



# PHY 711 Classical Mechanics and Mathematical Methods

10-10:50 AM MWF in Olin 103

## Notes on Lecture 36

**Continued discussion of viscous fluids:**  
**Chap. 12 in F & W**

1. **Some general comments**
2. **Navier-Stokes equation**
3. **Review of results from last time – Stokes “law”**
4. **Effects on linearized sound waves**

33	Mon, 11/11/2024	Chap. 10	Surface waves in fluids; soliton solutions	<a href="#">#26</a>
34	Wed, 11/13/2024	Chap. 11	Heat conduction	<a href="#">#27</a>
35	Fri, 11/15/2024	Chap. 12	Viscous effects in hydrodynamics	<a href="#">#28</a>
36	Mon, 11/18/2024	Chap. 12	Viscous effects in hydrodynamics	<a href="#">#29</a>
37	Wed, 11/20/2024	Chap. 13	Elasticity	<a href="#">#30</a>
38	Fri, 11/22/2024	Chap. 1-13	Review	
39	Mon, 11/25/2024	Chap. 1-13	Review	
	Wed, 11/27/2024	Thanksgiving		
	Fri, 11/29/2024	Thanksgiving		
	Mon, 12/02/2024		Presentations 1	
	Wed, 12/04/2024		Presentations 2	
40	Fri, 12/06/2024	Chap. 1-13	Review	

## PHY 711 -- Assignment #29

Assigned: 11/18/2024 Due: 11/25/2024

Continue reading Chapter 12 in **Fetter & Walecka**.

1. Work problem 12.13 at the end of Chapter 12 in **Fetter & Walecka**.

Comment on outstanding homework.

## Equations for motion of non-viscous fluid --

Modified Newton-Euler equation in terms of fluid momentum:

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_j \mathbf{v})}{\partial x_j} = \rho \mathbf{f}_{\text{applied}} - \nabla p$$

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_j \mathbf{v})}{\partial x_j} + \nabla p = \rho \mathbf{f}_{\text{applied}}$$

Fluid momentum:  $\rho \mathbf{v}$

Stress tensor:  $T_{ij} \equiv \rho v_i v_j + p \delta_{ij}$

$i^{\text{th}}$  component of Newton-Euler equation:

$$\frac{\partial(\rho v_i)}{\partial t} + \sum_{j=1}^3 \frac{\partial T_{ij}}{\partial x_j} = \rho f_i$$

Now consider the effects of viscosity

In terms of stress tensor:

$$T_{ij} = T_{ij}^{\text{ideal}} + T_{ij}^{\text{viscous}}$$

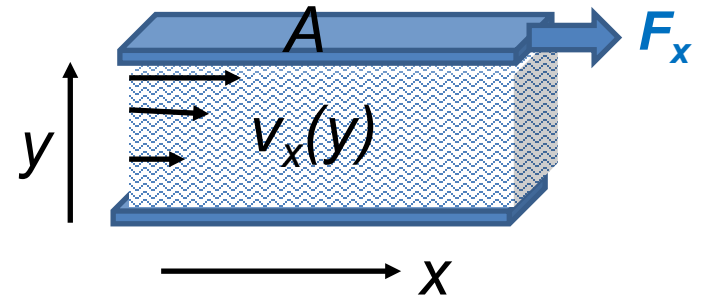
$$T_{ij}^{\text{ideal}} = \rho v_i v_j + p \delta_{ij} = T_{ji}^{\text{ideal}}$$

As an example of a viscous effect, consider --

Newton's "law" of viscosity

$$\frac{F_x}{A} = \eta \frac{\partial v_x}{\partial y}$$

material dependent parameter



## Effects of viscosity

Argue that viscosity is due to shear forces in a fluid of the form:

$$\frac{F_{drag}}{A} = \eta \frac{\partial v_x}{\partial y}$$

Formulate viscosity stress tensor with traceless and diagonal terms:

$$T_{kl}^{viscous} = -\eta \left( \frac{\partial v_k}{\partial x_l} + \frac{\partial v_l}{\partial x_k} - \frac{2}{3} \delta_{kl} (\nabla \cdot \mathbf{v}) \right) - \zeta \delta_{kl} (\nabla \cdot \mathbf{v})$$



viscosity



bulk (or dilational) viscosity

$$\text{Total stress tensor: } T_{kl} = T_{kl}^{ideal} + T_{kl}^{viscous}$$

$$T_{kl}^{ideal} = \rho v_k v_l + p \delta_{kl}$$

$$T_{kl}^{viscous} = -\eta \left( \frac{\partial v_k}{\partial x_l} + \frac{\partial v_l}{\partial x_k} - \frac{2}{3} \delta_{kl} (\nabla \cdot \mathbf{v}) \right) - \zeta \delta_{kl} (\nabla \cdot \mathbf{v})$$

