

# PHY 711 Classical Mechanics and Mathematical Methods 10-10:50 AM MWF in Olin 103

# Notes on Lecture 35: Chap. 12 in F & W

# **Viscous fluids**

- 1. Viscous stress tensor
- 2. Navier-Stokes equation
- 3. Example for incompressible fluid Stokes "law"
- 4. Viscous effects on sound waves => next time

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29	Fri, 11/01/2024	Chap. 9	Ideal gas fluids	<u>#22</u>
30	Mon, 11/04/2024	Chap. 9	Traveling and standing waves in the linear approximation	<u>#23</u>
31	Wed, 11/06/2024	Chap. 9	Non-linear and other wave properties	<u>#24</u>
32	Fri, 11/08/2024	Chap. 10	Surface waves in fluids	<u>#25</u>
33	Mon, 11/11/2024	Chap. 10	Surface waves in fluids; soliton solutions	<u>#26</u>
34	Wed, 11/13/2024	Chap. 11	Heat conduction	<u>#27</u>
35	Fri, 11/15/2024	Chap. 12	Viscous effects in hydrodynamics	<u>#28</u>
36	Mon, 11/18/2024	Chap. 12	Viscous effects in hydrodynamics	
37	Wed, 11/20/2024	Chap. 13	Elasticity	
38	Fri, 11/22/2024	Chap. 1-13	Review	
39	Mon, 11/25/2024	Chap. 1-13	Review	
	Wed, 11/27/2024	Thanksgiving		
	Fri, 11/29/2024	Thanksgiving		
	Mon, 12/02/2024		Presentations 1	
	Wed, 12/04/2024		Presentations 2	
40	Fri, 12/06/2024	Chap. 1-13	Review	

# PHY 711 -- Assignment #28

#### Assigned: 11/15/2024 Due: 11/18/2024

Start reading Chapter 12 in Fetter & Walecka.

1. Work problem 12.4 at the end of Chapter 12 in Fetter & Walecka.

### Equations for motion of non-viscous fluid

Newton-Euler equation of motion:

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho (\mathbf{v} \cdot \nabla) \mathbf{v} = \rho \mathbf{f}_{applied} - \nabla p$$

Continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0 \qquad \Rightarrow \mathbf{v} \left( \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) \right) = 0$$

Add the two equations:

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \frac{\partial \rho}{\partial t} \mathbf{v} + \rho (\mathbf{v} \cdot \nabla) \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v}) = \rho \mathbf{f}_{applied} - \nabla p$$

$$\frac{\partial (\rho \mathbf{v})}{\partial t} \sum_{j=1}^{3} \frac{\partial (\rho v_j \mathbf{v})}{\partial x_j}$$

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#### Equations for motion of non-viscous fluid -- continued

Modified Newton-Euler equation in terms of fluid momentum:

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \sum_{j=1}^{3} \frac{\partial(\rho v_{j} \mathbf{v})}{\partial x_{j}} = \rho \mathbf{f}_{applied} - \nabla p$$
$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \sum_{j=1}^{3} \frac{\partial(\rho v_{j} \mathbf{v})}{\partial x_{j}} + \nabla p = \rho \mathbf{f}_{applied}$$

Fluid momentum:  $\rho \mathbf{v}$ Stress tensor:  $T_{ij} \equiv \rho v_i v_j + p \delta_{ij}$ 

 $i^{th}$  component of Newton-Euler equation:

$$\frac{\partial(\rho v_i)}{\partial t} + \sum_{j=1}^3 \frac{\partial T_{ij}}{\partial x_j} = \rho f_i$$

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Now consider the effects of viscosity

