

**PHY 711 Classical Mechanics and
Mathematical Methods
10-10:50 AM MWF in Olin 103**

Notes on Lecture 40

Review of topics covered in this course

- 1. Comment on numerical methods**
- 2. Review of the Sturm-Liouville equation**
- 3. Solving some example problems**

35	Fri, 11/15/2024	Chap. 12	Viscous effects in hydrodynamics	#28
36	Mon, 11/18/2024	Chap. 12	Viscous effects in hydrodynamics	#29
37	Wed, 11/20/2024	Chap. 13	Elasticity	#30
38	Fri, 11/22/2024	Chap. 1-13	Review	
39	Mon, 11/25/2024	Chap. 1-13	Review	
	Wed, 11/27/2024	Thanksgiving		
	Fri, 11/29/2024	Thanksgiving		
	Mon, 12/02/2024		Presentations 1	
	Wed, 12/04/2024		Presentations 2	
40	Fri, 12/06/2024	Chap. 1-13	Review b	

Please fill out the course evaluation form for PHY 711

DECEMBER 2024

Final available

SUN	MON	TUE	WED	THU	FRI	SAT
1	2	3	4	5	6	7
8	9	10	11	12	13	14
15	16	17	18	19	20	21

Today

Final due

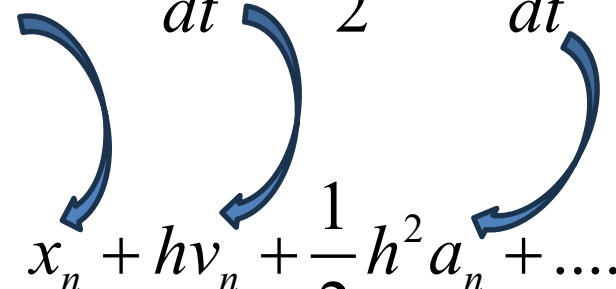
Brief comment on numerical methods --

Consider a continuous function $x(t)$

A Taylor expansion in the neighborhood of t :

$$x(t+h) = x(t) + h \frac{dx(t)}{dt} + \frac{1}{2} h^2 \frac{d^2 x(t)}{dt^2} + \frac{1}{3!} h^3 \frac{d^3 x(t)}{dt^3} + \dots$$

Let $x_n \equiv nh$

$$x_{n+1} = x_n + hv_n + \frac{1}{2} h^2 a_n + \dots$$


Here it is assumed that h is small and $h^3 \ll h^2$

Example differential equation (one dimension);

$$\frac{d^2x}{dt^2} = f(t) \quad \text{Let } t = nh \quad (n = 1, 2, 3 \dots)$$

$$x_n \equiv x(nh); \quad f_n \equiv f(nh)$$

Euler's method :

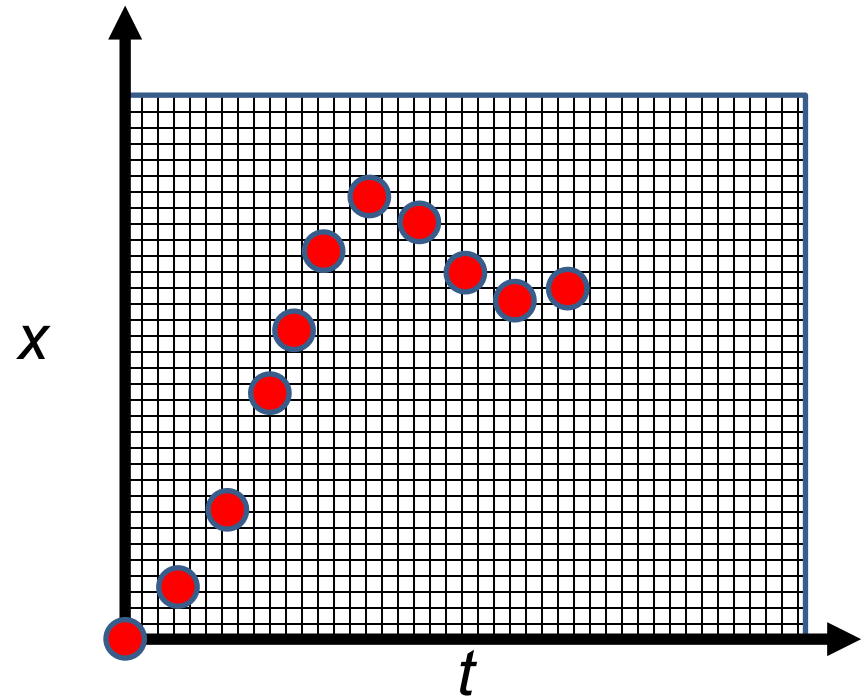
$$x_{n+1} = x_n + hv_n + \frac{1}{2}h^2 f_n$$