## Effects of viscosity -- continued

Incorporating generalized stress tensor into Newton-Euler equations

$$\frac{\partial(\rho v_i)}{\partial t} + \sum_{j=1}^3 \frac{\partial T_{ij}}{\partial x_j} = \rho f_i$$

$$\frac{\partial(\rho v_i)}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_i v_j)}{\partial x_j} = \rho f_i - \frac{\partial p}{\partial x_i} + \eta \sum_{j=1}^3 \frac{\partial^2 v_i}{\partial x_j^2} + \left( \zeta + \frac{1}{3} \eta \right) \sum_{j=1}^3 \frac{\partial^2 v_j}{\partial x_i \partial x_j}$$

Continuity equation

$$\frac{\partial \rho}{\partial t} + \sum_{j=1}^3 \frac{\partial(\rho v_j)}{\partial x_j} = 0$$

Vector form (Navier-Stokes equation)

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity equation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

# Newton-Euler equations for viscous fluids

Navier-Stokes equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity condition

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

Typical viscosities at 20° C and 1 atm:

Fluid	$\eta/\rho$ (m <sup>2</sup> /s)	$\eta$ (Pa s)
Water	1.00 x 10 <sup>-6</sup>	1 x 10 <sup>-3</sup>
Air	14.9 x 10 <sup>-6</sup>	0.018 x 10 <sup>-3</sup>
Ethyl alcohol	1.52 x 10 <sup>-6</sup>	1.2 x 10 <sup>-3</sup>
Glycerine	1183 x 10 <sup>-6</sup>	1490 x 10 <sup>-3</sup>

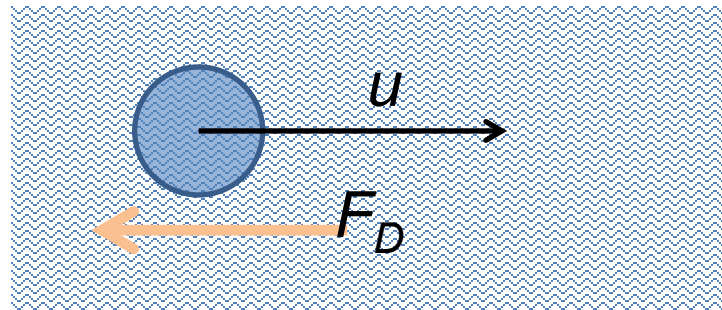




More discussion of viscous effects in incompressible fluids

Stokes' analysis of viscous drag on a sphere of radius  $R$  moving at speed  $u$  in medium with viscosity  $\eta$  :

$$F_D = -\eta(6\pi Ru)$$



“Derivation”

1. Consider the general effects of viscosity on fluid equations
2. Solve the linearized equations for the case of steady-state flow of a sphere of radius  $R$
3. Infer the drag force needed to maintain the steady-state flow
4. Note that solution is special to the sphere geometry.

## Some of the details

For an incompressible fluid:  $\nabla \cdot \mathbf{v} = 0$

For irrotational flow:  $\nabla \times \mathbf{v} = 0 \quad \Rightarrow \quad \mathbf{v} = -\nabla\Phi(\mathbf{r}) \quad \nabla^2\Phi = 0$

For spherical polar coordinates and asymptotic form:

$$\Phi(r \rightarrow \infty, \theta) = -v_0 r \cos \theta$$

For an ideal fluid (no viscosity):  $v_r(a) = 0$

$$\Phi(r, \theta) = -v_0 \left( r + \frac{a^3}{2r^2} \right) \cos \theta \quad v_r(r) = v_0 \left( 1 - \frac{a^3}{r^3} \right) \cos \theta$$

For viscous fluid:  $v_r(a, \theta) = 0$  and  $v_\theta(a, \theta) = 0$

with  $\mathbf{v} = v_0 \left( \nabla \times \left( \nabla \times f(r) \hat{\mathbf{z}} \right) + \hat{\mathbf{z}} \right)$  and  $\nabla^4 f(r) = 0$ .