In terms of stress tensor:  

$$T_{ij} = T_{ij}^{\text{ideal}} + T_{ij}^{\text{viscous}}$$

$$T_{ij}^{\text{ideal}} = \rho v_i v_j + p \delta_{ij} = T_{ji}^{\text{ideal}}$$

As an example of a viscous effect, consider --

Newton's "law" of viscosity

$$\frac{F_x}{A} = \eta \frac{\partial v_x}{\partial y}$$

material dependent parameter



#### Effects of viscosity

Argue that viscosity is due to shear forces in a fluid of the form:

$$\frac{F_{drag}}{A} = \eta \frac{\partial v_x}{\partial y}$$

Formulate viscosity stress tensor with traceless and diagonal terms:

Total stress tensor:  $T_{kl} = T_{kl}^{ideal} + T_{kl}^{viscous}$ 

$$T_{kl}^{\text{ideal}} = \rho v_k v_l + p \delta_{kl}$$
$$T_{kl}^{\text{viscous}} = -\eta \left( \frac{\partial v_k}{\partial x_l} + \frac{\partial v_l}{\partial x_k} - \frac{2}{3} \delta_{kl} \left( \nabla \cdot \mathbf{v} \right) \right) - \zeta \delta_{kl} \left( \nabla \cdot \mathbf{v} \right)$$

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#### Effects of viscosity -- continued

Incorporating generalized stress tensor into Newton-Euler equations

$$\frac{\partial \left(\rho v_{i}\right)}{\partial t} + \sum_{i=1}^{3} \frac{\partial T_{ij}}{\partial x_{j}} = \rho f_{i}$$

$$\frac{\partial \left(\rho v_{i}\right)}{\partial t} + \sum_{j=1}^{3} \frac{\partial \left(\rho v_{i} v_{j}\right)}{\partial x_{j}} = \rho f_{i} - \frac{\partial p}{\partial x_{i}} + \eta \sum_{j=1}^{3} \frac{\partial^{2} v_{i}}{\partial x_{j}^{2}} + \left(\zeta + \frac{1}{3}\eta\right) \sum_{j=1}^{3} \frac{\partial^{2} v_{j}}{\partial x_{i} \partial x_{j}}$$

Continuity equation

$$\frac{\partial \rho}{\partial t} + \sum_{j=1}^{3} \frac{\partial \left(\rho v_{j}\right)}{\partial x_{j}} = 0$$

Vector form (Navier-Stokes equation)

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla \left( \nabla \cdot \mathbf{v} \right)$$
  
Continuity equation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

### Newton-Euler equations for viscous fluids

Navier-Stokes equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla \left( \nabla \cdot \mathbf{v} \right)$$

Continuity condition

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

Typical viscosities at 20° C and 1 atm:

Fluid	η/ρ <b>(m²/s)</b>	η (Pa s)
Water	1.00 x 10 <sup>-6</sup>	1 x 10 <sup>-3</sup>
Air	14.9 x 10 <sup>-6</sup>	0.018 x 10 <sup>-3</sup>
Ethyl alcohol	1.52 x 10 <sup>-6</sup>	1.2 x 10 <sup>-3</sup>
Glycerine	1183 x 10 <sup>-6</sup>	1490 x 10 <sup>-3</sup>

Example – steady flow of an incompressible fluid in a long pipe with a circular cross section of radius *R* Navier-Stokes equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla \left( \nabla \cdot \mathbf{v} \right)$$

Continuity condition

Note that  $\nabla \times (\nabla \times \mathbf{v}) = \nabla (\nabla \cdot \mathbf{v}) - \nabla^2 \mathbf{v}$  $\frac{\partial \rho}{\partial t} + \nabla \cdot \left(\rho \mathbf{v}\right) = 0$ Incompressible fluid  $\Rightarrow \nabla \cdot \mathbf{v} = 0$  $\Rightarrow \frac{\partial \mathbf{v}}{\partial t} = 0$ Steady flow  $\implies \nabla \times \mathbf{v} = 0$ Irrotational flow No applied force  $\Rightarrow$  **f**=0 Neglect non-linear terms  $\Rightarrow \nabla(v^2) = 0$ 11/15/2024 PHY 711 Fall 2024 -- Lecture 35 10