$$v_{n+1} = v_n + hf_n$$

Velocity Verlet algorithm :

$$x_{n+1} = x_n + hv_n + \frac{1}{2}h^2 f_n$$

$$v_{n+1} = v_n + \frac{1}{2}h(f_n + f_{n+1})$$



Note that it is possible to check the magnitude of the terms that you are neglecting and estimate the error. Also, one needs to be careful of device-dependent restrictions. In general, it is useful to use scaled coordinates.

For example, $1 + 1 \times 10^{-15} = 1.0000000000000001$
 $= 1.0$ for most devices.

When you perform numerical work, you need to take care about your algorithms both in terms of software and hardware.

Review of the Sturm-Liouville equations

Linear second-order ordinary differential equations
Sturm-Liouville equations

Inhomogenous problem: $\left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) - \lambda \sigma(x) \right) \varphi(x) = F(x)$

given functions

applied force

solution to be determined

When applicable, it is assumed that the form of the applied force is known.

Homogenous problem: $F(x)=0$

Why are Sturm-Liouville equations interesting?

- A. They sound fancy?
- B. They describe all second-order differential equations?
- C. Another method of graduate student torture?
- D. Several special functions are solutions to Sturm-Liouville equations?
- E. They have several interesting properties?

Examples of Sturm-Liouville eigenvalue equations --

$$\left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) - \lambda \sigma(x) \right) \varphi(x) = 0$$

Bessel functions: $0 \leq x < \infty$

$$\tau(x) = -x \quad v(x) = x \quad \sigma(x) = \frac{1}{x} \quad \lambda = \nu^2 \quad \varphi(x) = J_\nu(x)$$

Legendre functions: $-1 \leq x \leq 1$

$$\tau(x) = -(1-x^2) \quad v(x) = 0 \quad \sigma(x) = 1 \quad \lambda = l(l+1) \quad \varphi(x) = P_l(x)$$

Fourier functions: $0 \leq x \leq 1$

$$\tau(x) = 1 \quad v(x) = 0 \quad \sigma(x) = 1 \quad \lambda = n^2 \pi^2 \quad \varphi(x) = \sin(n\pi x)$$

Homogenous problem : $\left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) - \lambda \sigma(x) \right) \phi_0(x) = 0$

Inhomogenous problem : $\left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) - \lambda \sigma(x) \right) \phi(x) = F(x)$

Eigenfunctions :

$$\left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) \right) f_n(x) = \lambda_n \sigma(x) f_n(x)$$

Orthogonality of eigenfunctions: $\int_a^b \sigma(x) f_n(x) f_m(x) dx = \delta_{nm} N_n,$

where $N_n \equiv \int_a^b \sigma(x) (f_n(x))^2 dx.$

Completeness of eigenfunctions:

$$\sigma(x) \sum_n \frac{f_n(x) f_n(x')}{N_n} = \delta(x - x')$$

Comment on orthogonality of eigenfunctions

$$\left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) \right) f_n(x) = \lambda_n \sigma(x) f_n(x)$$

$$\left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) \right) f_m(x) = \lambda_m \sigma(x) f_m(x)$$

$$\begin{aligned} f_m(x) \left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) \right) f_n(x) - f_n(x) \left(-\frac{d}{dx} \tau(x) \frac{d}{dx} + v(x) \right) f_m(x) \\ = (\lambda_n - \lambda_m) \sigma(x) f_n(x) f_m(x) \end{aligned}$$

$$-\frac{d}{dx} \left(f_m(x) \tau(x) \frac{df_n(x)}{dx} - f_n(x) \tau(x) \frac{df_m(x)}{dx} \right) = (\lambda_n - \lambda_m) \sigma(x) f_n(x) f_m(x)$$