$$v_r = v_0 \cos \theta \left( 1 - \frac{3a}{2r} + \frac{a^3}{2r^3} \right) \quad v_\theta = -v_0 \sin \theta \left( 1 - \frac{3a}{4r} - \frac{a^3}{4r^3} \right)$$

General equations for hydrodynamics --

Vector form (Navier-Stokes equation)

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity equation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

Additional effects of viscosity – allowing for changes in entropy  
-- particularly in the case of sound waves in air

$$p(\rho, s) = p_0 + \left( \frac{\partial p}{\partial \rho} \right)_s \delta \rho + \left( \frac{\partial p}{\partial s} \right)_\rho \delta s$$

# Newton-Euler equations for viscous fluids

Navier-Stokes equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity condition

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

# Newton-Euler equations for viscous fluids – effects on sound

Without viscosity terms:

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p \qquad \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

Assume:  $\mathbf{v} = 0 + \delta \mathbf{v}$        $\mathbf{f} = 0$        $\rho = \rho_0 + \delta \rho$

$$p = p_0 + \delta p = p_0 + \left( \frac{\partial p}{\partial \rho} \right)_s \delta \rho \equiv p_0 + c^2 \delta \rho$$

Linearized equations:  $\frac{\partial \delta \mathbf{v}}{\partial t} = -\frac{c^2}{\rho_0} \nabla \delta \rho$        $\frac{\partial \delta \rho}{\partial t} + \rho_0 \nabla \cdot (\delta \mathbf{v}) = 0$

Let  $\delta \mathbf{v} \equiv \delta \mathbf{v}_0 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$        $\delta \rho \equiv \delta \rho_0 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$

## Sound waves without viscosity -- continued

$$\text{Linearized equations: } \frac{\partial \delta \mathbf{v}}{\partial t} = -\frac{c^2}{\rho_0} \nabla \delta \rho \quad \frac{\partial \delta \rho}{\partial t} + \rho_0 \nabla \cdot (\delta \mathbf{v}) = 0$$

$$\text{Let } \delta \mathbf{v} \equiv \delta \mathbf{v}_0 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)} \quad \delta \rho \equiv \delta \rho_0 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$$

$$\frac{\partial \delta \mathbf{v}}{\partial t} = -\frac{c^2}{\rho_0} \nabla \delta \rho \quad \Rightarrow \quad \omega \delta \mathbf{v}_0 = \frac{c^2 \delta \rho_0}{\rho_0} \mathbf{k}$$

$$\frac{\partial \delta \rho}{\partial t} + \rho_0 \nabla \cdot (\delta \mathbf{v}) = 0 \quad \Rightarrow \quad -\omega \delta \rho_0 + \rho_0 \mathbf{k} \cdot \delta \mathbf{v}_0 = 0$$

$$\Rightarrow k^2 = \frac{\omega^2}{c^2} \quad \frac{\delta \rho_0}{\rho_0} = \frac{\hat{\mathbf{k}} \cdot \delta \mathbf{v}_0}{c}$$

→ Pure longitudinal harmonic wave solutions

# Newton-Euler equations for viscous fluids – effects on sound

Recall full equations:

Navier-Stokes equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

Continuity condition

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

Assume:  $\mathbf{v} = \mathbf{0} + \delta \mathbf{v}$        $\mathbf{f} = \mathbf{0}$        $\rho = \rho_0 + \delta \rho$

$$p = p_0 + \delta p = p_0 + c^2 \delta \rho + \left( \frac{\partial p}{\partial s} \right)_\rho \delta s$$

where  $c^2 \equiv \left( \frac{\partial p}{\partial \rho} \right)_s$



viscosity  
causes heat  
transfer

# Newton-Euler equations for viscous fluids – effects on sound

Note that pressure now depends both on density and entropy so that entropy must be coupled into the equations

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\rho T \frac{\partial s}{\partial t} = k_{th} \nabla^2 T$$

