



# PHY 711 Classical Mechanics and Mathematical Methods

10-10:50 AM MWF in Olin 103

**Notes on Lecture 36: Chap. 12 in F & W**

## Viscous fluids

1. Viscous stress tensor
2. Navier-Stokes equation
3. Example for incompressible fluid – Stokes “law”
4. Effects on sound waves => next time



<b>29</b>	Fri, 11/03/2023	Chap. 9	Ideal gas fluids	<a href="#">#23</a>
<b>31</b>	Mon, 11/06/2023	Chap. 9	Traveling and standing waves in the linear approximation	<a href="#">#24</a>
<b>32</b>	Wed, 11/08/2023	Chap. 9	Non-linear and other wave properties	Topic
<b>33</b>	Fri, 11/10/2023	Chap. 9	Analysis of non-linear waves and shock waves	<a href="#">#25</a>
<b>34</b>	Mon, 11/13/2023	Chap. 10	Surface waves in fluids	<a href="#">#26</a>
<b>35</b>	Wed, 11/15/2023	Chap. 10	Surface waves in fluids; soliton solutions	<a href="#">#27</a>
<b>36</b>	Fri, 11/17/2023	Chap. 11	Heat conduction	<a href="#">#28</a>
<b>37</b>	Mon, 11/20/2023	Chap. 12	Viscous effects in hydrodynamics	
	Wed, 11/22/2023	Thanksgiving		
	Fri, 11/24/2023	Thanksgiving		
	Mon, 11/27/2023		Presentations I	
	Wed, 11/29/2023		Presentations 2	
	Fri, 12/01/2023		Presentations 3	
<b>38</b>	Mon, 12/04/2023	Chap. 12	Viscous effects in hydrodynamics	
<b>39</b>	Wed, 12/06/2023		Review	
<b>40</b>	Fri, 12/08/2023		Review	



## PHY 711 Presentation Schedule

Monday 11/27/2023

	Presenter Name	Topic
10:00-10:16	Gabby Tamayo	Three body problem / Ejection
10:17-10:33	Thilini Karunaratna	Lagrangian and Hamiltonian Equations
10:34-10:50	Joe Granlie	Canonical transformations (+Ham. Jacobi maybe)

Wednesday 11/29/2023

	Presenter Name	Topic
10:00-10:24	Athul Prem	Numerical simulation of particle dynamics
10:25-10:50	David Carchipulla-Morales	Eddy Covariance Momentum Conservation

Friday 12/01/2023

	Presenter Name	Topic
10:00-10:24	Caela Flake	Analyze the equations of motion for the <u>Foucault</u> Pendulum
10:25-10:50	Mitchell Turk	Molecular Dynamics Simulation Mechanics and Methods

# Equations for motion of non-viscous fluid

Newton-Euler equation of motion:

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho (\mathbf{v} \cdot \nabla) \mathbf{v} = \rho \mathbf{f}_{\text{applied}} - \nabla p$$

Continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0 \quad \Rightarrow \quad \mathbf{v} \left( \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) \right) = 0$$

Add the two equations:

$$\underbrace{\rho \frac{\partial \mathbf{v}}{\partial t} + \frac{\partial \rho}{\partial t} \mathbf{v}}_{\frac{\partial(\rho \mathbf{v})}{\partial t}} + \underbrace{\rho (\mathbf{v} \cdot \nabla) \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v})}_{\sum_{j=1}^3 \frac{\partial(\rho v_j \mathbf{v})}{\partial x_j}} = \rho \mathbf{f}_{\text{applied}} - \nabla p$$

## Equations for motion of non-viscous fluid -- continued

Modified Newton-Euler equation in terms of fluid momentum:

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_j \mathbf{v})}{\partial x_j} = \rho \mathbf{f}_{\text{applied}} - \nabla p$$

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_j \mathbf{v})}{\partial x_j} + \nabla p = \rho \mathbf{f}_{\text{applied}}$$

Fluid momentum:  $\rho \mathbf{v}$

Stress tensor:  $T_{ij} \equiv \rho v_i v_j + p \delta_{ij}$

$i^{\text{th}}$  component of Newton-Euler equation:

$$\frac{\partial(\rho v_i)}{\partial t} + \sum_{j=1}^3 \frac{\partial T_{ij}}{\partial x_j} = \rho f_i$$

Now consider the effects of viscosity

In terms of stress tensor:

$$T_{ij} = T_{ij}^{\text{ideal}} + T_{ij}^{\text{viscous}}$$

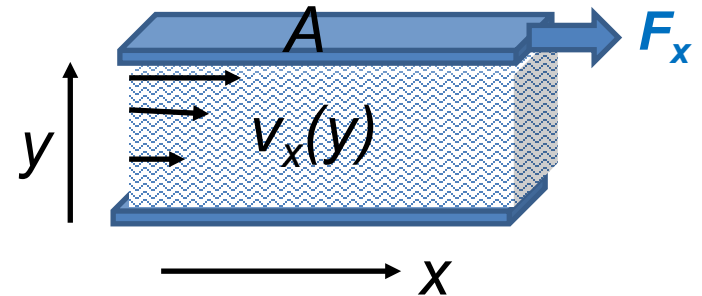
$$T_{ij}^{\text{ideal}} = \rho v_i v_j + p \delta_{ij} = T_{ji}^{\text{ideal}}$$