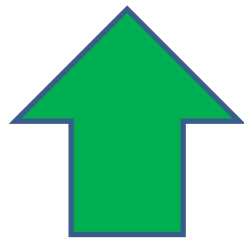
Comment on orthogonality of eigenfunctions -- continued

$$-\frac{d}{dx} \left(f_m(x) \tau(x) \frac{df_n(x)}{dx} - f_n(x) \tau(x) \frac{df_m(x)}{dx} \right) = (\lambda_n - \lambda_m) \sigma(x) f_n(x) f_m(x)$$

Now consider integrating both sides of the equation in the interval

$a \leq x \leq b$:

$$-\left(f_m(x) \tau(x) \frac{df_n(x)}{dx} - f_n(x) \tau(x) \frac{df_m(x)}{dx} \right) \Big|_a^b = (\lambda_n - \lambda_m) \int_a^b dx \sigma(x) f_n(x) f_m(x)$$



Vanishes for various boundary conditions
at $x=a$ and $x=b$

Comment on orthogonality of eigenfunctions -- continued

$$-\left(f_m(x)\tau(x)\frac{df_n(x)}{dx} - f_n(x)\tau(x)\frac{df_m(x)}{dx} \right) \Big|_a^b = (\lambda_n - \lambda_m) \int_a^b dx \sigma(x) f_n(x) f_m(x)$$

Possible boundary values for Sturm-Liouville equations:

1. $f_m(a) = f_m(b) = 0$

2. $\tau(x)\frac{df_m(x)}{dx} \Big|_a = \tau(x)\frac{df_m(x)}{dx} \Big|_b = 0$

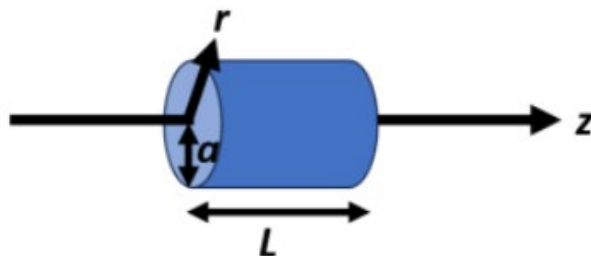
3. $f_m(a) = f_m(b)$ and $\frac{df_m(a)}{dx} = \frac{df_m(b)}{dx}$

In any of these cases, we can conclude that:

$$\int_a^b dx \sigma(x) f_n(x) f_m(x) = 0 \text{ for } \lambda_n \neq \lambda_m$$

For additional information about Sturm-Liouville equations, see Lectures 21,22,23

Read Chapter 11 of Fetter and Walecka.



1.

A cylindrical solid material with cylindrical radius a and length L and thermal diffusivity κ has a time-dependent cylindrically symmetric temperature profile $T(r, z, t)$. In these cylindrical coordinates, the material is contained within $0 \leq r \leq a$ and $0 \leq z \leq L$. In the absence of external heating, the temperature profile is well-described by the equation of heat conduction

$$\frac{\partial T}{\partial t} = \kappa \nabla^2 T.$$

At $t \leq 0$, the material is prepared so that its temperature profile is given by

$$T(r, z, t \leq 0) = \begin{cases} 0 & \text{for } r > a \text{ and/or } z < 0 \text{ or } z > L \\ A \cos(\pi z/L) & \text{for } 0 \leq r \leq a \text{ and } 0 \leq z \leq L, \end{cases}$$

where A is a given constant. The cylindrical solid is placed in a thermally insulated container so that its temperature is well-described by the boundary conditions

$$\hat{\mathbf{n}} \cdot \nabla T(r, z, t) = 0$$

at all of its surfaces. Find an expression for the temperature profile of this system $T(r, z, t)$ for $t > 0$.