Navier-Stokes equation becomes:

$$0 = -\frac{1}{\rho}\nabla p + \frac{\eta}{\rho}\nabla^2 \mathbf{v}$$

Assume that  $\mathbf{v}(\mathbf{r},t) = v_z(r)\hat{\mathbf{z}}$ 

$$\frac{\partial p}{\partial z} = \eta \nabla^2 v_z(r) \quad \text{(independent of } z\text{)}$$



Suppose that  $\frac{\partial p}{\partial z} = -\frac{\Delta p}{L}$  (uniform pressure gradient)  $\Rightarrow \nabla^2 v_z(r) = -\frac{\Delta p}{\eta L}$ 

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# Example – steady flow of an incompressible fluid in a long pipe with a circular cross section of radius *R* -- continued

$$\nabla^2 v_z(r) = -\frac{\Delta p}{\eta L}$$
  
$$\frac{1}{r} \frac{d}{dr} r \frac{dv_z(r)}{dr} = -\frac{\Delta p}{\eta L}$$
  
$$v_z(r) = -\frac{\Delta p r^2}{4\eta L} + C_1 \ln(r) + C_2$$

$$\Rightarrow C_1 = 0 \qquad v_z(R) = 0 = -\frac{\Delta p R^2}{4\eta L} + C_2$$

$$v_z(r) = \frac{\Delta p}{4\eta L} \left( R^2 - r^2 \right)$$

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#### Comment on boundary condition





Example – steady flow of an incompressible fluid in a long pipe with a circular cross section of radius *R* -- continued

$$v_z(r) = \frac{\Delta p}{4\eta L} \left( R^2 - r^2 \right)$$

Mass flow rate through the pipe:

$$\frac{dM}{dt} = 2\pi\rho \int_0^R r dr v_z(r) = \frac{\Delta p \rho \pi R^4}{8\eta L}$$



#### Poiseuille formula; →Method for measuring η

Example – steady flow of an incompressible fluid in a long tube with a circular cross section of outer radius R and inner radius  $\kappa R$ 

$$\nabla^2 v_z(r) = -\frac{\Delta p}{\eta L}$$

$$\frac{1}{r} \frac{d}{dr} r \frac{dv_z(r)}{dr} = -\frac{\Delta p}{\eta L}$$

$$v_z(r) = -\frac{\Delta p r^2}{4\eta L} + C_1 \ln(r) + C_2$$

$$v_z(R) = 0 = -\frac{\Delta p R^2}{4\eta L} + C_1 \ln(R) + C_2$$

$$v_z(\kappa R) = 0 = -\frac{\Delta p \kappa^2 R^2}{4\eta L} + C_1 \ln(\kappa R) + C_2$$

Example – steady flow of an incompressible fluid in a long tube with a circular cross section of outer radius R and inner radius  $\kappa R$  -- continued

Solving for  $C_1$  and  $C_2$ :  $v_z(r) = \frac{\Delta p R^2}{4nL} \left( 1 - \left(\frac{r}{R}\right)^2 - \frac{1 - \kappa^2}{\ln \kappa} \ln\left(\frac{r}{R}\right) \right)$ Mass flow rate through the pipe:  $\frac{dM}{dt} = 2\pi\rho \int_{\kappa R}^{R} r dr v_z(r) = \frac{\Delta p \rho \pi R^4}{8\eta L} \left( 1 - \kappa^4 + \frac{\left(1 - \kappa^2\right)^2}{\ln \kappa} \right)$ PHY 711 Fall 2024 -- Lecture 35 11/15/2024



More discussion of viscous effects in incompressible fluids Stokes' analysis of viscous drag on a sphere of radius Rmoving at speed u in medium with viscosity  $\eta$ :

 $E_{D}$ 

$$F_D = -\eta (6\pi R u)$$



- 1. Consider the general effects of viscosity on fluid equations
- Consider the solution to the linearized equations for the case of steady-state flow of a sphere of radius R
- 3. Infer the drag force needed to maintain the steady-state flow

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Have you ever encountered Stokes law in previous contexts?