As an example of a viscous effect, consider --

Newton's "law" of viscosity

$$\frac{F_x}{A} = \eta \frac{\partial v_x}{\partial y}$$

material dependent parameter





## Effects of viscosity

Argue that viscosity is due to shear forces in a fluid of the form:

$$\frac{F_{drag}}{A} = \eta \frac{\partial v_x}{\partial y}$$

Formulate viscosity stress tensor with traceless and diagonal terms:

$$T_{kl}^{viscous} = -\eta \left( \frac{\partial v_k}{\partial x_l} + \frac{\partial v_l}{\partial x_k} - \frac{2}{3} \delta_{kl} (\nabla \cdot \mathbf{v}) \right) - \zeta \delta_{kl} (\nabla \cdot \mathbf{v})$$

 **viscosity**  **bulk viscosity**

Total stress tensor:  $T_{kl} = T_{kl}^{ideal} + T_{kl}^{viscous}$

$$T_{kl}^{ideal} = \rho v_k v_l + p \delta_{kl}$$

$$T_{kl}^{viscous} = -\eta \left( \frac{\partial v_k}{\partial x_l} + \frac{\partial v_l}{\partial x_k} - \frac{2}{3} \delta_{kl} (\nabla \cdot \mathbf{v}) \right) - \zeta \delta_{kl} (\nabla \cdot \mathbf{v})$$

## Effects of viscosity -- continued

Incorporating generalized stress tensor into Newton-Euler equations

$$\frac{\partial(\rho v_i)}{\partial t} + \sum_{j=1}^3 \frac{\partial T_{ij}}{\partial x_j} = \rho f_i$$

$$\frac{\partial(\rho v_i)}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_i v_j)}{\partial x_j} = \rho f_i - \frac{\partial p}{\partial x_i} + \eta \sum_{j=1}^3 \frac{\partial^2 v_i}{\partial x_j^2} + \left( \zeta + \frac{1}{3} \eta \right) \sum_{j=1}^3 \frac{\partial^2 v_j}{\partial x_i \partial x_j}$$

Continuity equation

$$\frac{\partial \rho}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_j)}{\partial x_j} = 0$$

Vector form (Navier-Stokes equation)

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity equation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$



# Newton-Euler equations for viscous fluids

Navier-Stokes equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity condition

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

Typical viscosities at 20° C and 1 atm:

Fluid	$\eta/\rho$ (m <sup>2</sup> /s)	$\eta$ (Pa s)
Water	1.00 x 10 <sup>-6</sup>	1 x 10 <sup>-3</sup>
Air	14.9 x 10 <sup>-6</sup>	0.018 x 10 <sup>-3</sup>
Ethyl alcohol	1.52 x 10 <sup>-6</sup>	1.2 x 10 <sup>-3</sup>
Glycerine	1183 x 10 <sup>-6</sup>	1490 x 10 <sup>-3</sup>

Example – steady flow of an incompressible fluid in a long pipe with a circular cross section of radius  $R$

Navier-Stokes equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity condition

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\text{Note that } \nabla \times (\nabla \times \mathbf{v}) = \nabla (\nabla \cdot \mathbf{v}) - \nabla^2 \mathbf{v}$$

$$\text{Incompressible fluid} \Rightarrow \nabla \cdot \mathbf{v} = 0$$

$$\text{Steady flow} \Rightarrow \frac{\partial \mathbf{v}}{\partial t} = 0$$

$$\text{Irrotational flow} \Rightarrow \nabla \times \mathbf{v} = 0$$

$$\text{No applied force} \Rightarrow \mathbf{f} = 0$$

$$\text{Neglect non-linear terms} \Rightarrow \nabla (v^2) = 0$$

Example – steady flow of an incompressible fluid in a long pipe with a circular cross section of radius  $R$  -- continued

Navier-Stokes equation becomes:

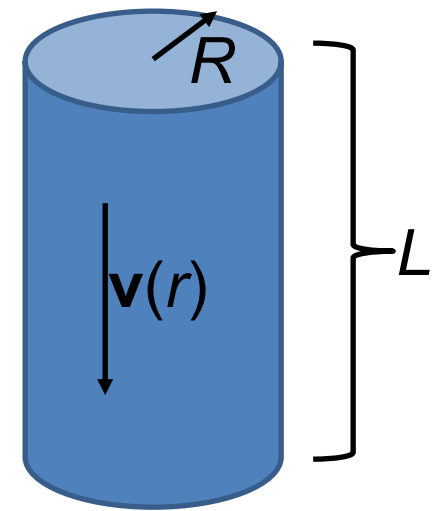
$$0 = -\frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v}$$

Assume that  $\mathbf{v}(\mathbf{r}, t) = v_z(r) \hat{\mathbf{z}}$

$$\frac{\partial p}{\partial z} = \eta \nabla^2 v_z(r) \quad (\text{independent of } z)$$