The diffusion (or heat conduction) equation for the temperature profile $T(\mathbf{r}, t)$:

$$\frac{\partial T}{\partial t} = \kappa \nabla^2 T$$

For cylindrical coordinates -- $T(\mathbf{r}, t) = T(r, \varphi, z, t)$

and the diffusion equation takes the form:

$$\frac{\partial T(r, \varphi, z, t)}{\partial t} = \kappa \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2} + \frac{\partial^2}{\partial z^2} \right) T(r, \varphi, z, t)$$

Partial differential equation:

$$\frac{\partial T(r, \varphi, z, t)}{\partial t} = \kappa \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2} + \frac{\partial^2}{\partial z^2} \right) T(r, \varphi, z, t)$$

Assume separable form: $T(r, \varphi, z, t) = R(r)\Phi(\varphi)Z(z)f(t)$

In this particular case, the φ dependence is trivial, so that it is reasonable to assume that $T(r, \varphi, z, t) = T(r, z, t) = R(r)Z(z)f(t)$

$$\text{Then } \frac{\partial T(r, z, t)}{\partial t} = R(r)Z(z) \frac{df(t)}{dt}$$

$$\nabla^2 T(r, z, t) = Z(z)f(t) \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right) R(r) + R(r)f(t) \frac{d^2 Z(z)}{dz^2}$$

Summary:

$$\frac{\partial T(r, z, t)}{\partial t} = \kappa \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{\partial^2}{\partial z^2} \right) T(r, z, t)$$

$$T(r, z, t) = R(r)Z(z)f(t)$$

$$\text{Then } \frac{\partial T(r, z, t)}{\partial t} = R(r)Z(z) \frac{df(t)}{dt}$$

$$\nabla^2 T(r, z, t) = Z(z)f(t) \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right) R(r) + R(r)f(t) \frac{d^2 Z(z)}{dz^2}$$

$$R(r)Z(z) \frac{df(t)}{dt} = \kappa \left(Z(z)f(t) \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right) R(r) + R(r)f(t) \frac{d^2 Z(z)}{dz^2} \right)$$

Divide both sides of the equation by $R(r)Z(z)f(t)$

$$\frac{1}{f(t)} \frac{df(t)}{dt} = \kappa \left(\frac{1}{R(r)} \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right) R(r) + \frac{1}{Z(z)} \frac{d^2 Z(z)}{dz^2} \right)$$

$$\frac{1}{f(t)} \frac{df(t)}{dt} = \kappa \left(\frac{1}{R(r)} \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right) R(r) + \frac{1}{Z(z)} \frac{d^2 Z(z)}{dz^2} \right)$$

Suppose $\frac{df(t)}{dt} = -\lambda f(t)$ and $\frac{d^2 Z(z)}{dz^2} = -\alpha^2 Z(z)$

and $\left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right) R(r) = -\mu^2 R(r)$

where λ , α , and μ are real numbers.

This will work if $\lambda = \kappa(\alpha^2 + \mu^2)$

Solution of ordinary differential equation for the radial component:

$$\left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} + \mu^2 \right) R(r) = 0$$

Recall that the regular solution of the Bessel equation of order 0 is a solution of the differential equation:

$$\left(\frac{d^2}{dx^2} + \frac{1}{x} \frac{d}{dx} + 1 \right) J_0(x) = 0$$

Therefore, $R(r) = CJ_0(\mu r)$ where C is a constant

More generally, multiple solutions μ_n may be viable, in which case

the solution has the form $R(r) = \sum_n C_n J_0(\mu_n r)$.

$$R(r) = \sum_n C_n J_0(\mu_n r)$$
 Satisfies the radial differential equation, but does not satisfy boundary conditions