- a. Milliken oil drop experiment
- b. A sphere falling due to gravity in a viscous fluid, reaching a terminal velocity
- c. Other?



### Newton-Euler equation for incompressible fluid, modified by viscous contribution (Navier-Stokes equation):

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f}_{applied} - \frac{\nabla p}{\rho} + \frac{\eta}{\rho} \nabla^2 \mathbf{v}$$
  
*v* Kinematic viscosity

Typical kinematic viscosities at 20° C and 1 atm:

Fluid	ν (m²/s)
Water	1.00 x 10 <sup>-6</sup>
Air	14.9 x 10 <sup>-6</sup>
Ethyl alcohol	1.52 x 10 <sup>-6</sup>
Glycerine	1183 x 10 <sup>-6</sup>

# Stokes' analysis of viscous drag on a sphere of radius Rmoving at speed u in medium with viscosity $\eta$ :

Effects of drag force on motion of

particle of mass m with constant force F:

$$F - 6\pi R \eta u = m \frac{du}{dt} \qquad \text{with } u(0) = 0$$
$$\Rightarrow u(t) = \frac{F}{6\pi R \eta} \left( 1 - e^{-\frac{6\pi R \eta}{m}t} \right)$$

 $F_D = -\eta (6\pi R u)$ 

# Effects of drag force on motion of

particle of mass m with constant force F:





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## Effects of drag force on motion of particle of mass *m* with an initial velocity with $u(0) = U_0$ and no external force



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#### Recall: PHY 711 -- Assignment #21 Oct. 30, 2024

Determine the form of the velocity potential for an incompressible fluid representing uniform velocity in the **z** direction at large distances from a spherical obstruction of radius *a*. Find the form of the velocity potential and the velocity field for all r > a. Assume that for r = a, the velocity in the radial direction is 0 but the velocity in the azimuthal direction is not necessarily 0.

$$\nabla^2 \Phi = 0$$
  
$$\Phi(r,\theta) = -v_0 \left(r + \frac{a^3}{2r^2}\right) \cos\theta$$

In the present viscous case, we will assume that **v**(*a*)=0. 11/15/2024 PHY 711 Fall 2024 -- Lecture 35



This treatment follows Landau & Lifshitz, *Fluid Mechanics* 

Newton-Euler equation for incompressible fluid,

modified by viscous contribution (Navier-Stokes equation):

 $\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f}_{applied} - \frac{\nabla p}{\rho} + \frac{\eta}{\rho} \nabla^2 \mathbf{v}$ Continuity equation:  $\nabla \cdot \mathbf{v} = 0$ Assume steady state:  $\Rightarrow \frac{\partial \mathbf{V}}{\partial t} = 0$ Assume non-linear effects small Initially set  $\mathbf{f}_{applied} = 0$ ;  $\Rightarrow \nabla p = \eta \nabla^2 \mathbf{v}$ PHY 711 Fall 2024 -- Lecture 35 11/15/2024 24



$$\nabla p = \eta \nabla^2 \mathbf{v}$$

Take curl of both sides of equation:  $\nabla \times (\nabla p) = 0 = \eta \nabla^2 (\nabla \times \mathbf{v})$ 

Assume (with a little insight from Landau):

$$\mathbf{v} = \nabla \times \left(\nabla \times f(r)\mathbf{u}\right) + \mathbf{u}$$

where  $f(r) \xrightarrow[r \to \infty]{} 0$ 

Note that:

$$\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$



Digression

Some comment on assumption:  $\mathbf{v} = \nabla \times (\nabla \times f(r)\mathbf{u}) + \mathbf{u}$  $\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$ Here  $\mathbf{A} = f(r)\mathbf{u}$  $\nabla \times \mathbf{v} = \nabla \times (\nabla \times (\nabla \times \mathbf{A})) = -\nabla \times (\nabla^2 \mathbf{A})$ Also note:  $\nabla p = \eta \nabla^2 \mathbf{v}$  $\Rightarrow \nabla \times \nabla p = 0 = \nabla \times \eta \nabla^2 \mathbf{v}$ or  $\nabla^2 (\nabla \times \mathbf{v}) = 0$  $\nabla^2 \left( \nabla \times \nabla^2 \mathbf{A} \right) = \nabla^4 \left( \nabla \times \mathbf{A} \right) = 0$ 