Assume:  $\mathbf{v} = \mathbf{0} + \delta \mathbf{v}$        $\mathbf{f} = \mathbf{0}$        $\rho = \rho_0 + \delta \rho$

$$p = p_0 + \delta p = p_0 + c^2 \delta \rho + \left( \frac{\partial p}{\partial s} \right)_{\rho} \delta s \quad \text{where } c^2 \equiv \left( \frac{\partial p}{\partial \rho} \right)_{s}$$

$$T = T_0 + \delta T = T_0 + \left( \frac{\partial T}{\partial \rho} \right)_{s} \delta \rho + \left( \frac{\partial T}{\partial s} \right)_{\rho} \delta s$$

$$s = s_0 + \delta s$$



# Newton-Euler equations for viscous fluids – linearized equations

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = \mathbf{f} - \frac{1}{\rho} \nabla p + \frac{\eta}{\rho} \nabla^2 \mathbf{v} + \frac{1}{\rho} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \mathbf{v})$$

$$\Rightarrow \frac{\partial \delta \mathbf{v}}{\partial t} = - \underbrace{\frac{1}{\rho_0}}_{\rho_0} \nabla \delta p + \frac{\eta}{\rho} \nabla^2 \delta \mathbf{v} + \frac{1}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \delta \mathbf{v})$$

$$- \frac{1}{\rho_0} \left\{ \left( \frac{\partial p}{\partial \rho} \right)_s \nabla \delta \rho + \left( \frac{\partial p}{\partial s} \right)_\rho \nabla \delta s \right\} = - \frac{c^2}{\rho_0} \nabla \delta \rho - \rho_0 \left( \frac{\partial T}{\partial \rho} \right)_s \nabla \delta s$$

Digression -- from the first law of thermodynamics:

$$d\epsilon = T ds + \frac{p}{\rho^2} d\rho$$

$$\left( \frac{\partial}{\partial \rho} \left( \frac{\partial \epsilon}{\partial s} \right)_\rho \right)_s = \left( \frac{\partial T}{\partial \rho} \right)_s \Leftrightarrow \left( \frac{\partial}{\partial s} \left( \frac{\partial \epsilon}{\partial \rho} \right)_s \right)_\rho = \left( \frac{\partial p / \rho^2}{\partial s} \right)_\rho \approx \frac{1}{\rho_0^2} \left( \frac{\partial p}{\partial s} \right)_\rho$$

# Newton-Euler equations for viscous fluids – linearized equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\Rightarrow \frac{\partial \delta \rho}{\partial t} + \rho_0 \nabla \cdot (\delta \mathbf{v}) = 0$$

$$\rho T \frac{\partial s}{\partial t} = k_{th} \nabla^2 T$$

$$\Rightarrow \frac{\partial \delta s}{\partial t} = \frac{k_{th}}{\rho_0 T_0} \left( \left( \frac{\partial T}{\partial s} \right)_\rho \nabla^2 \delta s + \left( \frac{\partial T}{\partial \rho} \right)_s \nabla^2 \delta \rho \right)$$

Further relationships:

$$\left( \frac{\partial T}{\partial s} \right)_\rho \approx \frac{T_0}{c_v}$$

$$\kappa = \frac{k_{th}}{\rho c_p}$$



heat capacity at constant volume

# Newton-Euler equations for viscous fluids – linearized equations

$$\Rightarrow \frac{\partial \delta s}{\partial t} = \left( \gamma \kappa \nabla^2 \delta s + \frac{c_p \kappa}{T_0} \left( \frac{\partial T}{\partial \rho} \right)_s \nabla^2 \delta \rho \right) \quad \text{where } \gamma \equiv \frac{c_p}{c_v}$$

Newton-Euler equations for viscous fluids – effects on sound  
 Linearized equations (with the help of various  
 thermodynamic relationships):

$$\frac{\partial \delta \mathbf{v}}{\partial t} = -\frac{c^2}{\rho_0} \nabla \delta \rho - \rho_0 \left( \frac{\partial T}{\partial \rho} \right)_s \nabla \delta s + \frac{\eta}{\rho_0} \nabla^2 \delta \mathbf{v} + \frac{1}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \delta \mathbf{v})$$

$$\frac{\partial \delta \rho}{\partial t} + \rho_0 \nabla \cdot (\delta \mathbf{v}) = 0$$

$$\frac{\partial \delta s}{\partial t} = \gamma \kappa \nabla^2 \delta s + \frac{c_p \kappa}{T_0} \left( \frac{\partial T}{\partial \rho} \right)_s \nabla^2 \delta \rho$$