Suppose that  $\frac{\partial p}{\partial z} = -\frac{\Delta p}{L}$  (uniform pressure gradient)

$$\Rightarrow \nabla^2 v_z(r) = -\frac{\Delta p}{\eta L}$$



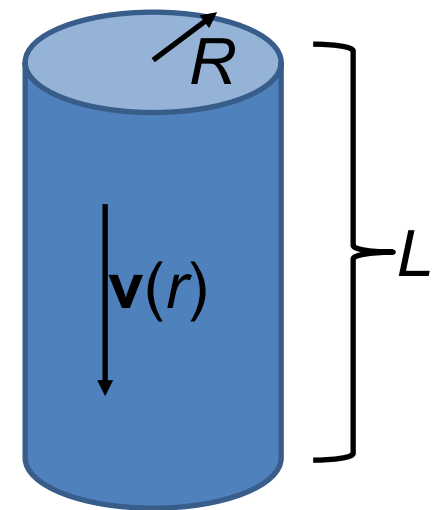
Example – steady flow of an incompressible fluid in a long pipe with a circular cross section of radius  $R$  -- continued

$$\nabla^2 v_z(r) = -\frac{\Delta p}{\eta L}$$

$$\frac{1}{r} \frac{d}{dr} r \frac{dv_z(r)}{dr} = -\frac{\Delta p}{\eta L}$$

$$v_z(r) = -\frac{\Delta p r^2}{4\eta L} + C_1 \ln(r) + C_2$$

$$\Rightarrow C_1 = 0 \quad v_z(R) = 0 = -\frac{\Delta p R^2}{4\eta L} + C_2$$

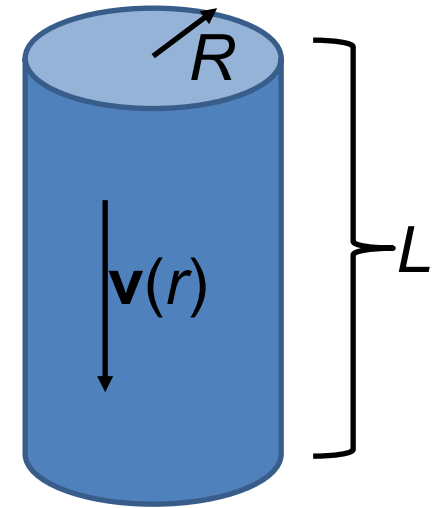
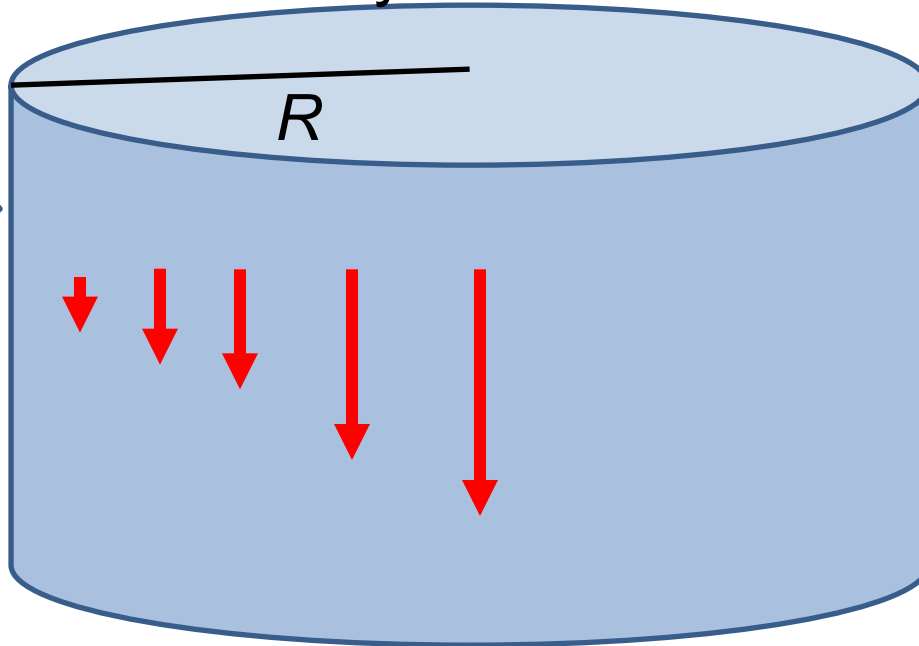


$$v_z(r) = \frac{\Delta p}{4\eta L} (R^2 - r^2)$$

# Comment on boundary condition

$$v_z(R) = 0$$

Fluid approximately stationary at boundary



Example – steady flow of an incompressible fluid in a long pipe with a circular cross section of radius  $R$  -- continued

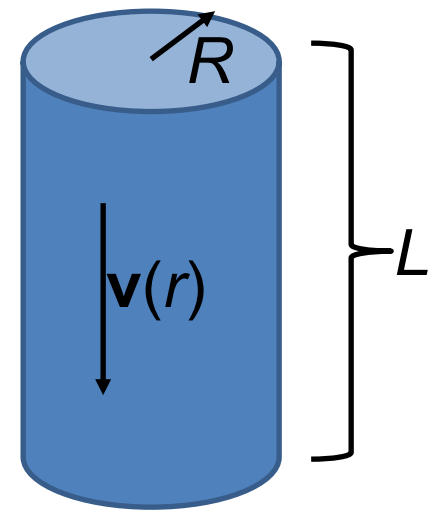
$$v_z(r) = \frac{\Delta p}{4\eta L} (R^2 - r^2)$$

Mass flow rate through the pipe:

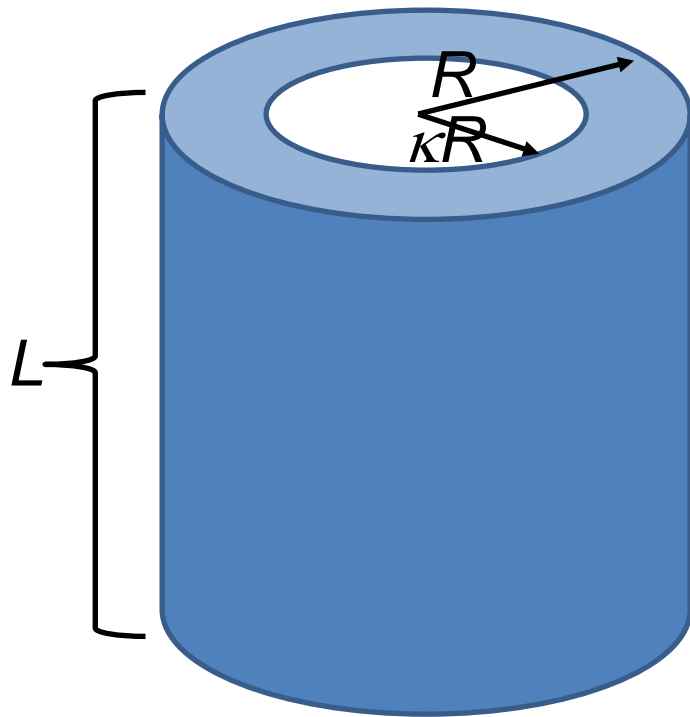
$$\frac{dM}{dt} = 2\pi\rho \int_0^R r dr v_z(r) = \frac{\Delta p \rho \pi R^4}{8\eta L}$$

Poiseuille formula;

→ Method for measuring  $\eta$



Example – steady flow of an incompressible fluid in a long tube with a circular cross section of outer radius  $R$  and inner radius  $\kappa R$



$$\nabla^2 v_z(r) = -\frac{\Delta p}{\eta L}$$

$$\frac{1}{r} \frac{d}{dr} r \frac{dv_z(r)}{dr} = -\frac{\Delta p}{\eta L}$$

$$v_z(r) = -\frac{\Delta p r^2}{4\eta L} + C_1 \ln(r) + C_2$$

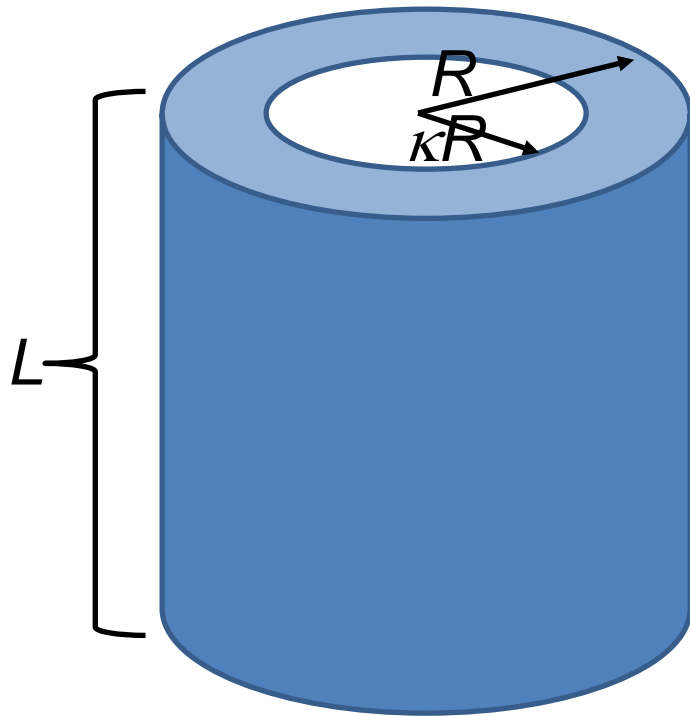
$$v_z(R) = 0 = -\frac{\Delta p R^2}{4\eta L} + C_1 \ln(R) + C_2$$

$$v_z(\kappa R) = 0 = -\frac{\Delta p \kappa^2 R^2}{4\eta L} + C_1 \ln(\kappa R) + C_2$$

Example – steady flow of an incompressible fluid in a long tube with a circular cross section of outer radius  $R$  and inner radius  $\kappa R$  -- continued

Solving for  $C_1$  and  $C_2$  :

$$v_z(r) = \frac{\Delta p R^2}{4\eta L} \left( 1 - \left( \frac{r}{R} \right)^2 - \frac{1 - \kappa^2}{\ln \kappa} \ln \left( \frac{r}{R} \right) \right)$$



Mass flow rate through the pipe:

$$\frac{dM}{dt} = 2\pi\rho \int_{\kappa R}^R r dr v_z(r) = \frac{\Delta p \rho \pi R^4}{8\eta L} \left( 1 - \kappa^4 + \frac{(1 - \kappa^2)^2}{\ln \kappa} \right)$$

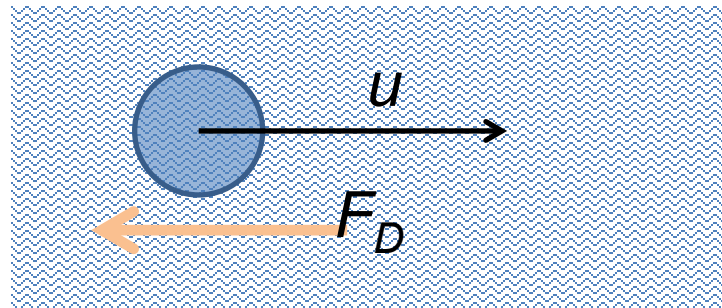




More discussion of viscous effects in incompressible fluids

Stokes' analysis of viscous drag on a sphere of radius  $R$  moving at speed  $u$  in medium with viscosity  $\eta$  :

$$F_D = -\eta(6\pi Ru)$$



Plan:

1. Consider the general effects of viscosity on fluid equations
2. Consider the solution to the linearized equations for the case of steady-state flow of a sphere of radius  $R$
3. Infer the drag force needed to maintain the steady-state flow

Have you ever encountered Stokes law in previous contexts?