![](_page_27_Picture_0.jpeg)

$$\nabla^{4} f(r) = 0 \qquad \Rightarrow \left(\frac{d^{2}}{dr^{2}} + \frac{2}{r}\frac{d}{dr}\right)^{2} f(r) = 0$$
$$f(r) = C_{1}r^{2} + C_{2}r + C_{3} + \frac{C_{4}}{r}$$
$$\mathbf{v} = u\left(\nabla \times \left(\nabla \times f(r)\hat{\mathbf{z}}\right) + \hat{\mathbf{z}}\right)$$
$$= u\left(\nabla\left(\nabla \cdot \left(f(r)\hat{\mathbf{z}}\right)\right) - \nabla^{2}f(r)\hat{\mathbf{z}} + \hat{\mathbf{z}}\right)$$

Note that:  $\hat{\mathbf{z}} = \cos\theta \hat{\mathbf{r}} - \sin\theta \hat{\mathbf{\theta}}$ 

$$\mathbf{v} = u \left( \nabla \left( \frac{df}{dr} \cos \theta \right) - \left( \nabla^2 \left( f(r) \right) - 1 \right) \left( \cos \theta \hat{\mathbf{r}} - \sin \theta \hat{\mathbf{\theta}} \right) \right)$$

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$$\begin{aligned} v_r &= u\cos\theta \left(1 - \frac{2}{r}\frac{df}{dr}\right) = u\cos\theta \left(1 - 4C_1 - \frac{2C_2}{r} + \frac{2C_4}{r^3}\right) \\ v_\theta &= -u\sin\theta \left(1 - \frac{d^2f}{dr^2} - \frac{1}{r}\frac{df}{dr}\right) = -u\sin\theta \left(1 - 4C_1 - \frac{C_2}{r} - \frac{C_4}{r^3}\right) \\ \text{To satisfy } \mathbf{v}(r \to \infty) &= \mathbf{u} : \implies C_1 = 0 \\ \text{To satisfy } \mathbf{v}(R) &= 0 \quad \text{solve for } C_2, C_4 \\ v_r &= u\cos\theta \left(1 - \frac{3R}{2r} + \frac{R^3}{2r^3}\right) \\ v_\theta &= -u\sin\theta \left(1 - \frac{3R}{4r} - \frac{R^3}{4r^3}\right) \end{aligned}$$

![](_page_29_Picture_0.jpeg)

$$v_r = u\cos\theta \left(1 - \frac{3R}{2r} + \frac{R^3}{2r^3}\right)$$
$$v_\theta = -u\sin\theta \left(1 - \frac{3R}{4r} - \frac{R^3}{4r^3}\right)$$

Determining pressure:

$$\nabla p = \eta \nabla^2 \mathbf{v} = -\eta \nabla \left( u \cos \theta \left( \frac{3R}{2r^2} \right) \right)$$
$$\Rightarrow p(r) = p_0 - \eta u \cos \theta \left( \frac{3R}{2r^2} \right)$$

$$p(r) = p_0 - \eta u \cos \theta \left(\frac{3R}{2r^2}\right)$$

Corresponds to:

$$F_D \cos \theta = (p(R) - p_0) 4\pi R^2 = -\eta u \cos \theta (6\pi R)$$
$$\Rightarrow F_D = -\eta u (6\pi R)$$

![](_page_30_Picture_4.jpeg)