Here:  $\gamma = \frac{c_p}{c_v}$        $\kappa = \frac{k_{th}}{c_p \rho_0}$

# Linearized hydrodynamic equations

$$\frac{\partial \delta \mathbf{v}}{\partial t} = -\frac{c^2}{\rho_0} \nabla \delta \rho - \rho_0 \left( \frac{\partial T}{\partial \rho} \right)_s \nabla \delta s + \frac{\eta}{\rho_0} \nabla^2 \delta \mathbf{v} + \frac{1}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \nabla (\nabla \cdot \delta \mathbf{v})$$

$$\frac{\partial \delta \rho}{\partial t} + \rho_0 \nabla \cdot (\delta \mathbf{v}) = 0$$

$$\frac{\partial \delta s}{\partial t} = \gamma \kappa \nabla^2 \delta s + \frac{c_p \kappa}{T_0} \left( \frac{\partial T}{\partial \rho} \right)_s \nabla^2 \delta \rho$$

It can be shown that

$$\left( \frac{\partial T}{\partial \rho} \right)_s = \frac{T c^2 \beta}{\rho c_p} \quad \text{where} \quad \beta \equiv \frac{1}{V} \left( \frac{\partial V}{\partial T} \right)_p \quad (\text{thermal expansion})$$

$$\text{Let} \quad \delta \mathbf{v} \equiv \delta \mathbf{v}_0 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)} \quad \delta \rho \equiv \delta \rho_0 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)} \quad \delta s \equiv \delta s_0 e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$$

Linearized hydrodynamic equations; plane wave solutions:

$$\omega \delta \mathbf{v}_0 = \frac{c^2 \delta \rho_0}{\rho_0} \mathbf{k} + \frac{T_0 \beta c^2}{c_p} \delta s_0 \mathbf{k} - \frac{i \eta k^2}{\rho_0} \delta \mathbf{v}_0 - \frac{i}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \mathbf{k} (\mathbf{k} \cdot \delta \mathbf{v}_0)$$

$$\omega \delta \rho_0 - \rho_0 \mathbf{k} \cdot \delta \mathbf{v}_0 = 0$$

$$\omega \delta s_0 = -i \gamma \kappa k^2 \delta s_0 - \frac{i \kappa \beta c^2}{\rho_0} k^2 \delta \rho_0$$

In the absence of thermal expansion,  $\beta = 0$

$$\omega \delta \mathbf{v}_0 = \frac{c^2 \delta \rho_0}{\rho_0} \mathbf{k} - \frac{i \eta k^2}{\rho_0} \delta \mathbf{v}_0 - \frac{i}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \mathbf{k} (\mathbf{k} \cdot \delta \mathbf{v}_0)$$

$$\omega \delta \rho_0 - \rho_0 \mathbf{k} \cdot \delta \mathbf{v}_0 = 0$$

$$\omega \delta s_0 = -i \gamma \kappa k^2 \delta s_0$$

→ Entropy and mechanical modes are independent

Linearized hydrodynamic equations; full plane wave solutions:

$$\omega \delta \mathbf{v}_0 = \frac{c^2 \delta \rho_0}{\rho_0} \mathbf{k} + \frac{T_0 \beta c^2}{c_p} \delta s_0 \mathbf{k} - \frac{i \eta k^2}{\rho_0} \delta \mathbf{v}_0 - \frac{i}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \mathbf{k} (\mathbf{k} \cdot \delta \mathbf{v}_0)$$

$$\omega \delta \rho_0 - \rho_0 \mathbf{k} \cdot \delta \mathbf{v}_0 = 0$$

$$\omega \delta s_0 = -i \gamma \kappa k^2 \delta s_0 - \frac{i \kappa \beta c^2}{\rho_0} k^2 \delta \rho_0$$

Longitudinal solutions: ( $\delta \mathbf{v} \cdot \mathbf{k} \neq 0$ ):

$$\left( \omega^2 - c^2 k^2 + i \frac{\omega k^2}{\rho_0} \left( \frac{4}{3} \eta + \zeta \right) \right) \delta \rho_0 - \frac{\rho_0 T_0 \beta c^2 k^2}{c_p} \delta s_0 = 0$$

$$\frac{i \kappa \beta c^2}{\rho_0} k^2 \delta \rho_0 + \left( \omega + i \gamma \kappa k^2 \right) \delta s_0 = 0$$

