$$

$$C = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{3 \times 3} \underbrace{\begin{bmatrix} 3 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}}_{3 \times 2} \underbrace{\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}}_{2 \times 2}$$

$$4. D = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \Rightarrow \text{im}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

We need to find direction of greatest stretching. Let

$$\vec{v}_1 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \Rightarrow D\vec{v}_1 = \begin{bmatrix} \sqrt{2} \\ 0 \end{bmatrix} = \sqrt{2} \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Therefore,

$$\vec{v}_1 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}, \sigma_1 = \sqrt{2}, \vec{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Rank-nullity implies $\sigma_2 = 0$ and orthogonality implies

$$\vec{v}_2 = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}, \sigma_2 = 0, \vec{u}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{2} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}^*$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{2} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$5. E = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow \text{im}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

Let's find $\text{Ker}(E)$. Row reducing we

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

Consequently,

$$\text{Ker}(E) = \text{span} \left\{ \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \right\}$$

Therefore,

$$\vec{v}_2 = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}, \sigma_2 = 0$$

$$\Rightarrow \vec{v}_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Now,

$$E\vec{v}_1 = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{2}} \\ \frac{2}{\sqrt{2}} \end{bmatrix} = 2 \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Consequently, $\sigma_1 = 2$,

$$\vec{u}_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

By orthogonality

$$\vec{u}_2 = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \Rightarrow E = U \Sigma V^* = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

Point of SVD

If $A = U \Sigma V^*$ then

$$A = \underbrace{\sigma_1 u_1 v_1^*}_{\text{best rank-1 approximation}} + \sigma_2 u_2 v_2^* + \dots + \sigma_n u_n v_n^*$$

$\therefore$ best rank-1 approximation
of a matrix.