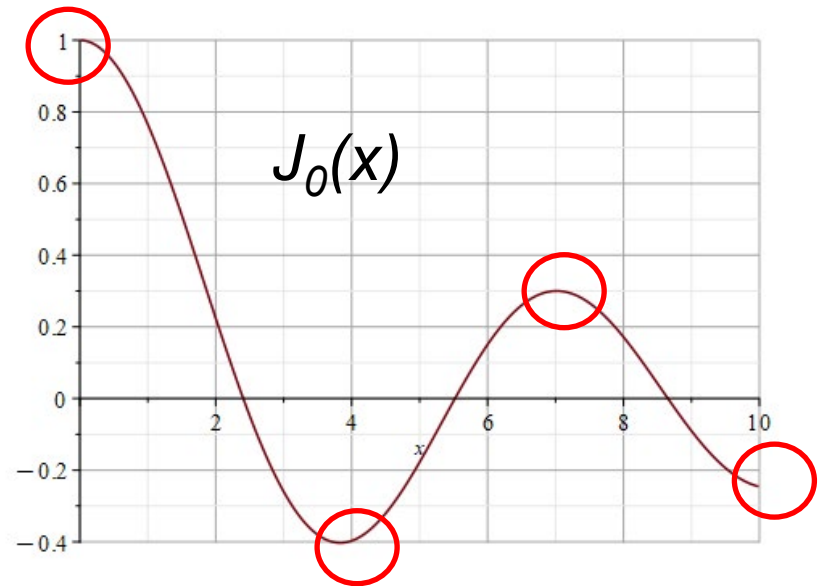
Need to find μ_n and C_n .

For boundary value at $r = a$

$$\left. \frac{dJ_0(\mu_n r)}{dr} \right|_{r=a} = 0$$

Define
$$\frac{dJ_0(x'_n)}{dx} = 0$$

$$\mu_n = \frac{x'_n}{a}$$



Note that the functions $J_0(\mu_n r)$ form a set of orthogonal functions over the range $0 \leq r \leq a$.

$$\left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} + \mu_n^2 \right) J_0(\mu_n r) = 0$$

$$\left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} + \mu_m^2 \right) J_0(\mu_m r) = 0$$

$$J_0(\mu_m r) \left(\frac{1}{r} \frac{d}{dr} r \frac{d}{dr} \right) J_0(\mu_n r) - J_0(\mu_n r) \left(\frac{1}{r} \frac{d}{dr} r \frac{d}{dr} \right) J_0(\mu_m r) =$$

$$(\mu_m^2 - \mu_n^2) J_0(\mu_n r) J_0(\mu_m r)$$

If $\mu_n = \mu_m$, then the equality is trivial. If $\mu_n \neq \mu_m$, the integrating both sides of the equation $0 \leq r \leq a$ implies that

$$\int_0^a dr \, r J_0(\mu_n r) J_0(\mu_m r) = 0$$

Solution of ordinary differential equation for the z component:

$$\left(\frac{d^2}{dz^2} + \alpha^2 \right) Z(z) = 0 \quad \text{with boundary values} \quad \left. \frac{dZ}{dz} \right|_{z=0} = 0 = \left. \frac{dZ}{dz} \right|_{z=L}$$

$$\Rightarrow Z(z) = \sum_k D_k \cos\left(\frac{k\pi z}{L}\right) \quad \text{where} \quad \alpha_k = \frac{k\pi}{L}$$

In our case, because of the initial conditions, only the $k = 1$ solution is present.