- a. Milliken oil drop experiment
- b. A sphere falling due to gravity in a viscous fluid, reaching a terminal velocity
- c. Other?



Newton-Euler equation for incompressible fluid,  
modified by viscous contribution (Navier-Stokes equation):

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f}_{\text{applied}} - \frac{\nabla p}{\rho} + \underbrace{\frac{\eta}{\rho}}_{\nu} \nabla^2 \mathbf{v}$$

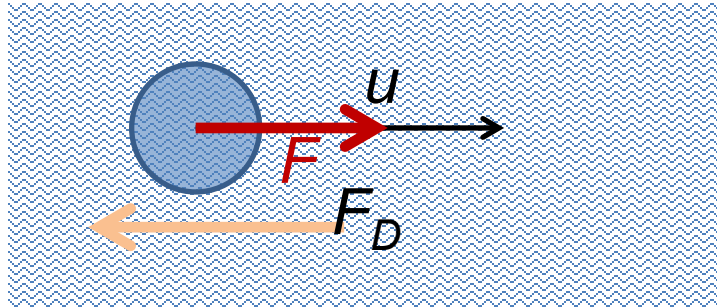
Kinematic viscosity

Typical kinematic viscosities at 20° C and 1 atm:

Fluid	$\nu$ (m <sup>2</sup> /s)
Water	1.00 x 10 <sup>-6</sup>
Air	14.9 x 10 <sup>-6</sup>
Ethyl alcohol	1.52 x 10 <sup>-6</sup>
Glycerine	1183 x 10 <sup>-6</sup>

Stokes' analysis of viscous drag on a sphere of radius  $R$  moving at speed  $u$  in medium with viscosity  $\eta$  :

$$F_D = -\eta(6\pi R u)$$



Effects of drag force on motion of

particle of mass  $m$  with constant force  $F$  :

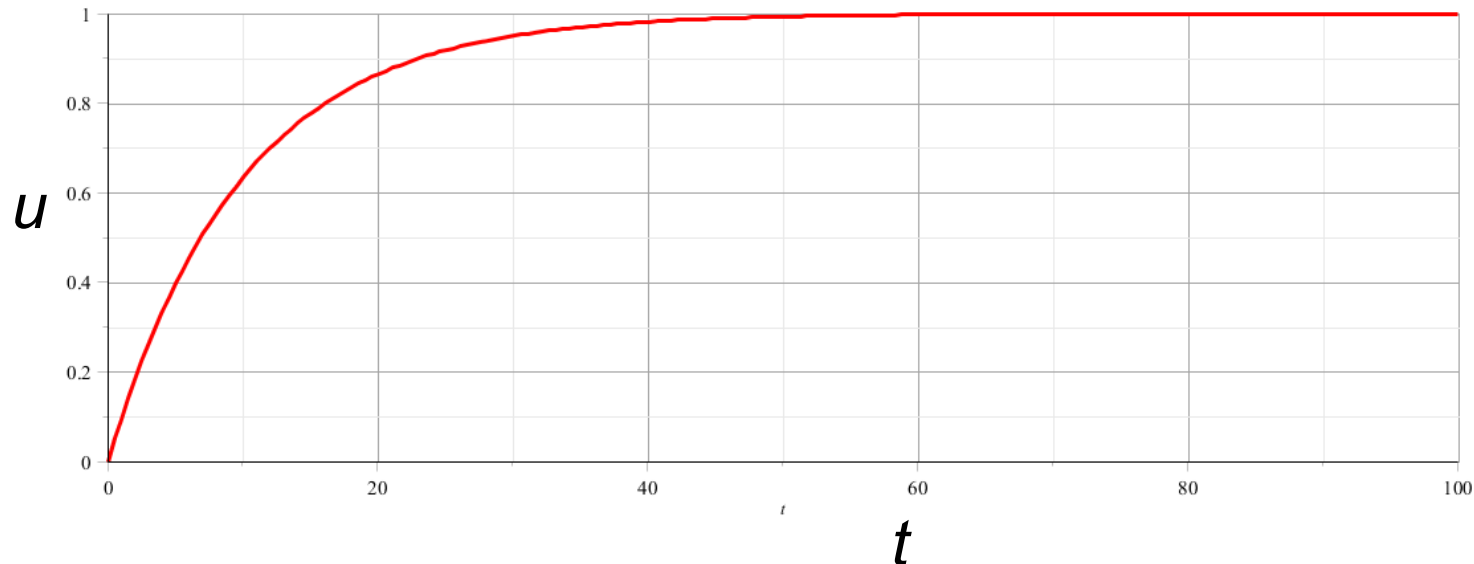
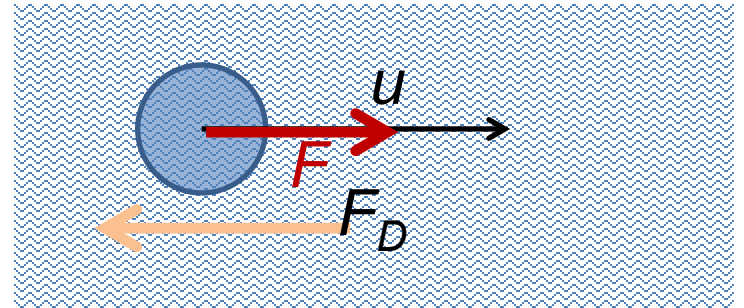
$$F - 6\pi R \eta u = m \frac{du}{dt} \quad \text{with } u(0) = 0$$

$$\Rightarrow u(t) = \frac{F}{6\pi R \eta} \left( 1 - e^{-\frac{6\pi R \eta}{m} t} \right)$$