# Linearized hydrodynamic equations; full plane wave solutions:

Longitudinal solutions:  $(\delta \mathbf{v} \cdot \mathbf{k} \neq 0)$ :

$$\left( \omega^2 - c^2 k^2 + i \frac{\omega k^2}{\rho_0} \left( \frac{4}{3} \eta + \zeta \right) \right) \delta \rho_0 - \frac{\rho_0 T_0 \beta c^2 k^2}{c_p} \delta s_0 = 0$$

$$\frac{i \kappa \beta c^2}{\rho_0} k^2 \delta \rho_0 + (\omega + i \gamma \kappa k^2) \delta s_0 = 0$$

Approximate solution:  $k = \frac{\omega}{c} + i \alpha$

$$\text{where } \alpha \approx \frac{\omega^2}{2c^3 \rho_0} \left( \frac{4}{3} \eta + \zeta \right) + \frac{\kappa T_0 \beta^2 \omega^2}{2c_p c}$$

$$\delta \rho = \delta \rho_0 e^{-\alpha \hat{\mathbf{k}} \cdot \mathbf{r}} e^{i \frac{\omega}{c} (\hat{\mathbf{k}} \cdot \mathbf{r} - ct)}$$



Linearized hydrodynamic equations; full plane wave solutions:

$$\omega \delta \mathbf{v}_0 = \frac{c^2 \delta \rho_0}{\rho_0} \mathbf{k} + \frac{T_0 \beta c^2}{c_p} \delta s_0 \mathbf{k} - \frac{i \eta k^2}{\rho_0} \delta \mathbf{v}_0 - \frac{i}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \mathbf{k} (\mathbf{k} \cdot \delta \mathbf{v}_0)$$

$$\omega \delta \rho_0 - \rho_0 \mathbf{k} \cdot \delta \mathbf{v}_0 = 0$$

$$\omega \delta s_0 = -i \gamma \kappa k^2 \delta s_0 - \frac{i \kappa \beta c^2}{\rho_0} k^2 \delta \rho_0$$

Transverse modes ( $\delta \mathbf{v} \cdot \mathbf{k} = 0$ ):

$$\delta \rho_0 = 0 \quad \delta s_0 = 0$$

$$\left( \omega + \frac{i \eta k^2}{\rho_0} \right) (\delta \mathbf{v} \times \mathbf{k}) = 0 \quad k = \pm \left( \frac{i \omega \rho_0}{\eta} \right)^{1/2}$$

New phenomena in the linear regime

1. Spatial attenuation of waves
2. New transverse modes

# Comment on HW 29 -- Analysis of special case of linearized sound wave equations

$$\omega \delta \mathbf{v}_0 = \frac{c^2 \delta \rho_0}{\rho_0} \mathbf{k} + \frac{T_0 \beta c^2}{c_p} \delta s_0 \mathbf{k} - \frac{i \eta k^2}{\rho_0} \delta \mathbf{v}_0 - \frac{i}{\rho_0} \left( \zeta + \frac{1}{3} \eta \right) \mathbf{k} (\mathbf{k} \cdot \delta \mathbf{v}_0)$$

$$\omega \delta \rho_0 - \rho_0 \mathbf{k} \cdot \delta \mathbf{v}_0 = 0$$

$$\omega \delta s_0 = -i \gamma \kappa k^2 \delta s_0 - \frac{i \kappa \beta c^2}{\rho_0} k^2 \delta \rho_0$$

For the homework problem,  $\eta = 0$  and  $\zeta = 0$

Also, note that in these expressions, we have used the expression

$$\left( \frac{\partial T}{\partial \rho} \right)_s = \frac{T_0 c^2 \beta}{\rho_0 c_p} \quad \text{alternatively we can use} \quad \left( \frac{\partial T}{\partial \rho} \right)_s = \frac{T_0}{c_p}$$

Eq. 62.24 of your textbook also shows that

$$\left( \frac{\partial T}{\partial \rho} \right)_{s \Rightarrow}^2 = \frac{T_0 c^2}{\rho_0^2 c_p} (\gamma - 1) = \left( \frac{T_0 c^2 \beta}{\rho_0 c_p} \right)^2 \quad \Rightarrow \quad c^4 \beta^2 = (\gamma - 1) \frac{c_p c^2}{T_0}$$