Full general solution:

$$T(r, z, t) = \sum_n C_n J_0(\mu_n r) \cos\left(\frac{\pi z}{L}\right) e^{-\lambda_n t}$$

$$\text{where } \lambda_n = \kappa \left(\mu_n^2 + \frac{\pi^2}{L^2} \right) = \kappa \left(\frac{x_n'^2}{a^2} + \frac{\pi^2}{L^2} \right)$$

Finishing up --

$$T(r, z, t) = \sum_n C_n J_0(\mu_n r) \cos\left(\frac{\pi z}{L}\right) e^{-\lambda_n t} \quad \text{with } \lambda_n = \kappa \left(\mu_n^2 + \frac{\pi^2}{L^2} \right)$$

At $t = 0$, $0 \leq r \leq a$, $0 \leq z \leq L$

$$T(r, z, 0) = A \cos\left(\frac{\pi z}{L}\right) = \sum_n C_n J_0(\mu_n r) \cos\left(\frac{\pi z}{L}\right)$$

Full general solution:

$$T(r, z, t) = \sum_n C_n J_0(\mu_n r) \cos\left(\frac{\pi z}{L}\right) e^{-\lambda_n t}$$

$$\text{where } \lambda_n = \kappa \left(\mu_n^2 + \frac{\pi^2}{L^2} \right)$$

$$\text{and where } C_n = A \frac{\int_0^a dr r J_0(\mu_n r)}{\int_0^a dr r J_0^2(\mu_n r)}$$

Advice about problem solving such as coupled differential equations

A particle of mass m and charge q is subjected to a vector potential $\mathbf{A}(\mathbf{r}, t) = -(E_0ct + B_0x)\hat{\mathbf{z}}$. In this case, the scalar potential is zero: $\Phi(\mathbf{r}, t) = 0$. (Note that we are using the cgs Gaussian units of your text book.) Here E_0 denotes a constant electric field amplitude and B_0 denotes a constant magnetic field amplitude. The initial particle position is $\mathbf{r}(t = 0) = 0$ and the initial particle velocity is $\dot{\mathbf{r}}(t = 0) = 0$.

- a. Determine the Lagrangian $L(x, y, z, \dot{x}, \dot{y}, \dot{z}, t)$ which describes the particle's motion.
 - b. Write the Euler-Lagrange equations for this system.
 - c. Find and evaluate the constants of motion for this system.
 - d. Find the particle trajectories $x(t)$, $y(t)$, $z(t)$ by solving the equations and imposing the given initial conditions.
2. A particle of mass m and charge q moves in three-dimensional space in the presence of a constant electric field of strength E_0 and a constant magnetic field of strength B_0 in cgs Gaussian units. Initially, $x(t = 0) = y(t = 0) = z(t = 0) = 0$ and $\dot{x}(t = 0) = \dot{y}(t = 0) = \dot{z}(t = 0) = 0$. The Lagrangian for this system in Cartesian coordinates is given by

$$L(x, y, z, \dot{x}, \dot{y}, \dot{z}) = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) + qE_0z - \frac{q}{c}B_0x\dot{z},$$

where c denotes the speed of light in vacuum.

- (a) Find the Hamiltonian of this system in canonical form.
- (b) Using either the Hamiltonian or Lagrangian formalisms, find the equations of motion for this system.
- (c) Solve the equations of motion using your knowledge of the initial values.
- (d) Comment on whether or not your solution makes physical sense.

$$1. L(x, y, z, \dot{x}, \dot{y}, \dot{z}) = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) - qE_0ct\dot{z} - \frac{q}{c}B_0x\dot{z}$$

$$2. L(x, y, z, \dot{x}, \dot{y}, \dot{z}) = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) + qE_0z - \frac{q}{c}B_0x\dot{z}$$

Initial conditions for both #1 and #2: $\mathbf{r}(t) = 0$ and $\dot{\mathbf{r}}(t) = 0$

What can you say about these two cases?

Solution:

$$z(t) = \frac{E_0 c}{B_0} \frac{mc}{qB_0} \left(1 - \cos \left(\frac{qB_0}{mc} t \right) \right)$$

$$x(t) = \frac{E_0 c}{B_0} \left(\frac{mc}{qB_0} \sin \left(\frac{qB_0}{mc} t \right) - t \right)$$

Do these solutions satisfy the equations?

Do these solutions satisfy the initial conditions?