Effects of drag force on motion of  
particle of mass  $m$  with constant force  $F$  :

$$F - 6\pi R \eta u = m \frac{du}{dt} \quad \text{with } u(0) = 0$$

$$\Rightarrow u(t) = \frac{F}{6\pi R \eta} \left( 1 - e^{-\frac{6\pi R \eta}{m} t} \right)$$



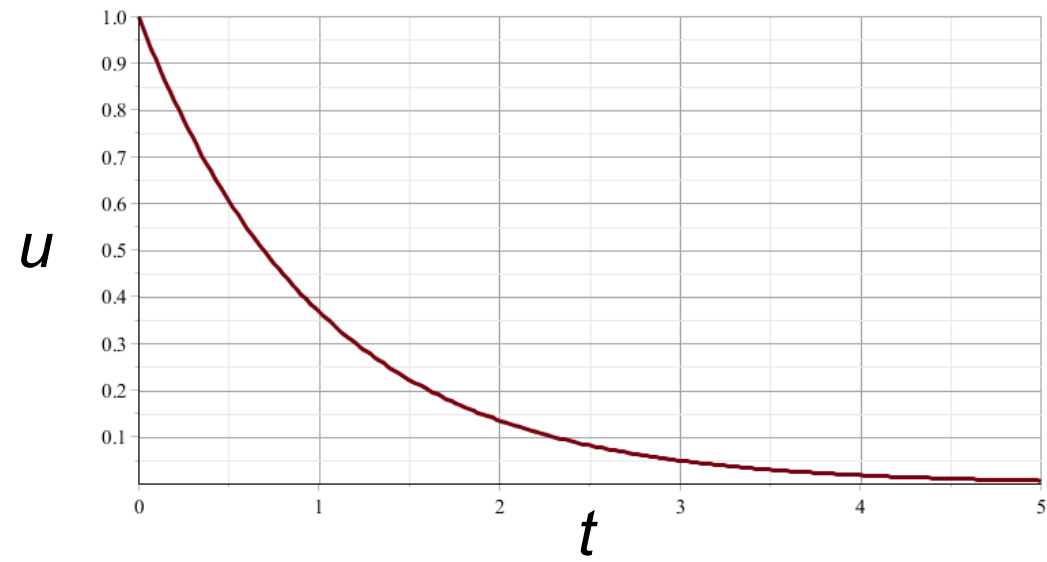
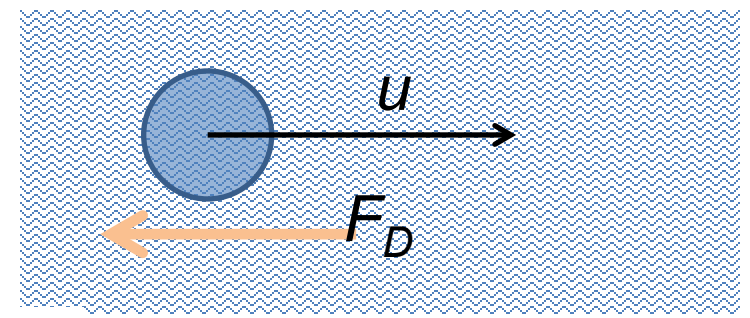


# Effects of drag force on motion of particle of mass $m$

with an initial velocity with  $u(0) = U_0$  and no external force

$$-6\pi R\eta u = m \frac{du}{dt}$$

$$\Rightarrow u(t) = U_0 e^{-\frac{6\pi R\eta}{m}t}$$

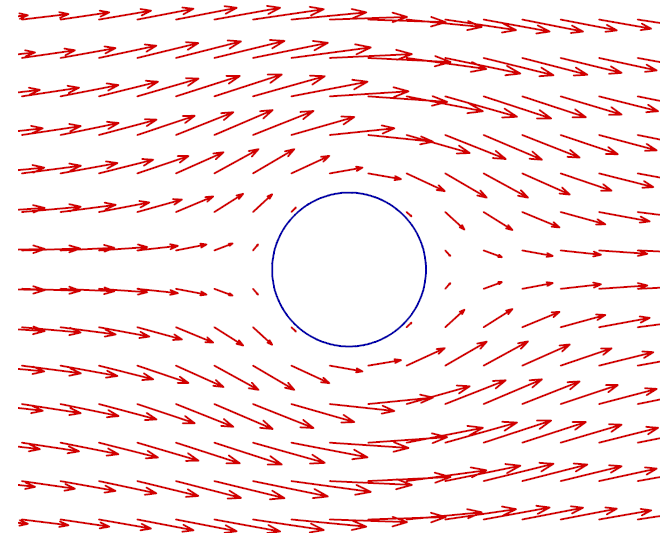


## Recall: PHY 711 -- Assignment #22      Nov. 01, 2023

Determine the form of the velocity potential for an incompressible fluid representing uniform velocity in the  $\mathbf{z}$  direction at large distances from a spherical obstruction of radius  $a$ . Find the form of the velocity potential and the velocity field for all  $r > a$ . Assume that for  $r = a$ , the velocity in the radial direction is 0 but the velocity in the azimuthal direction is not necessarily 0.

$$\nabla^2 \Phi = 0$$

$$\Phi(r, \theta) = -v_0 \left( r + \frac{a^3}{2r^2} \right) \cos \theta$$



In the present viscous case, we will assume that  $\mathbf{v}(a)=0$ .



Newton-Euler equation for incompressible fluid,  
modified by viscous contribution (Navier-Stokes equation):

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f}_{\text{applied}} - \frac{\nabla p}{\rho} + \frac{\eta}{\rho} \nabla^2 \mathbf{v}$$

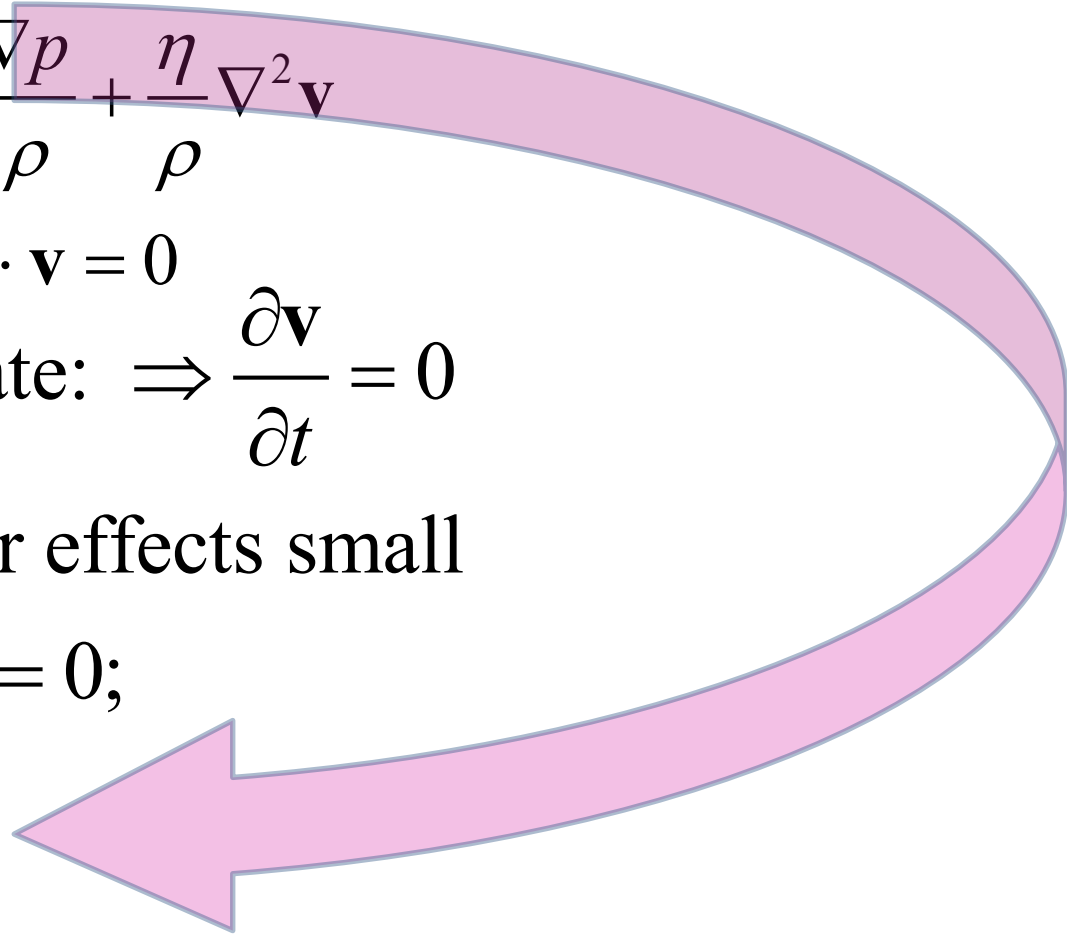
Continuity equation:  $\nabla \cdot \mathbf{v} = 0$

Assume steady state:  $\Rightarrow \frac{\partial \mathbf{v}}{\partial t} = 0$


Assume non-linear effects small

Initially set  $\mathbf{f}_{\text{applied}} = 0$ ;

$$\Rightarrow \nabla p = \eta \nabla^2 \mathbf{v}$$






$$\nabla p = \eta \nabla^2 \mathbf{v}$$

Take curl of both sides of equation:

$$\nabla \times (\nabla p) = 0 = \eta \nabla^2 (\nabla \times \mathbf{v})$$

Assume (with a little insight from Landau):

$$\mathbf{v} = \nabla \times (\nabla \times f(r) \mathbf{u}) + \mathbf{u}$$

where  $f(r) \xrightarrow{r \rightarrow \infty} 0$

Note that:

$$\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$

## Digression

Some comment on assumption:  $\mathbf{v} = \nabla \times (\nabla \times f(r)\mathbf{u}) + \mathbf{u}$

$$\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$


Here  $\mathbf{A} = f(r)\mathbf{u}$

$$\nabla \times \mathbf{v} = \nabla \times (\nabla \times (\nabla \times \mathbf{A})) = -\nabla \times (\nabla^2 \mathbf{A})$$

Also note:  $\nabla p = \eta \nabla^2 \mathbf{v}$

$$\Rightarrow \nabla \times \nabla p = 0 = \nabla \times \eta \nabla^2 \mathbf{v} \quad \text{or} \quad \nabla^2 (\nabla \times \mathbf{v}) = 0$$

$$\nabla^2 (\nabla \times \nabla^2 \mathbf{A}) = \nabla^4 (\nabla \times \mathbf{A}) = 0$$


$$\mathbf{v} = \nabla \times (\nabla \times f(r)\mathbf{u}) + \mathbf{u}$$

$$\mathbf{u} = u\hat{\mathbf{z}}$$

$$\nabla \times (\nabla \times f(r)\hat{\mathbf{z}}) = \nabla(\nabla \cdot f(r)\hat{\mathbf{z}}) - \nabla^2 f(r)\hat{\mathbf{z}}$$

$$\nabla \times \mathbf{v} = 0 \quad \Rightarrow \quad \nabla^2 (\nabla \times \mathbf{v}) = 0$$

$$\nabla^4 (\nabla \times f(r)\hat{\mathbf{z}}) = 0 \quad \Rightarrow \quad \nabla^4 (\nabla f(r) \times \hat{\mathbf{z}}) = 0 \quad \Rightarrow \quad \nabla^4 f(r) = 0$$

$$f(r) = C_1 r^2 + C_2 r + C_3 + \frac{C_4}{r}$$

$$v_r = u \cos \theta \left( 1 - \frac{2}{r} \frac{df}{dr} \right) = u \cos \theta \left( 1 - 4C_1 - \frac{2C_2}{r} + \frac{2C_4}{r^3} \right)$$

$$v_\theta = -u \sin \theta \left( 1 - \frac{d^2 f}{dr^2} - \frac{1}{r} \frac{df}{dr} \right) = -u \sin \theta \left( 1 - 4C_1 - \frac{C_2}{r} - \frac{C_4}{r^3} \right)$$



Some details:


$$\nabla^4 f(r) = 0 \quad \Rightarrow \quad \left( \frac{d^2}{dr^2} + \frac{2}{r} \frac{d}{dr} \right)^2 f(r) = 0$$

$$f(r) = C_1 r^2 + C_2 r + C_3 + \frac{C_4}{r}$$

$$\begin{aligned} \mathbf{v} &= u \left( \nabla \times \left( \nabla \times f(r) \hat{\mathbf{z}} \right) + \hat{\mathbf{z}} \right) \\ &= u \left( \nabla \left( \nabla \cdot \left( f(r) \hat{\mathbf{z}} \right) \right) - \nabla^2 f(r) \hat{\mathbf{z}} + \hat{\mathbf{z}} \right) \end{aligned}$$

Note that:  $\hat{\mathbf{z}} = \cos \theta \hat{\mathbf{r}} - \sin \theta \hat{\boldsymbol{\theta}}$

$$\mathbf{v} = u \left( \nabla \left( \frac{df}{dr} \cos \theta \right) - \left( \nabla^2 (f(r)) - 1 \right) \left( \cos \theta \hat{\mathbf{r}} - \sin \theta \hat{\boldsymbol{\theta}} \right) \right)$$


$$v_r = u \cos \theta \left( 1 - \frac{2}{r} \frac{df}{dr} \right) = u \cos \theta \left( 1 - 4C_1 - \frac{2C_2}{r} + \frac{2C_4}{r^3} \right)$$


$$v_\theta = -u \sin \theta \left( 1 - \frac{d^2 f}{dr^2} - \frac{1}{r} \frac{df}{dr} \right) = -u \sin \theta \left( 1 - 4C_1 - \frac{C_2}{r} - \frac{C_4}{r^3} \right)$$

To satisfy  $\mathbf{v}(r \rightarrow \infty) = \mathbf{u}$ :  $\Rightarrow C_1 = 0$

To satisfy  $\mathbf{v}(R) = 0$  solve for  $C_2, C_4$

$$v_r = u \cos \theta \left( 1 - \frac{3R}{2r} + \frac{R^3}{2r^3} \right)$$

$$v_\theta = -u \sin \theta \left( 1 - \frac{3R}{4r} - \frac{R^3}{4r^3} \right)$$


$$v_r = u \cos \theta \left( 1 - \frac{3R}{2r} + \frac{R^3}{2r^3} \right)$$

$$v_\theta = -u \sin \theta \left( 1 - \frac{3R}{4r} - \frac{R^3}{4r^3} \right)$$

Determining pressure:

$$\nabla p = \eta \nabla^2 \mathbf{v} = -\eta \nabla \left( u \cos \theta \left( \frac{3R}{2r^2} \right) \right)$$

$$\Rightarrow p(r) = p_0 - \eta u \cos \theta \left( \frac{3R}{2r^2} \right)$$

$$p(r) = p_0 - \eta u \cos \theta \left( \frac{3R}{2r^2} \right)$$

Corresponds to:

$$F_D \cos \theta = (p(R) - p_0) 4\pi R^2 = -\eta u \cos \theta (6\pi R)$$

$$\Rightarrow F_D = -\eta u (6\pi R)$$

